



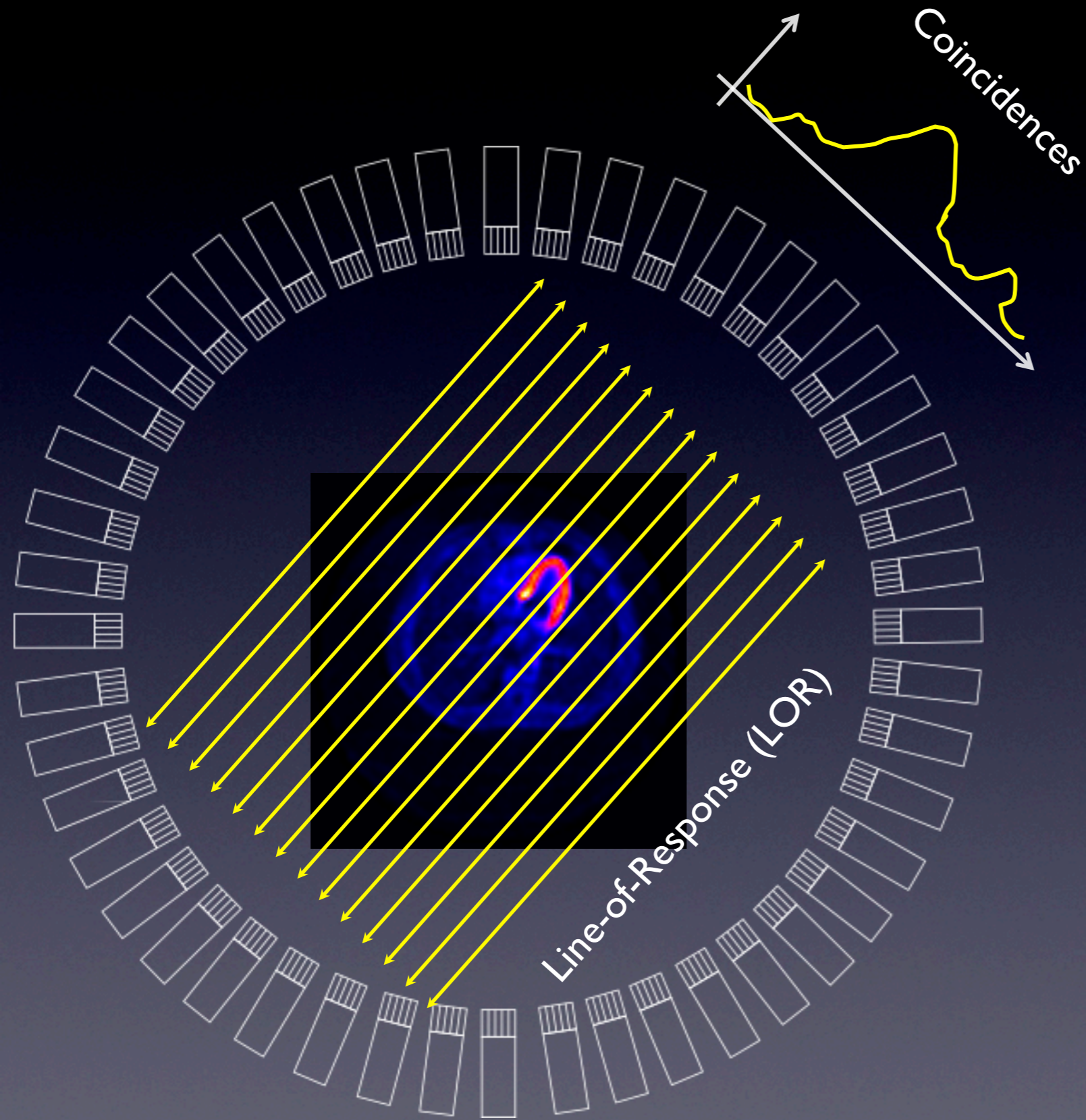
3D PET list-mode reconstruction including all available information provided by the detector

Awen AUTRET¹, Julien BERT¹, Olivier STRAUSS² and Dimitris VISVIKIS¹

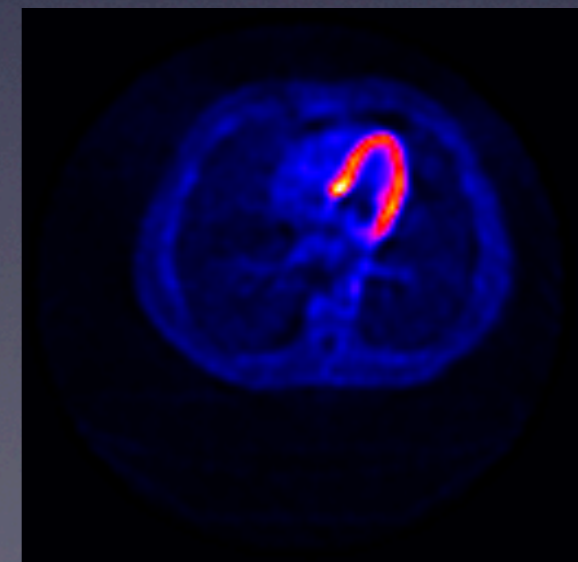
¹ Laboratoire du Traitement de l'Information Médicale (LaTIM)
INSERM UMR1101, CHRU Brest

² LIRMM, Université Montpellier 2, UMR5506

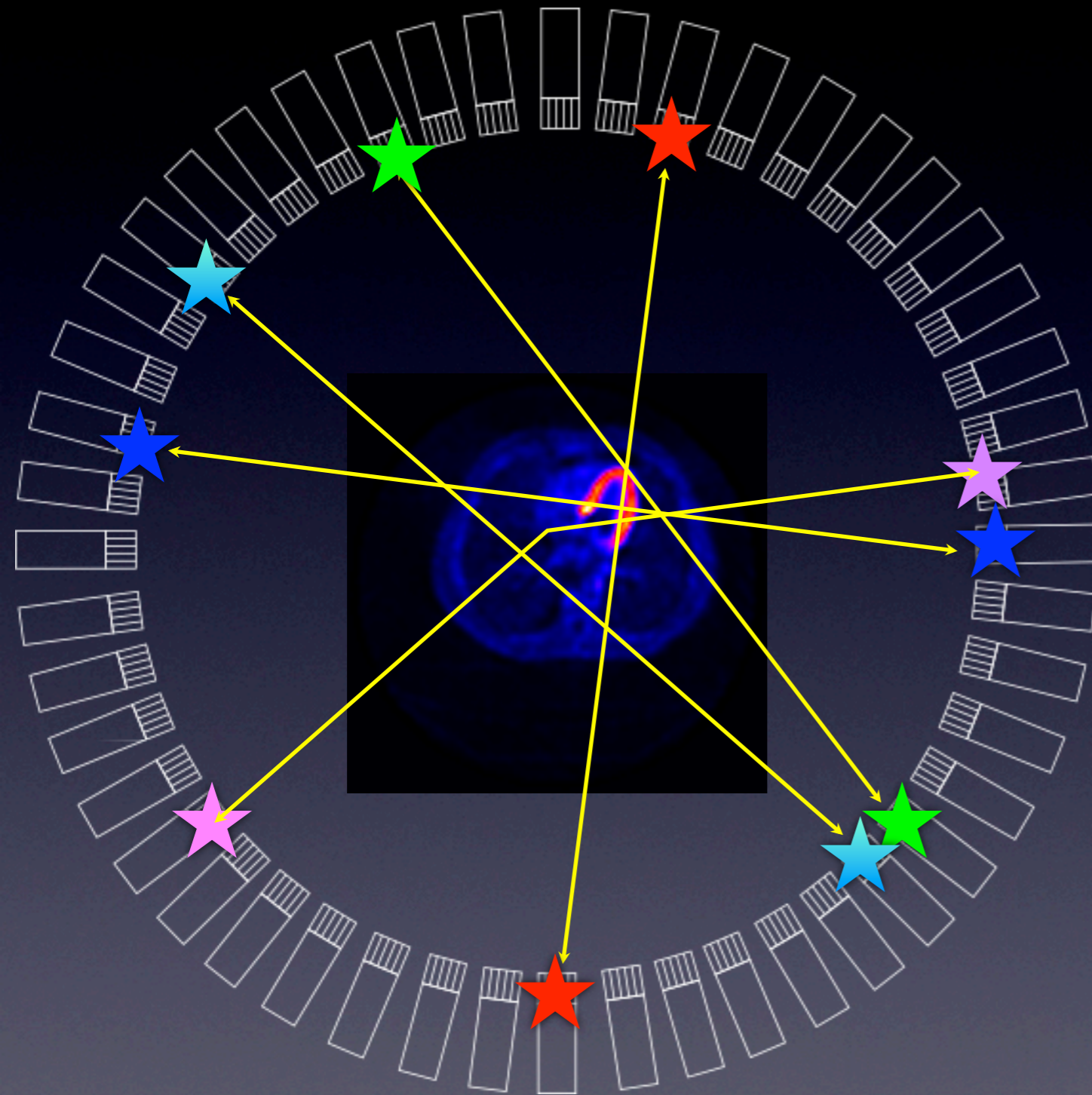
PET reconstruction



Sinogram



PET list-mode reconstruction



List-mode data:

ID1	T1	E1	DOI1
ID2	T2	E2	DOI2
ID3	T3	E3	DOI3
ID4	T4	E4	DOI4
ID5	T5	E5	DOI5

...

List-mode VS sinogram [Rahmim2004]:

