

# Regularization in Banach spaces

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- Bremen = Brême
- Population:  
500 000 - 800 000
- Group Prof. Maaß
- AG Technomathematik =  
Industrial Mathematics
- 10-15 people
- Mico-Cutting Processes,  
Impedance Tomography,  
Image Processing, Inexact  
Operators, Sparsity, ...

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- 1 Why Banach?
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## Ill-posed Problems, e.g. CT, MRT...

$A : X \rightarrow Y$  linear,  $X, Y$  Banach

$$Ax = y \quad \|y - y^\delta\| \leq \delta$$

Problem: Construct  $x_\delta$  with  $x_\delta \rightarrow x$  for  $\delta \rightarrow 0$

## Ill-posed Problems, e.g. CT, MRT...

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Problem: Construct  $x_\delta$  with  $x_\delta \rightarrow x$  for  $\delta \rightarrow 0$

Idea:

$$x_\delta = A^{-1}y_\delta$$

Problems:

- Solution does not exist
- Solution is not unique
- Solution does not depend continuously on  $y^\delta$

$\rightsquigarrow$  ill-posed problem  $\rightsquigarrow$  need for regularization

# Banach spaces - The Good, the Bad and the Ugly

- sequence spaces  $\ell^p$
- Lebesgue  $L^p$
- Sobolev  $W^s_\rho$
- Total-Variation  $TV$
- Besov  $B^s_{\rho,q}$

# Banach spaces - The Good, the Bad and the Ugly

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- Besov  $B^s_{p,q}$
- BMO, Orlicz, Hardy...

# Why Banach?

- $\ell^1 \rightarrow$  sparsity
- $L^2 \rightarrow$  smoothing
- approximation results  $\rightarrow B_{p,q}^s$
- domain spaces with step functions  $\rightarrow$  higher smoothness in  $B_{p,q}^s$  scale, cmp. to  $W_2^s$  scale
- ...



## Nice spaces, not so nice spaces...

- $\ell^1$  not reflexive, good to handle with basic tools (calculus on components)
- $\ell^p$   $1 < p < \infty$  reflexive, Clarkson, Hanner...,  $\ell^2$  even Hilbert
- $\ell^\infty$  not reflexive, no current applications?
- $TV$  not reflexive, hard to handle on multidimensional domains, even computation of the norm not trivial.
- Hilbert spaces reflexive, inner product... nice geometry (polarization and parallelogram identities)

nice Banach spaces  $\leftrightarrow$  nice geometry

# Banach space geometry

Definition (Duality mapping  $J_p : X \rightrightarrows X^*$  important! )

$$J_p(x) := \partial\left\{\frac{1}{p}\|\cdot\|^p\right\}(x)$$

In nice spaces

- Derivative

$$J_p = \nabla\frac{1}{p}\|\cdot\|^p$$

- Transport

$$J_{p'}^* J_p = I \quad J_p J_{p'}^* = I^*$$

- In Hilbert spaces  $J_2 = I$  (else nonlinear)

# Banach space geometry

## Definition ( $p$ -smoothness, $p$ -convexity)

$$\frac{1}{p} \|x - y\|^p \leq \frac{1}{p} \|x\|^p - \langle J_p(x), y \rangle + \frac{G_p}{p} \|y\|^p$$

$$\frac{1}{p} \|x - y\|^p \geq \frac{1}{p} \|x\|^p - \langle J_p(x), y \rangle + \frac{C_p}{p} \|y\|^p$$

## Examples

- $\ell^p, L^p, B_{p,r}^s, W_p^m$  are  $\min\{2, p, r\}$ -smooth ( $1 < p, r < \infty$ )
- $\ell^p, L^p, B_{p,r}^s, W_p^m$  are  $\max\{2, p, r\}$ -convex ( $1 < p, r < \infty$ )
- Hilbert spaces are 2-smooth and 2-convex (polarization identity)

# Case $X, Y$ Hilbert

## Standard

$$\Psi(x) = \frac{1}{2} \|Ax - y^\delta\|_Y^2 + \alpha \frac{1}{2} \|x\|_X^2$$

$$x^\dagger = A^* \omega \implies \|x_\alpha^\delta - x^\dagger\| \leq C\sqrt{\delta}$$

$$x^\dagger = (A^*A)^\mu \omega, \mu < 1 \implies \|x_\alpha^\delta - x^\dagger\| \leq C\delta^{\frac{2\mu}{1+2\mu}}$$

## Minimization schemes

$$A^*(Ax - y^\delta) + \alpha x = 0$$

$$x_{n+1} = x_n - \mu(A^*(Ax_n - y^\delta) + \alpha x_n)$$

## Case $X, Y$ Banach

$$\Psi(x) = \frac{1}{r} \|Ax - y^\delta\|_Y^r + \alpha \frac{1}{q} \|x\|_X^q$$

### FACT (HKPS, Hein)

Minimizers of  $\Psi$  can be used as regularizing sequence (for  $\delta \rightarrow 0$ ).

$$J_p(x^\dagger) = A^* \omega \implies \|x_\alpha^\delta - x^\dagger\|^{c_X} \leq C\delta$$

$$J_{S_X}(x^\dagger) = A^* J_{S_Y} A \omega \implies \|x_\alpha^\delta - x^\dagger\|^{c_X} \leq C\delta^{\frac{s_X s_Y}{s_X + s_Y - 1}}$$

### QUESTION

Minimization scheme?