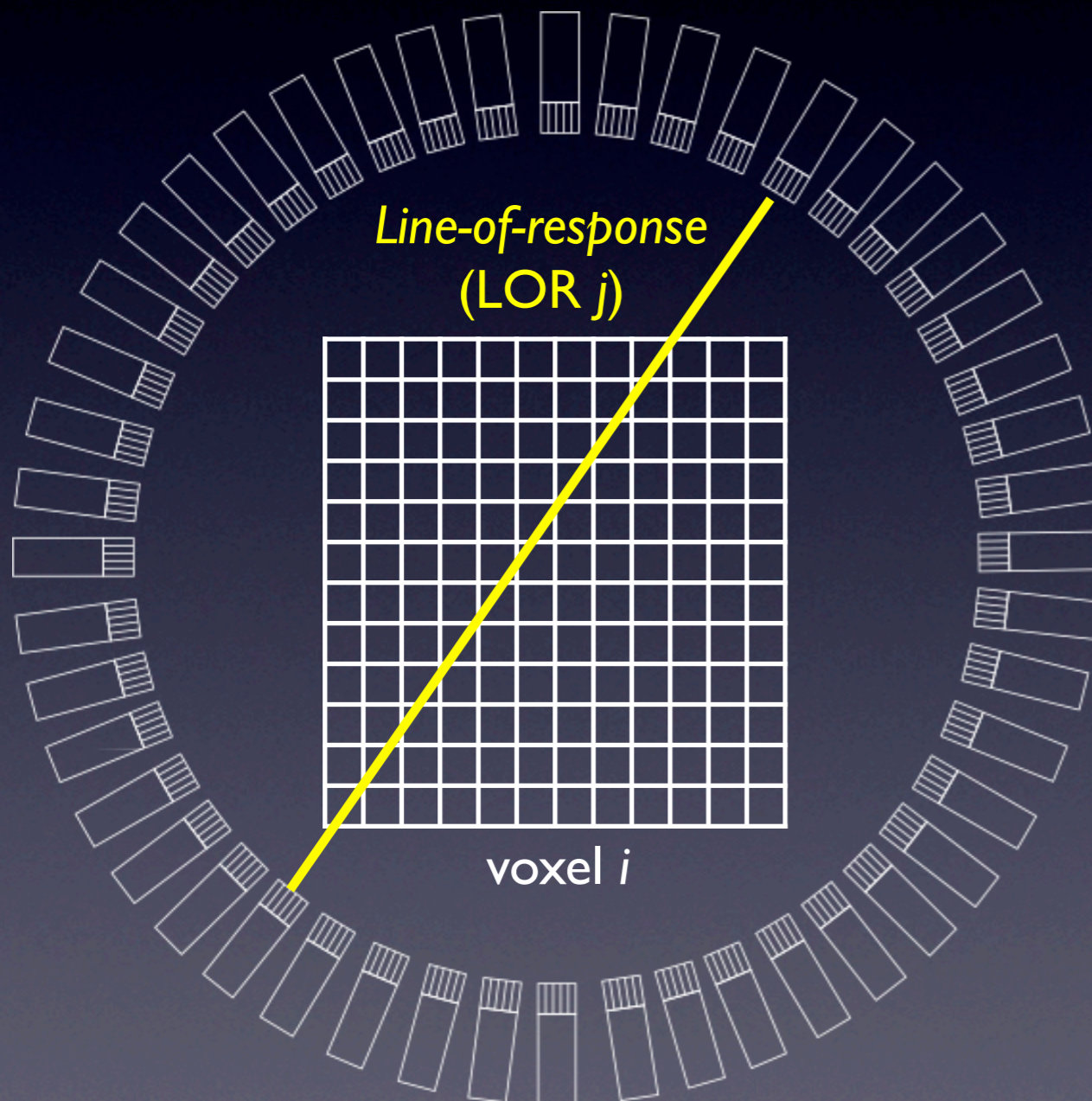
- Better spatial sampling
- Better temporal sampling (motion correction)
- More information: TOF, DOI, energy...

Quantitative clinical
reconstruction

PET list-mode reconstruction

Iterative reconstruction

- LM-OSEM [Reader 1998]
- For each LOR, forward and backward projection



System Matrix (SM)

Probability to detect a positron emission from the voxel i with the LOR j

store the “contribution” of each LOR in image space

$$\text{card}(SM) = (M, N)$$

M is the number of LORs and N the numbers of voxels

$$\text{card}(SM) = (M, N, t)$$

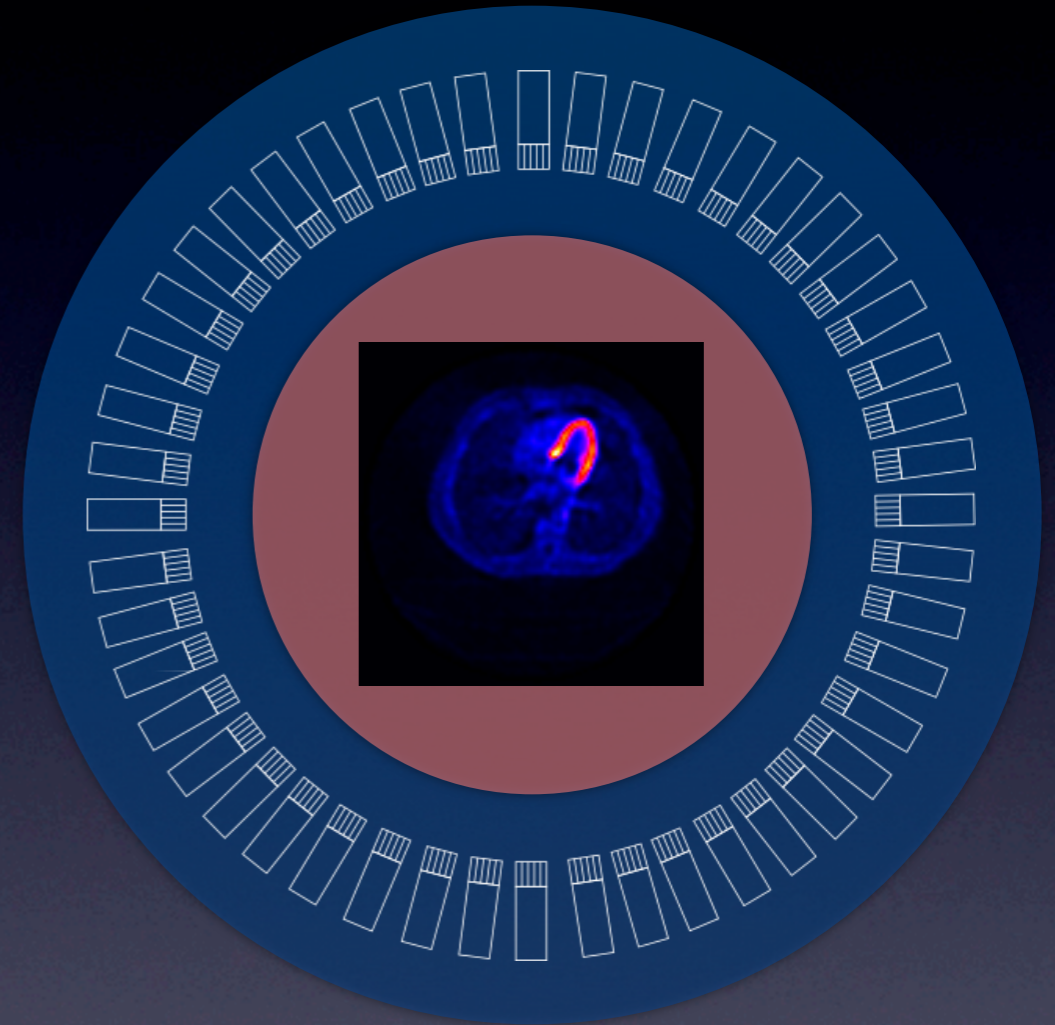
Huge matrix

- difficult to include additional information
- memory size (specially for GPU)

PET list-mode reconstruction

SM decomposition [Qi 1998]

$$\mathbb{R}^{M \times N} \quad \mathbb{R}^{N \times N} \quad \mathbb{R}^{N \times N} \\
 \text{SM} = \underbrace{\mathcal{P}}_{\text{Scanner}} + \underbrace{\mathcal{M}_{po} + \mathcal{M}_{pi}}_{\text{Patient physiology+physics}}$$



PET list-mode reconstruction

SM decomposition [Qi 1998]

$$\mathbb{R}^{M \times N} \quad \mathbb{R}^{N \times N} \quad \mathbb{R}^{N \times N}$$

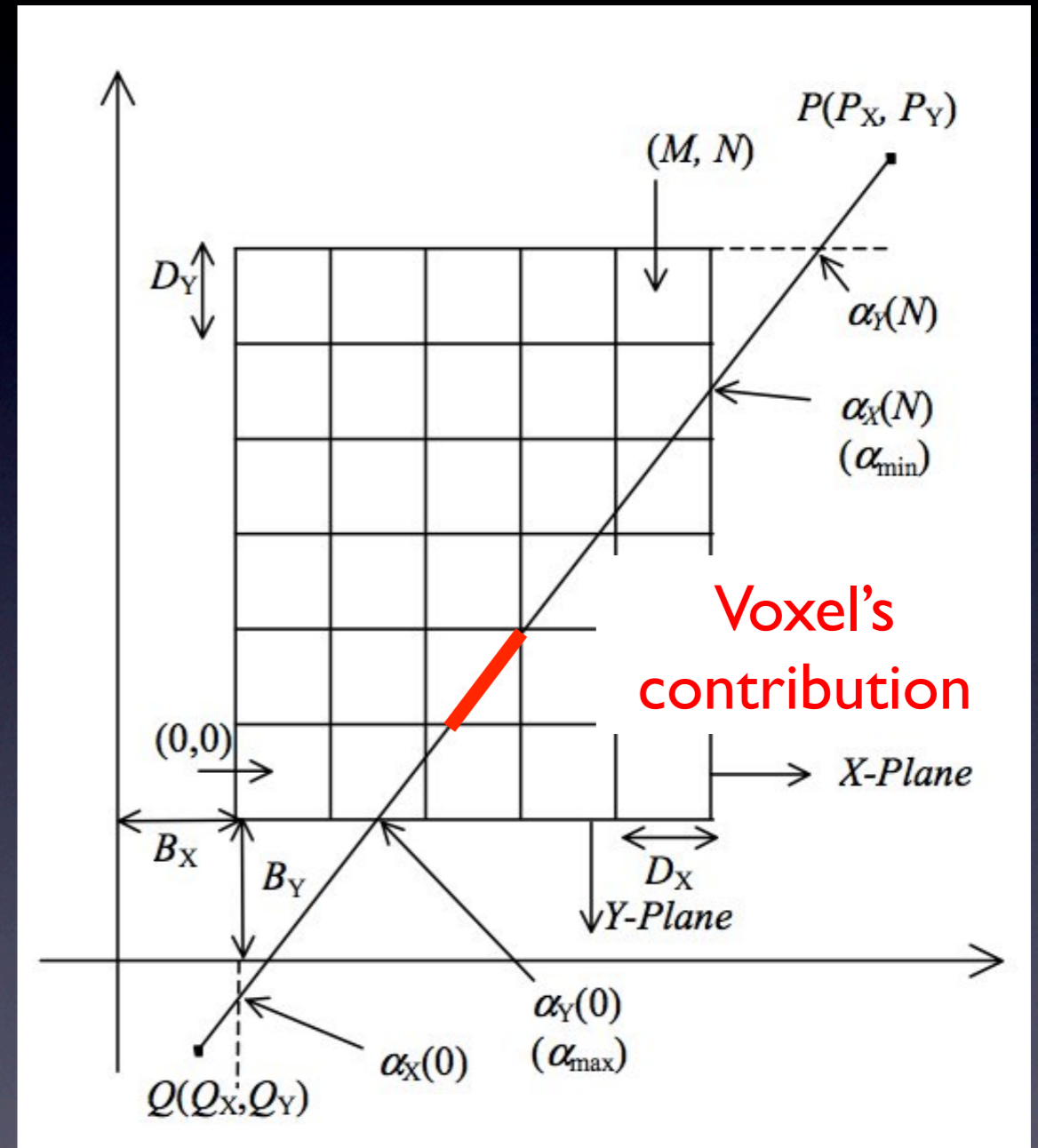
$$SM = \underbrace{\mathcal{P}}_{\text{Scanner}} + \mathcal{M}_{po} + \mathcal{M}_{pi}$$



Compute on-the-fly the contribution of the LOR using a projector

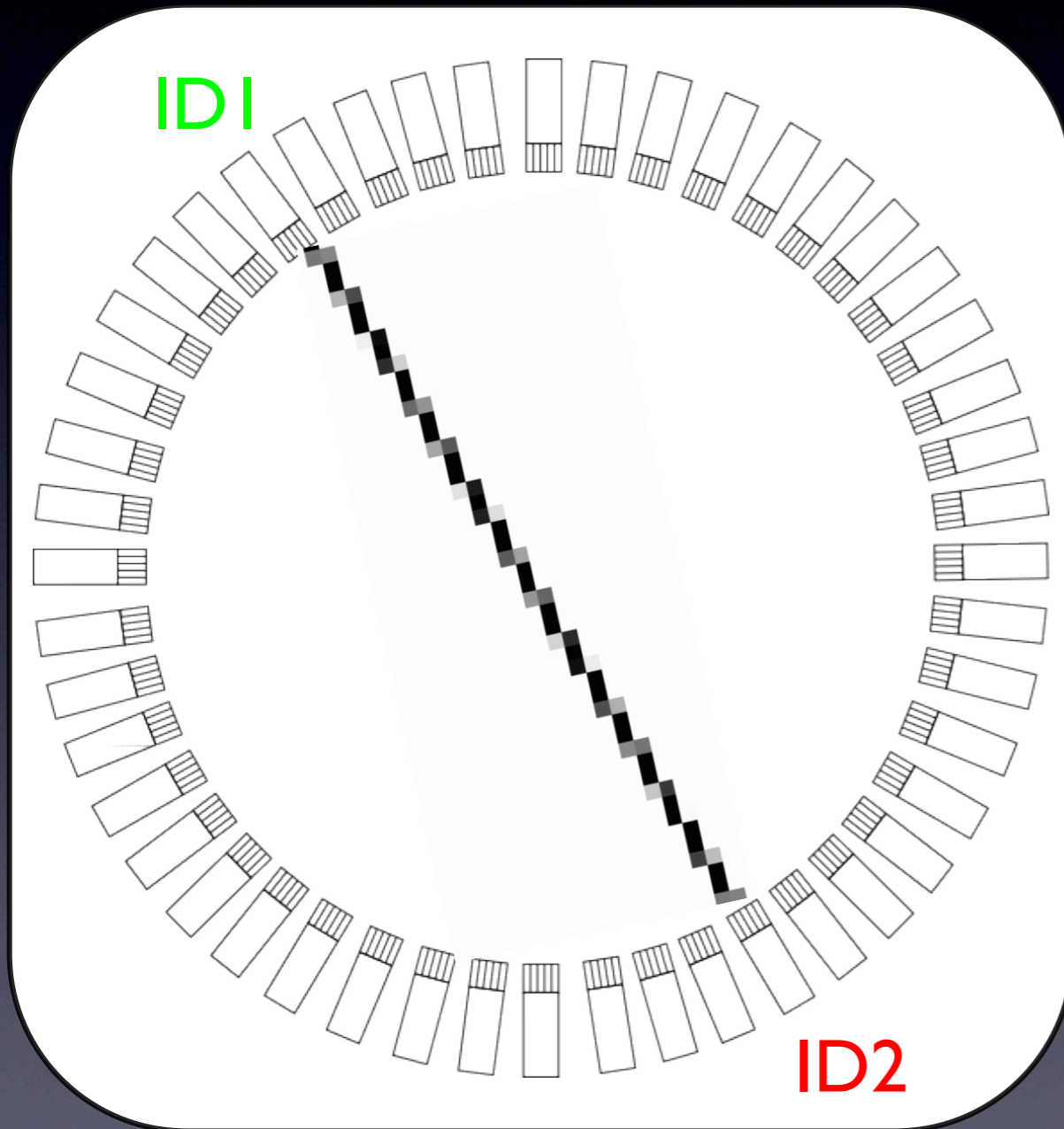


Siddon's algorithm [Siddon 1985, Zao 2002]



PET list-mode reconstruction

Siddon's algorithm is a simple projector
using only detector IDs



Recent and future detectors are able or will be able to record many kind of information

List-mode data:

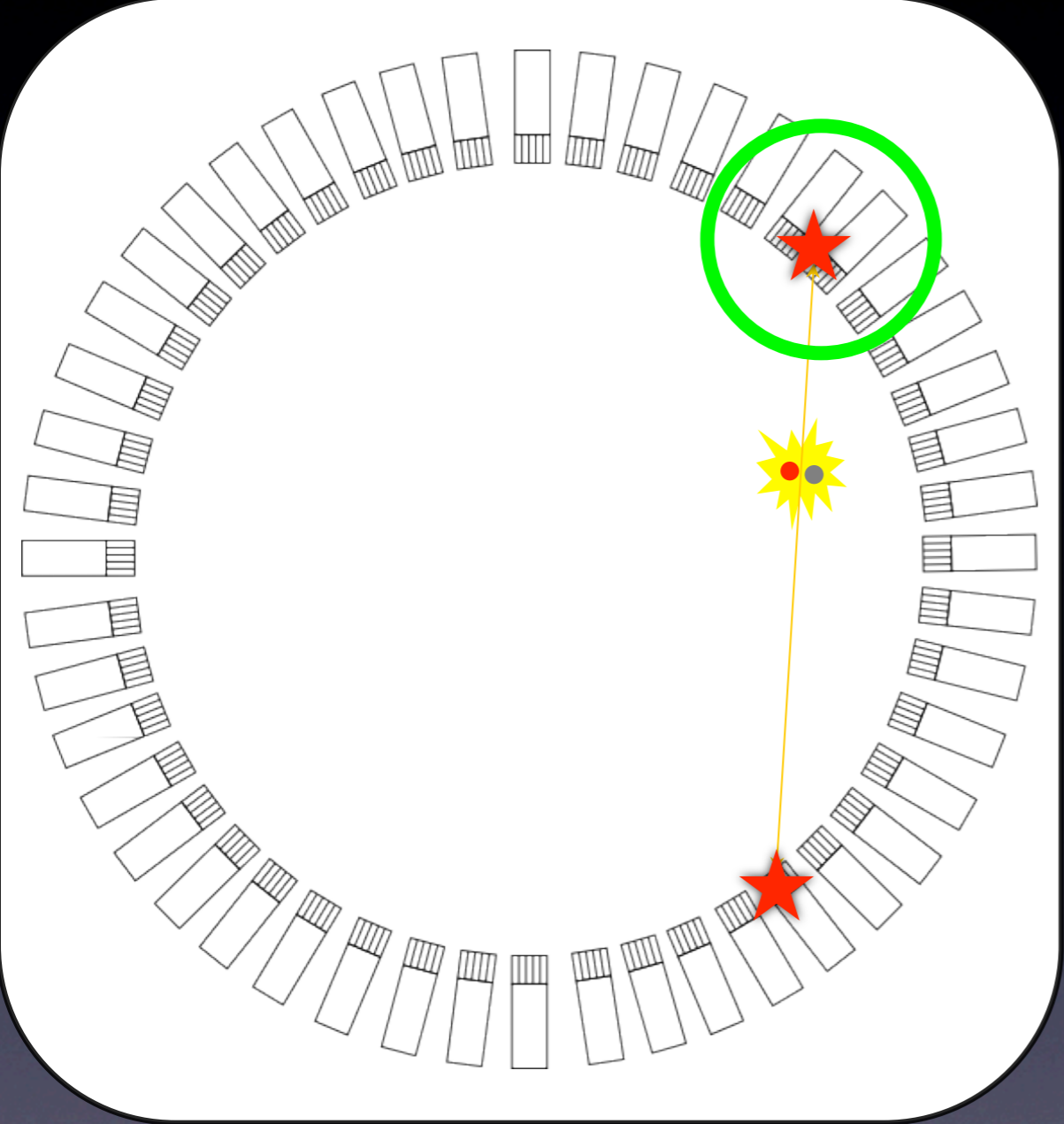
ID1	T1	E1	DOI1
ID2	T2	E2	DOI2
ID3	T3	E3	DOI3
ID4	T4	E4	DOI4
ID5	T5	E5	DOI5

...



How to use this information within the projector

Considering the detector itself



Geometrical effects

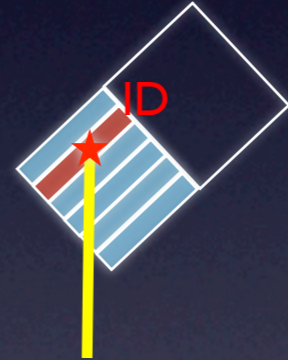
- rectangular crystals shape
- cylindrical scanner