## Case $X, Y$ Banach

$$\Psi(x) = \frac{1}{r} \|Ax - y^\delta\|_Y^r + \alpha \frac{1}{q} \|x\|_X^q$$

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### QUESTION

Minimization scheme?  $\rightsquigarrow$  Steepest descent

## Descent in the primal

$$x_{n+1} = x_n - \mu_n \mathcal{J}^* (\nabla \Psi(x_n))$$

$\mu_n$  via line search

$Y$   $r$ -smooth and  $X$   $p$ -smooth and  $s$ -convex, then  $(x_n)$  converge strongly to the minimizer of  $\Psi(x) := \frac{1}{r} \|Ax - y\|_Y^r + \frac{\alpha}{p} \|x\|_X^p$

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(Almost) sparse case

$$\Psi(x) := \frac{1}{2} \|Ax - y\|_2^2 + \alpha \frac{1}{1.01} \|x\|_{1.01}^{1.01}$$



## Descent in the dual

$$x_{n+1}^* \in x_n^* - \mu_n \partial \Psi(x_n) \quad x_{n+1} \in J^*(x_{n+1}^*)$$

$\mu_n$  small enough

$Y$  arbitrary,  $X$   $q$ -convex, then  $(x_n)$  converge strongly to the minimizer of  $\Psi(x) = \frac{1}{r} \|Ax - y^\delta\|_Y^r + \alpha \frac{1}{q} \|x\|_X^q$

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(Almost) sparse case

$$\Psi(x) := \frac{1}{2} \|Ax - y\|_2^2 + \alpha \frac{1}{2} \|x\|_{1.01}^2$$

## Convergence rates (dual)

$X$   $q$ -convex

$$\|x_n - x_\alpha^\delta\| \leq C \cdot n^{-\frac{1}{q(q-1)}}$$

$X$   $q$ -convex,  $Y$   $r$ -convex,  $M = \max\{q, r\} > 2$

$$\|x_n - x_\alpha^\delta\| \leq C \cdot n^{-\frac{(M-1)}{[(M-1)(q-1)-1]q}}$$

$X$  2-convex,  $Y$  2-convex

$$\|x_n - x_\alpha^\delta\| \leq C \cdot \exp(-n/C)$$

## Convergence rates (primal)

$X$   $s_X$ -smooth,  $c_X$ -convex  $Y$   $s_Y$ -smooth  $s = \min\{s_X, s_Y\} < c_X$

$$\|x_n - x_\alpha^\delta\| \leq C \cdot n^{-\frac{s-1}{c_X-s}}$$

$X$  2-smooth, 2-convex,  $Y$  2-smooth

$$\|x_n - x_\alpha^\delta\| \leq C \cdot \exp(-n/C)$$

# Landweber iteration

## Standard

$$x_{n+1} = x_n - \mu_n A^*(Ax_n - y^\delta) + \text{stoppage crit}$$

$$x^\dagger = A^* \omega \implies \|x_{\alpha(\delta)}^\delta - x^\dagger\| \leq C\sqrt{\delta}$$

$$x^\dagger = (A^*A)^\mu \omega \implies \|x_{\alpha(\delta)}^\delta - x^\dagger\| \leq C\delta^{\frac{2\mu}{1+2\mu}}$$

- no saturation
- only one iteration (cmp. to a-posteriori Tik.-reg.)

# Iteration in Banach space

Schöpfer, Schuster, Louis

$$J_p(x_{n+1}) = J_p(x_n) - \mu_n A^* J_{r,Y}(Ax_n - y^\delta) + \text{stoppage crit}$$

- no convergence rates
- special regularization (only cond. on  $X$ )
- usual regularization (cond. on  $X$  and  $Y$ )
- slow

# Iteration in Banach space

K, Hein

$$J_p(x_{n+1}) = J_p(x_n) - \mu A^* J_{r, \gamma}(Ax_n - y^\delta) + \beta_n J_p(x_n) + \text{stoppage crit}$$

- Convergence rate(s)

$$J_p(x^\dagger) = A^* \omega \implies \|x_{n(\delta)} - x^\dagger\| \leq C\sqrt{\delta}$$

- usual regularization (cond. on  $X$ )

# Open problems

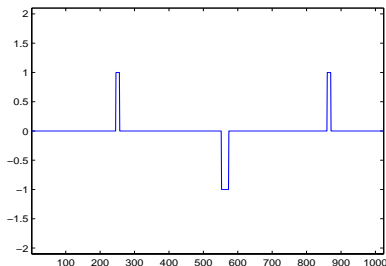
- slow algorithms (cmp. to spec. alg.) → acceleration?  
RESOP, SESOP
- asymptotic rates  $\leftrightarrow$  soph. choice of  $\alpha, \mu_n$
- only SC  $A^*\omega, A^*JA\omega \rightarrow$  gen. SC?



# The end

Thank you for your attention!

# An Inverse Problem - Restoring Peaks



$$Ax(t) = \int_0^t x(\tau) d\tau$$

$$\Psi(x) := \frac{1}{2} \|Ax - (Ax + \eta)\|_2^2 + \frac{\alpha}{2} \|x\|_{1.1}^2 \longrightarrow \min$$

# An Inverse Problem - Results