Gamma photon

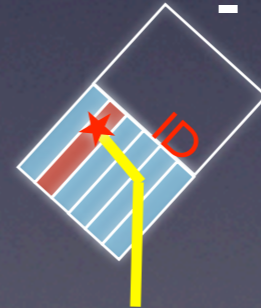
Crystal penetration

- photoelectric effect



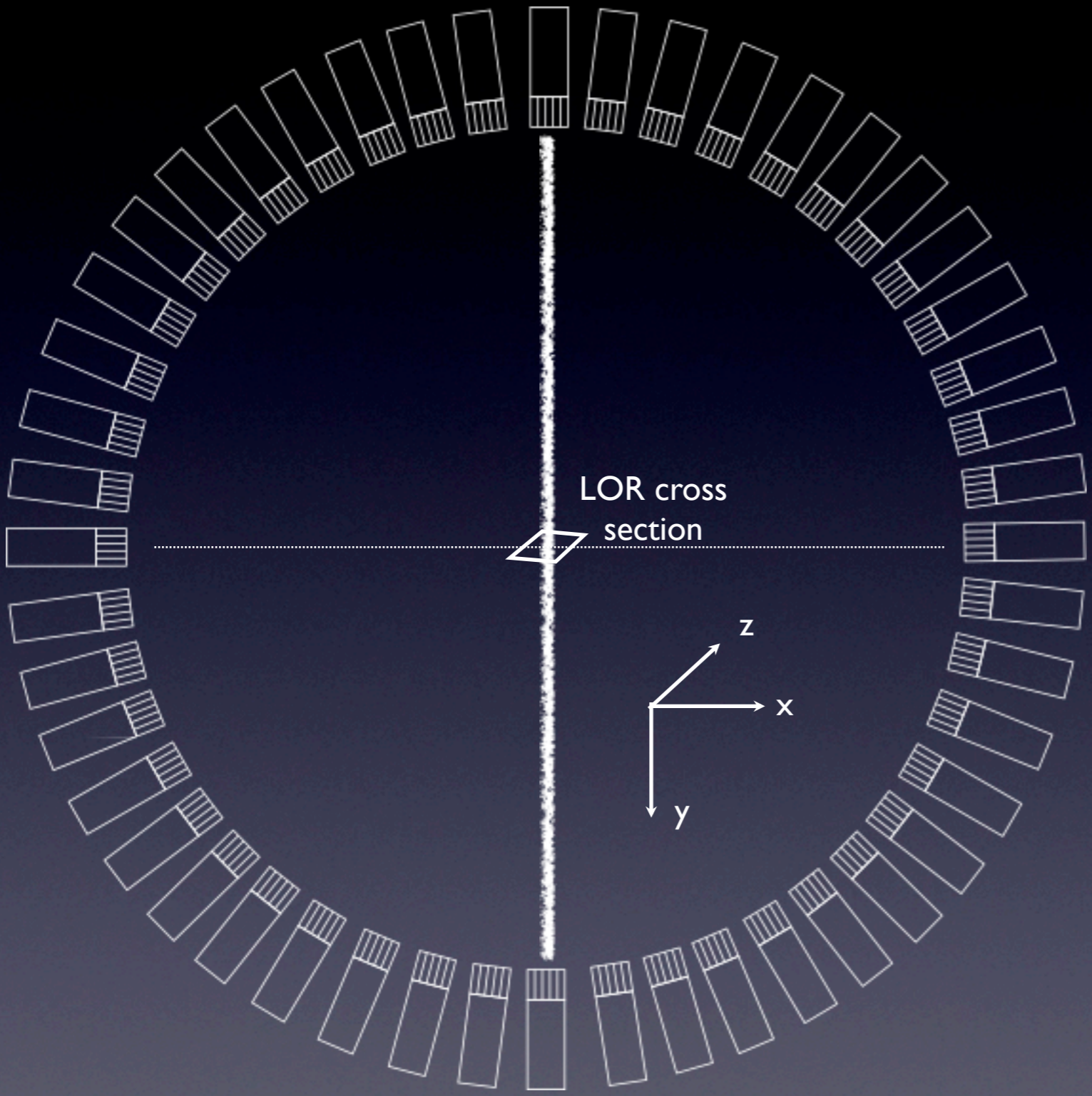
Intra and inter crystal scattering

- Compton scattering

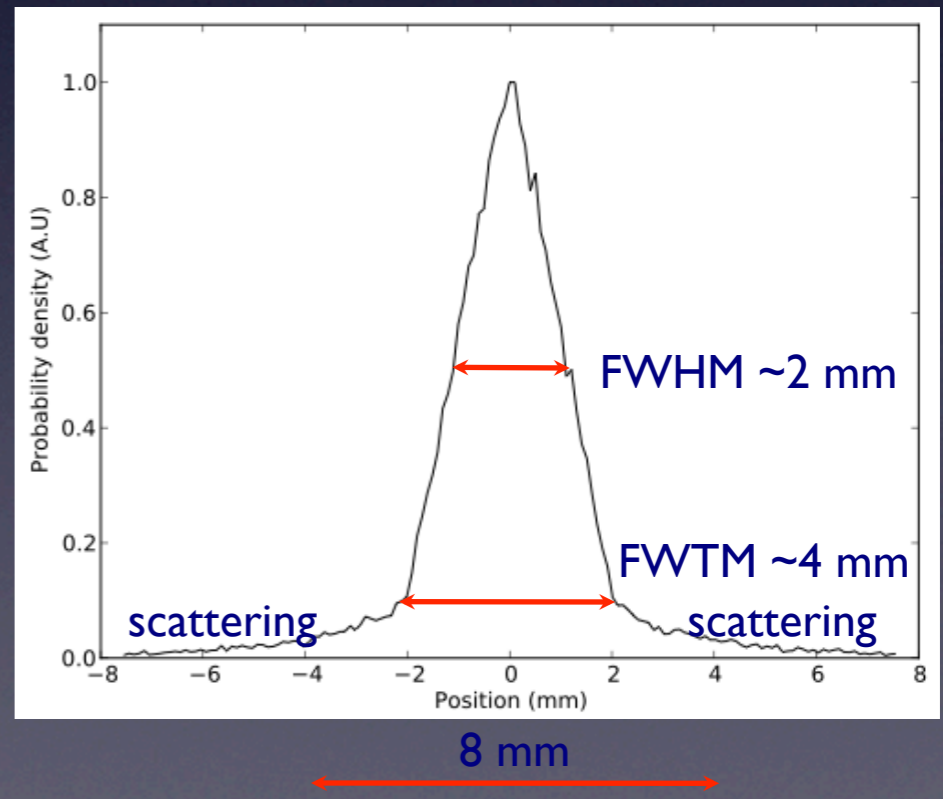
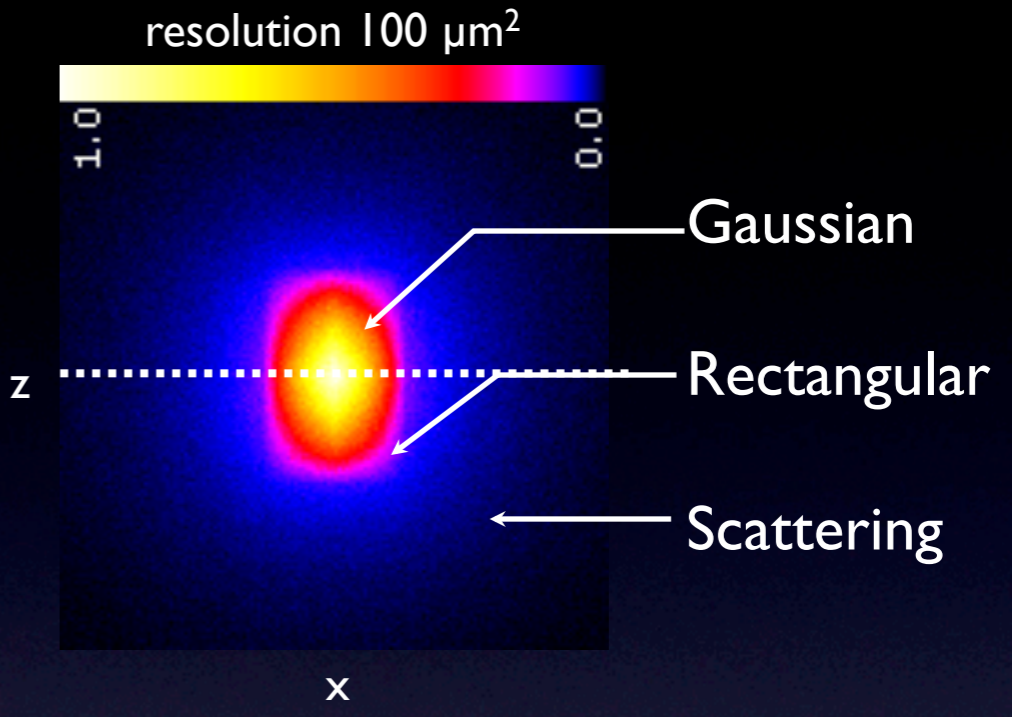


Does Siddon projector (a simple line) is enough?

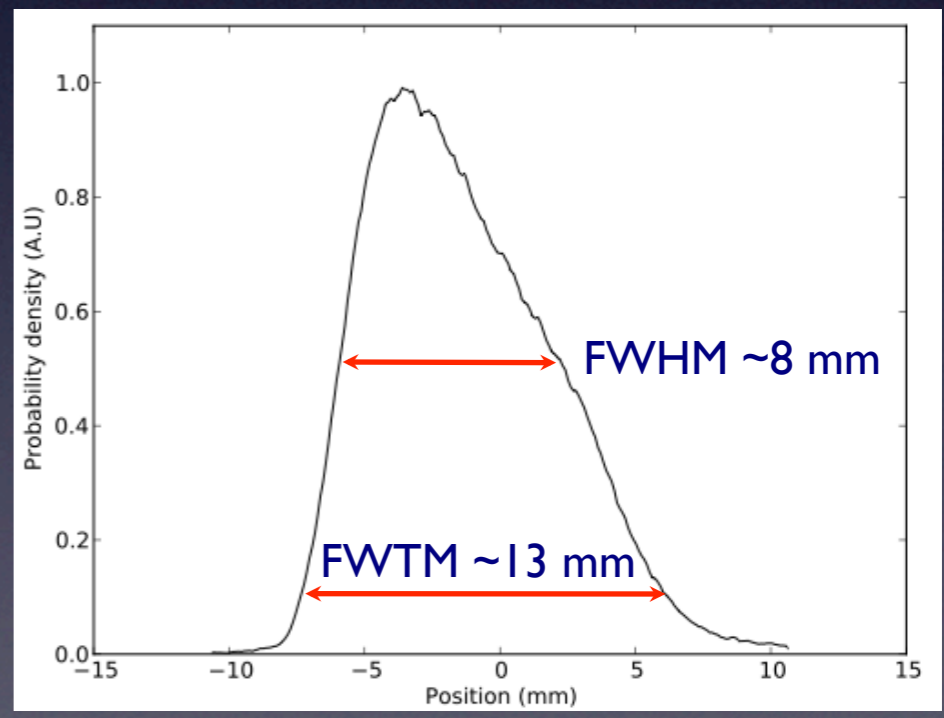
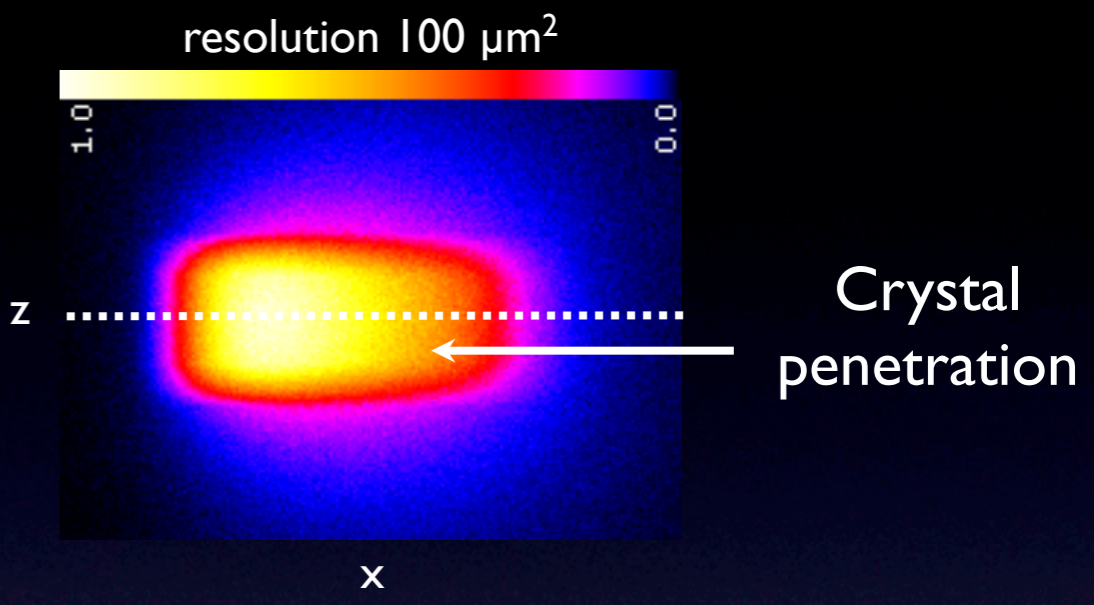
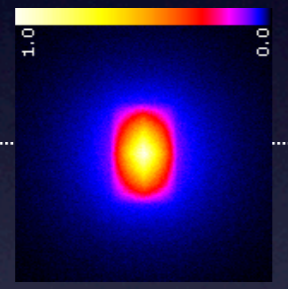
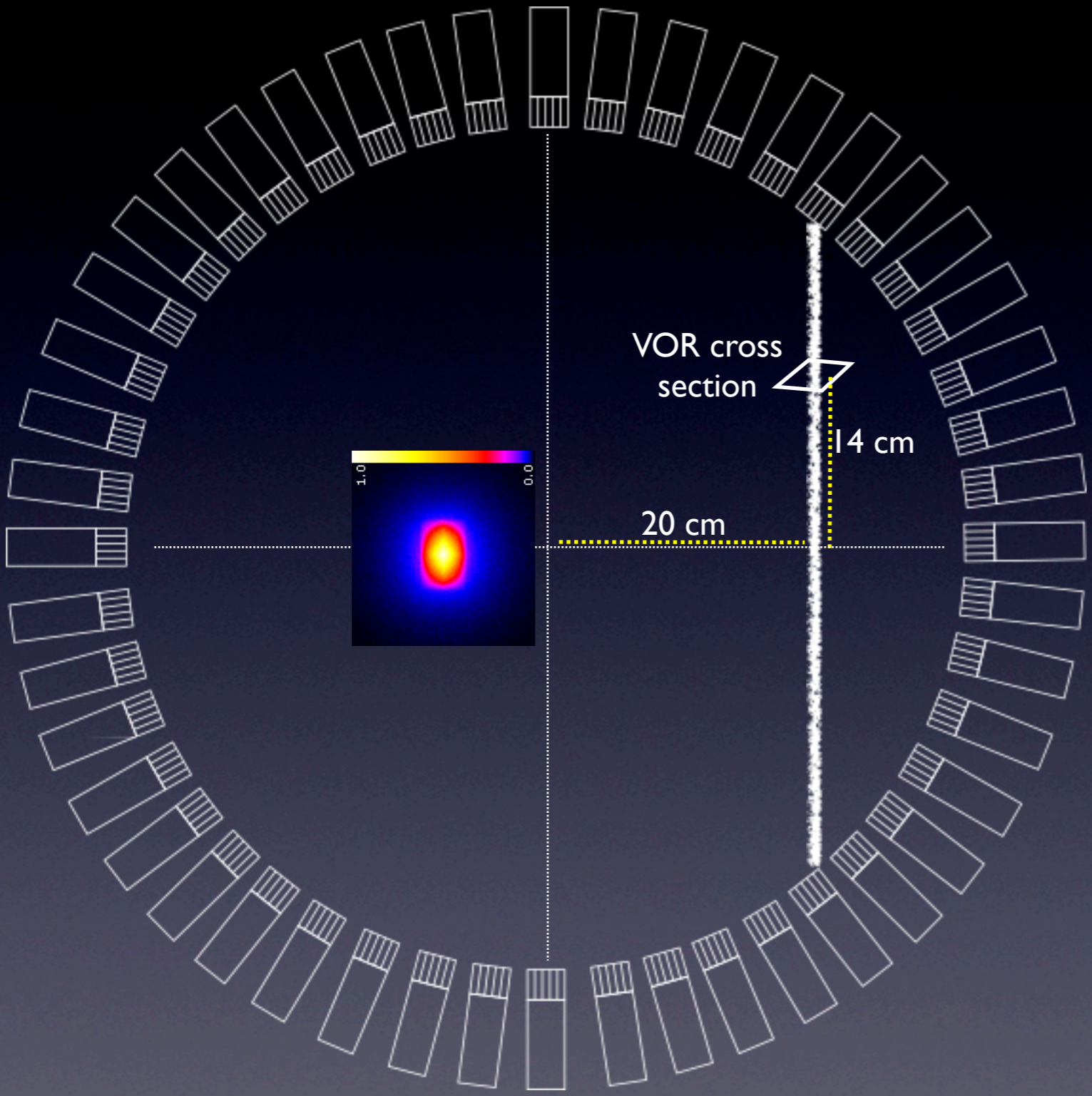
Considering the detector itself



PET Philips GEMINI

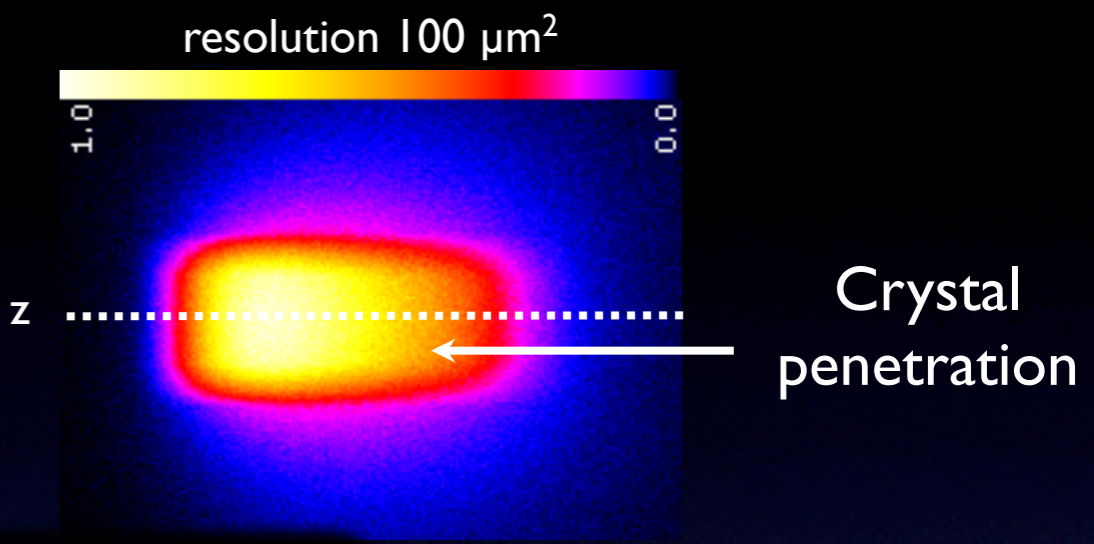
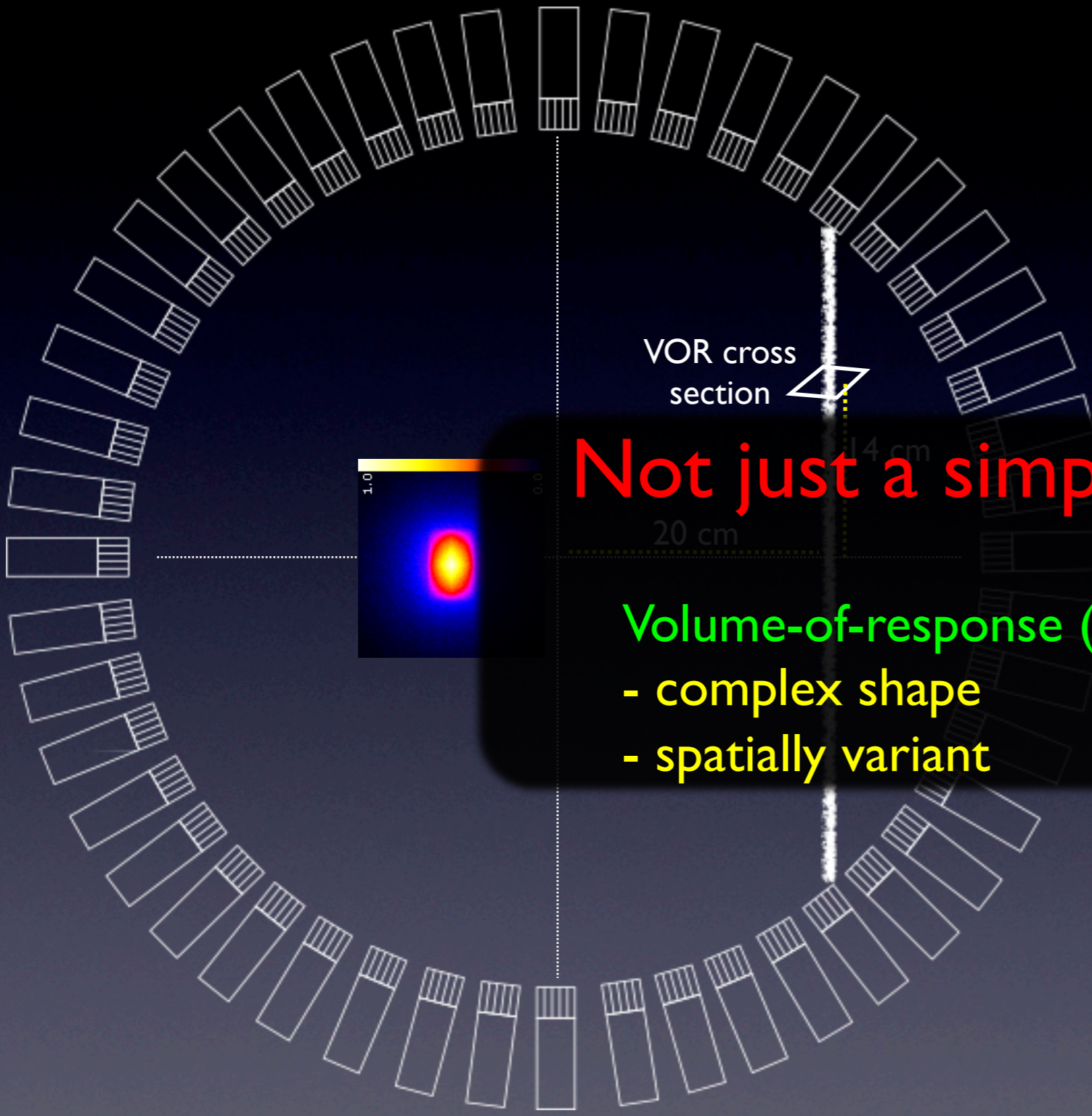


Considering the detector itself



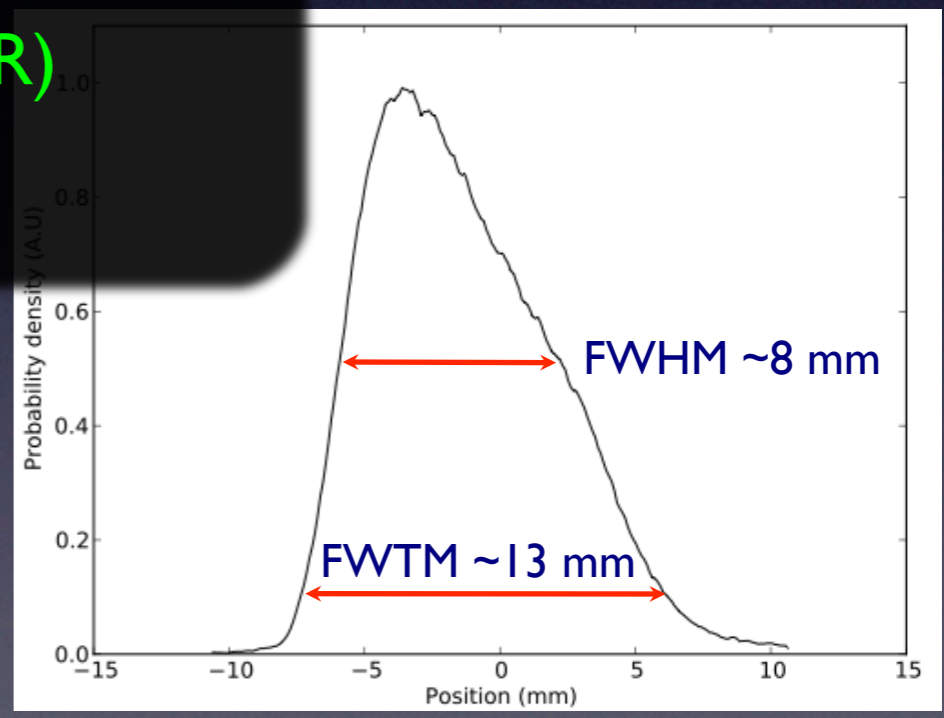
PET Philips GEMINI

Considering the detector itself



Not just a simple line!

- Volume-of-response (VOR)
- complex shape
- spatially variant

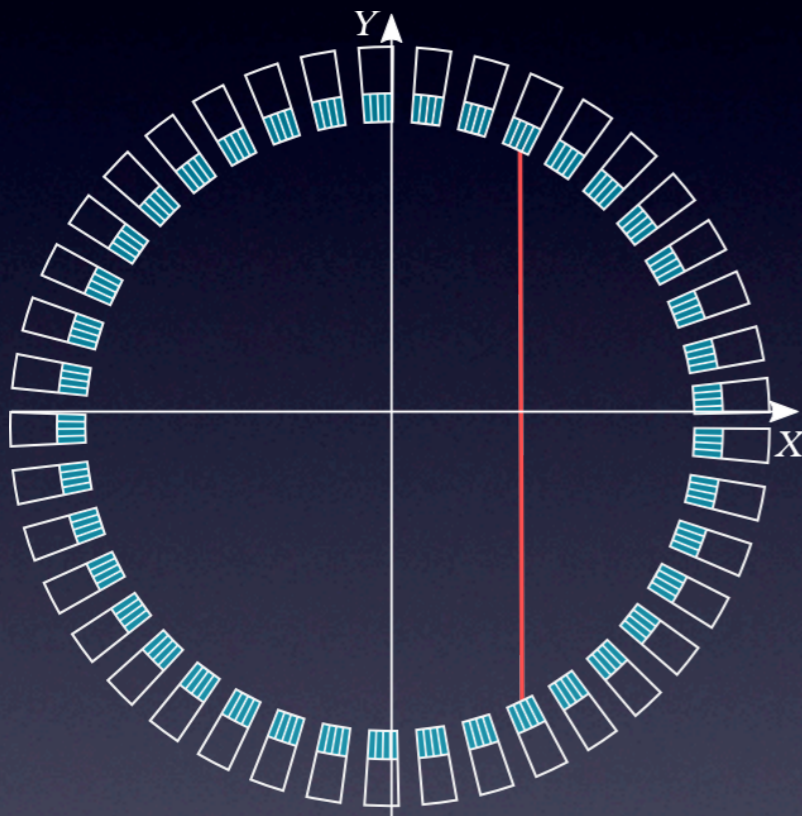


PET Philips GEMINI

Considering the detector itself

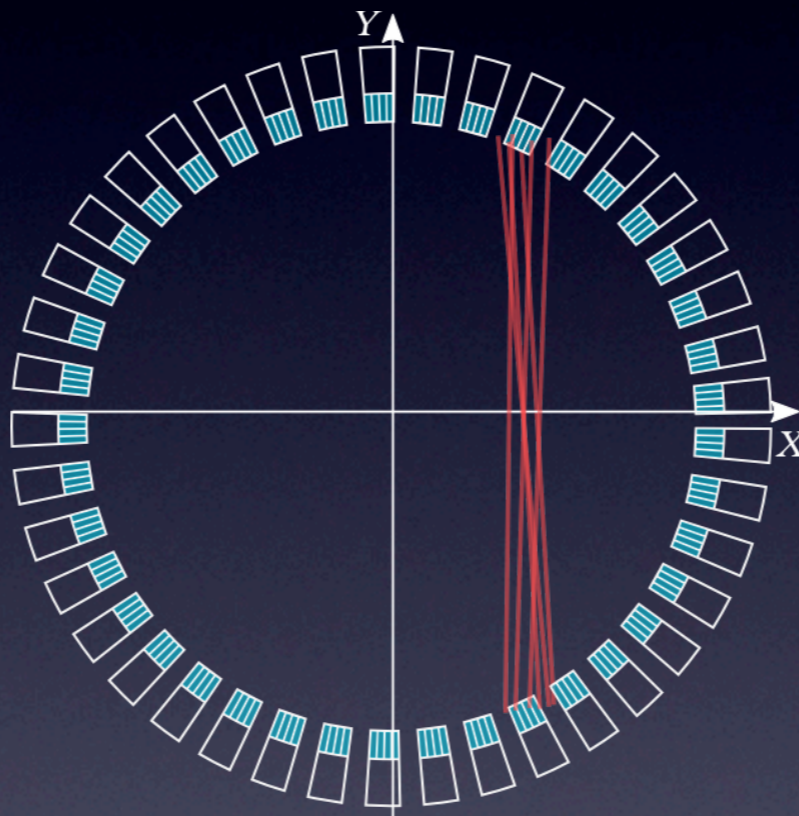
Computes on-the-fly the VOR including the detector effects

Single line
[Siddon 1985]



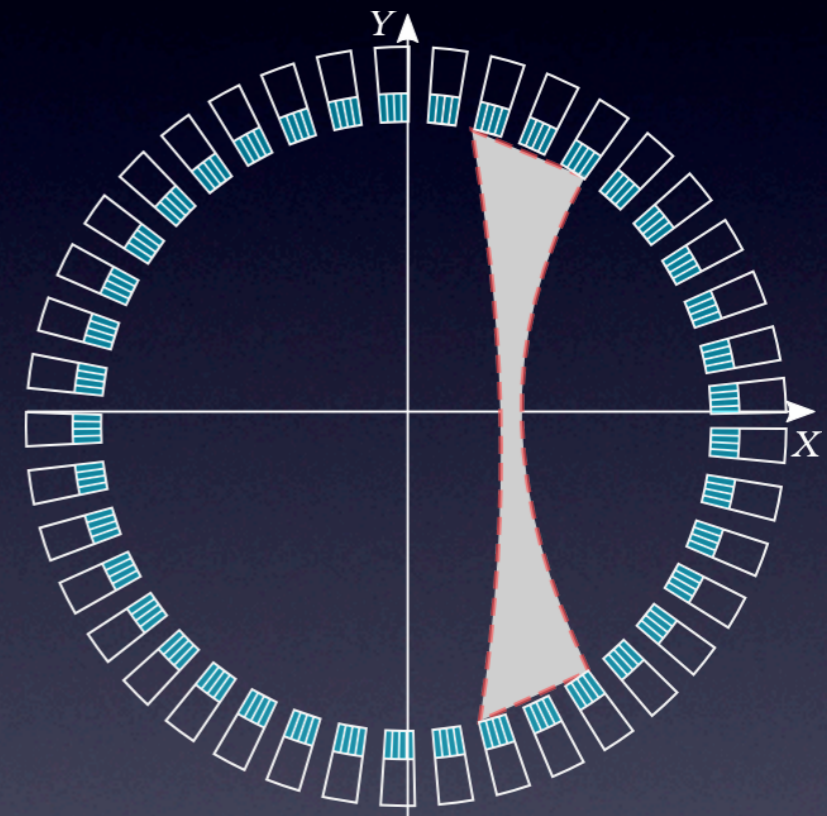
Geometrical effect
Crystal penetration
Crystal scattering

Multiple rays
[Chen2007, Moehrs2008]



Geometrical effect
Crystal penetration
Crystal scattering

VOR modeling
[Ortuño2011, Cui2011]

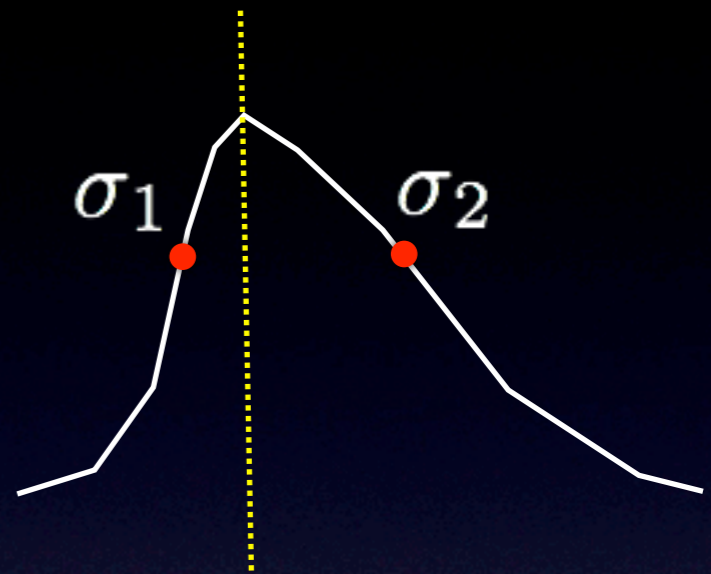
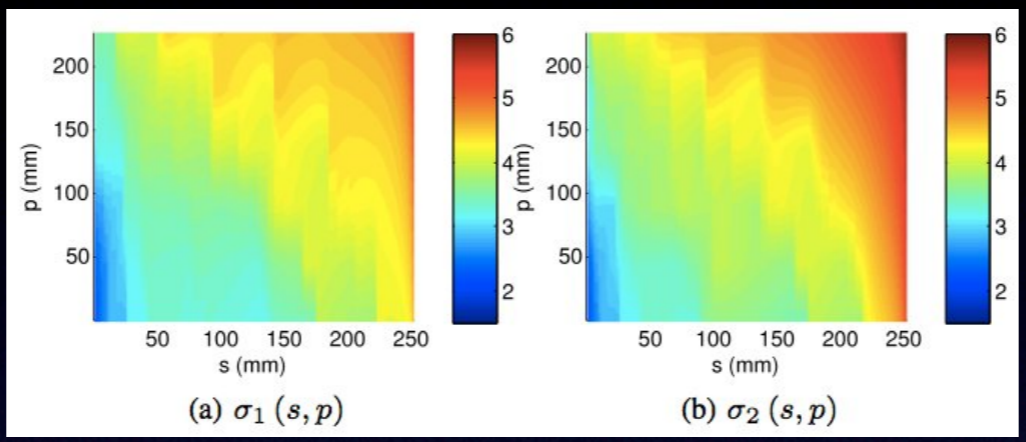
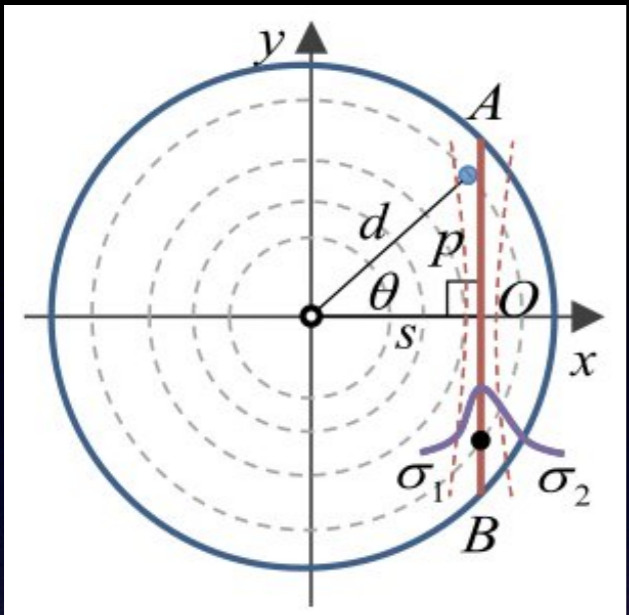


Geometrical effect
Crystal penetration
Crystal scattering

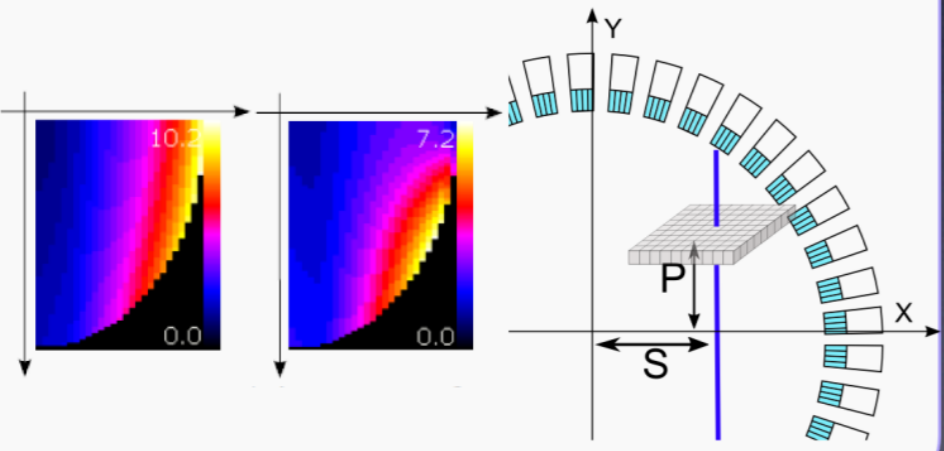
[Cui2011] spatially variant

Considering the detector itself

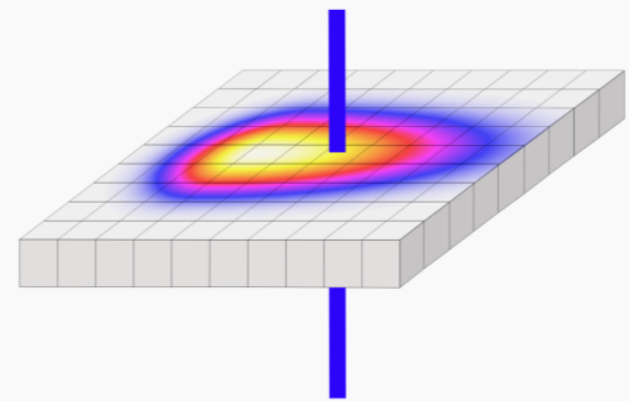
Gaussian VOR modeling [Cui2011a, Cui2011b]



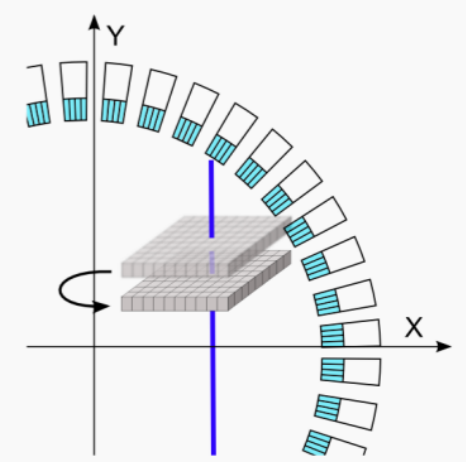
1. From the first slice of the VOR: select σ_{left} and σ_{right} of the gaussian model using the tables of pre-measured data.



2. Render the 2D asymmetrical Gaussian distribution in the current slice.

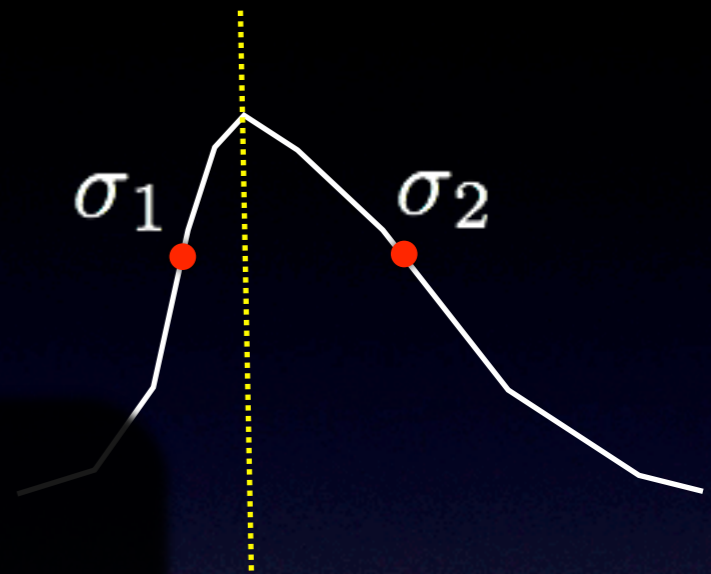
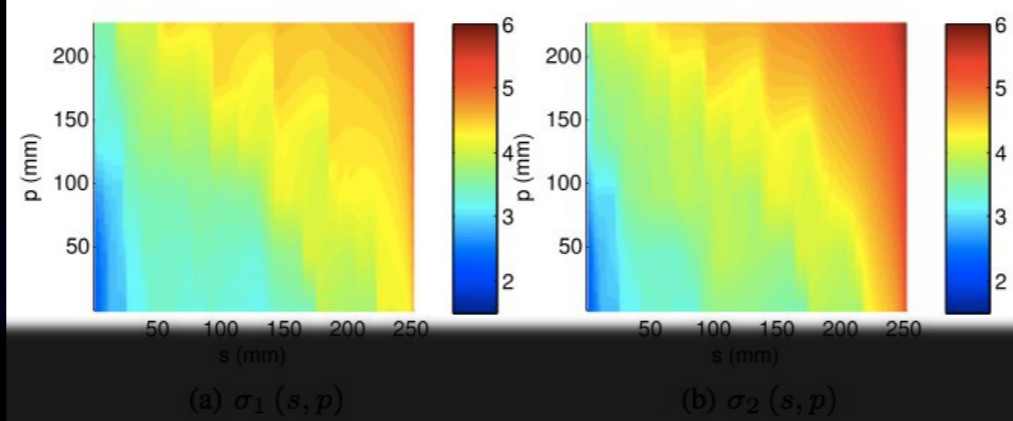
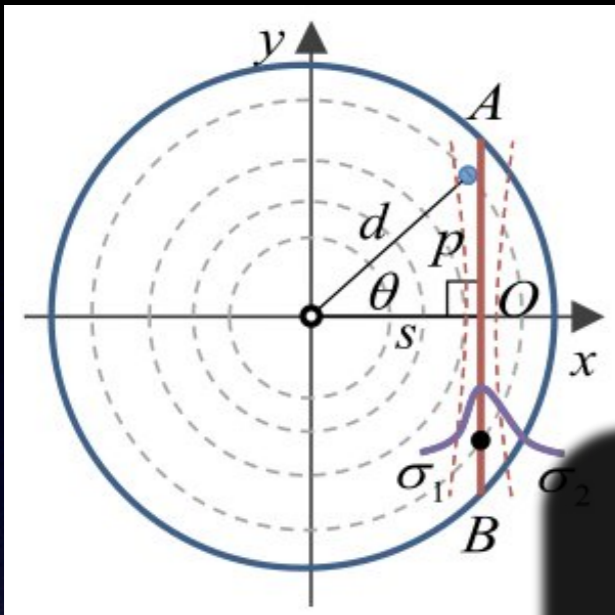


3. Go to the next slice and back to step 1 until the VOR is fully rendered.



Considering the detector itself

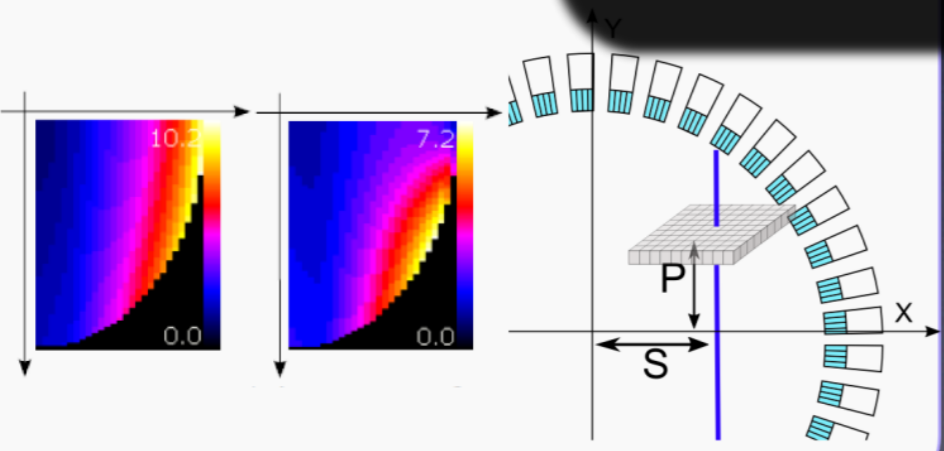
Gaussian VOR modeling [Cui2011a, Cui2011b]



Gaussian as VOR:

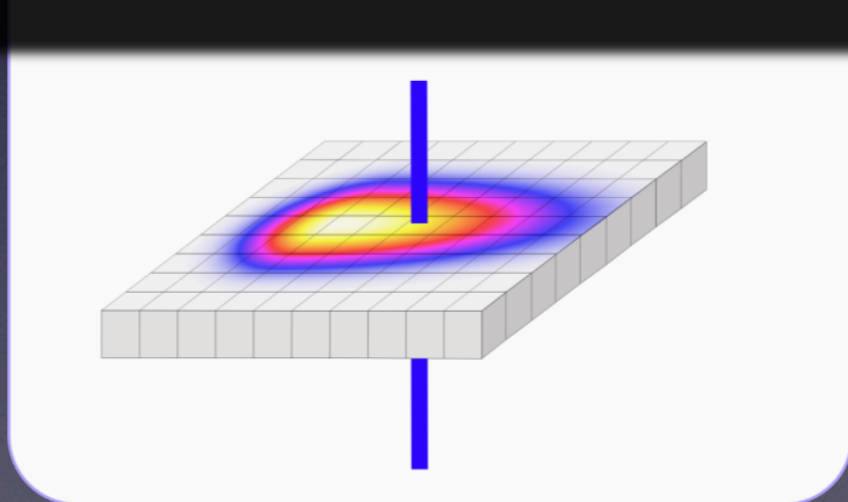
- no rectangular shape
- no scattering

1. From the first slice of the VOR, select the σ_{left} and σ_{right} of the gaussian model using the tables of pre-measured data.

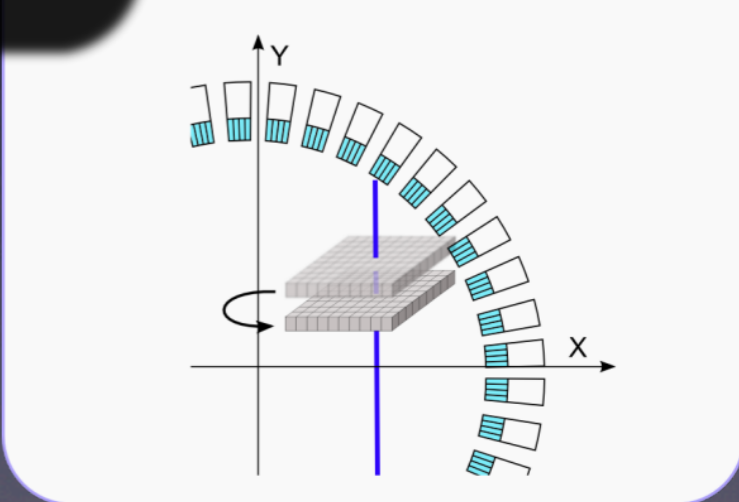


required interpolation to cover the field-of-view

2. Interpolate the Gaussian distribution in the current slice.



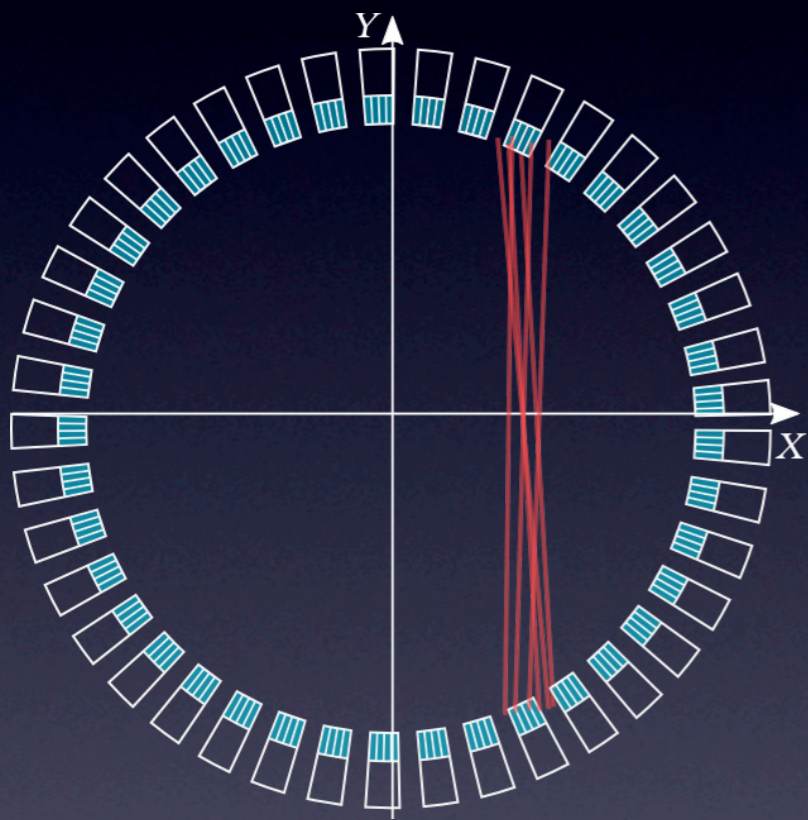
3. Go to the next slice and back to step 1 until the VOR is fully rendered.



Considering the detector itself

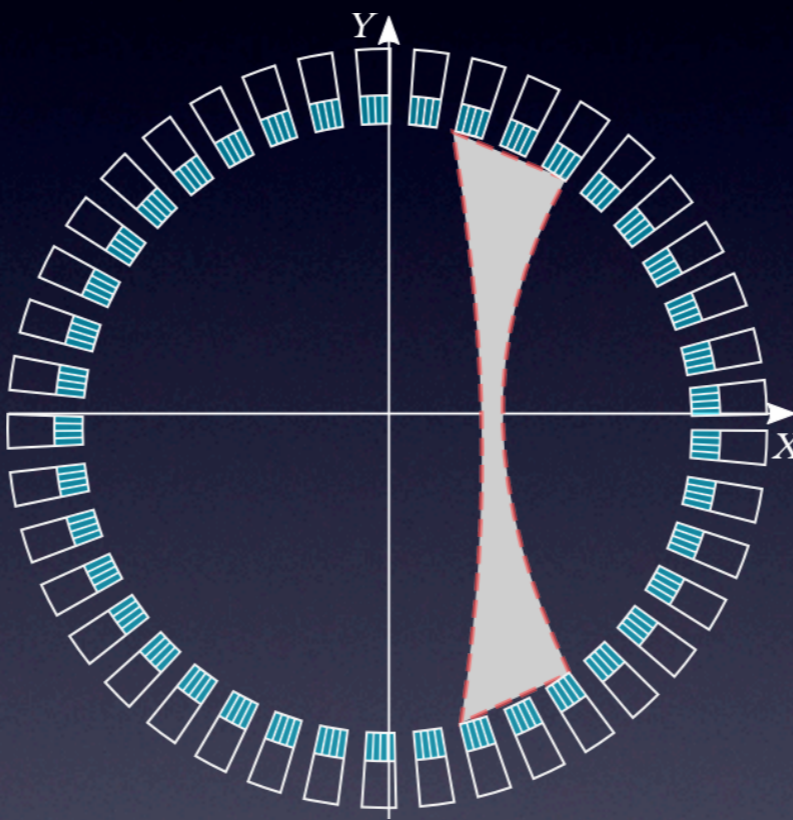
Computes on-the-fly the VOR including the detector effects

Multiple rays
[Chen2007, Moehrs2008]



Geometrical effect
Crystal penetration
Crystal scattering

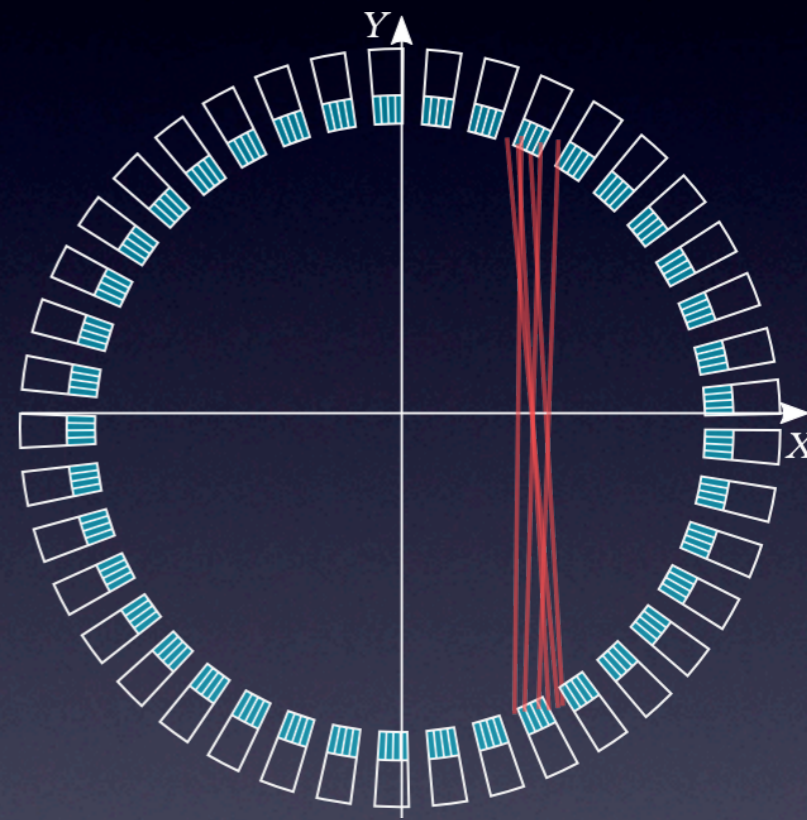
VOR modeling
[Ortuño2011, Cui2011]



Geometrical effect
Crystal penetration
Crystal scattering

[Cui2011] spatially variant

Multiple rays VOR modeling
[Autret2012]



Geometrical effect
Crystal penetration
Crystal scattering

Spatially variant

Ortuno et al., IEEE MIC, 2011

Cui et al., IEEE MIC, 2011

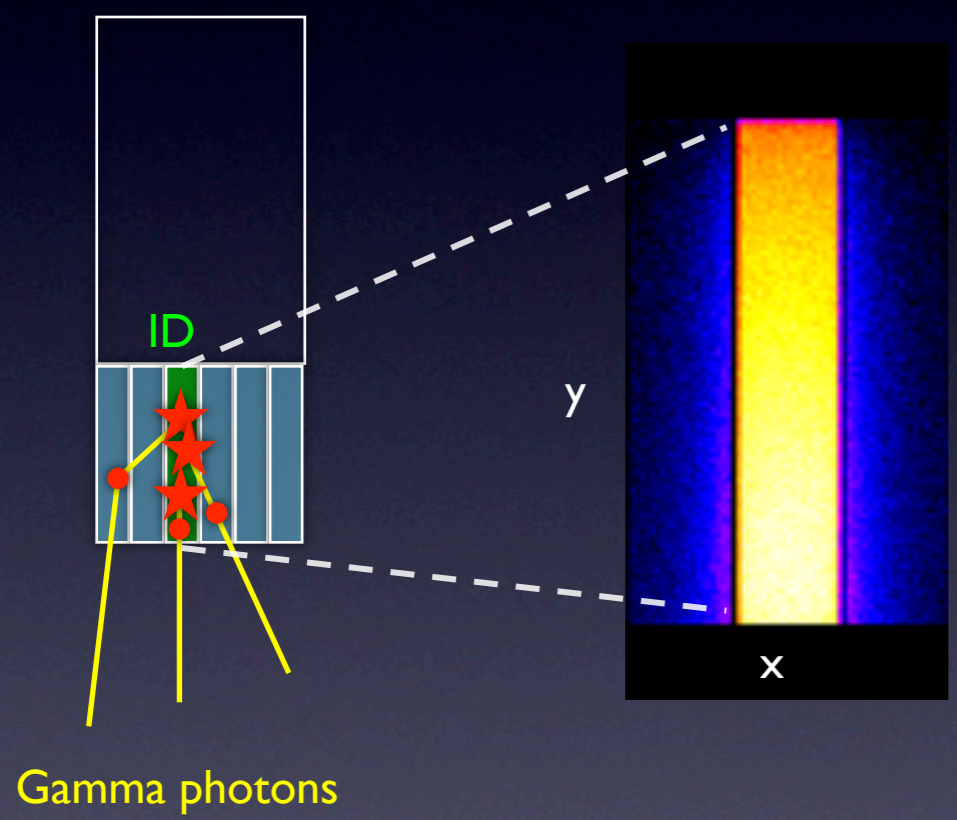
Autret et al., IEEE MIC, 2012

Moehrs, Phys. Med. Biol., 2008
Chen & Glick, IEEE MIC, 2007

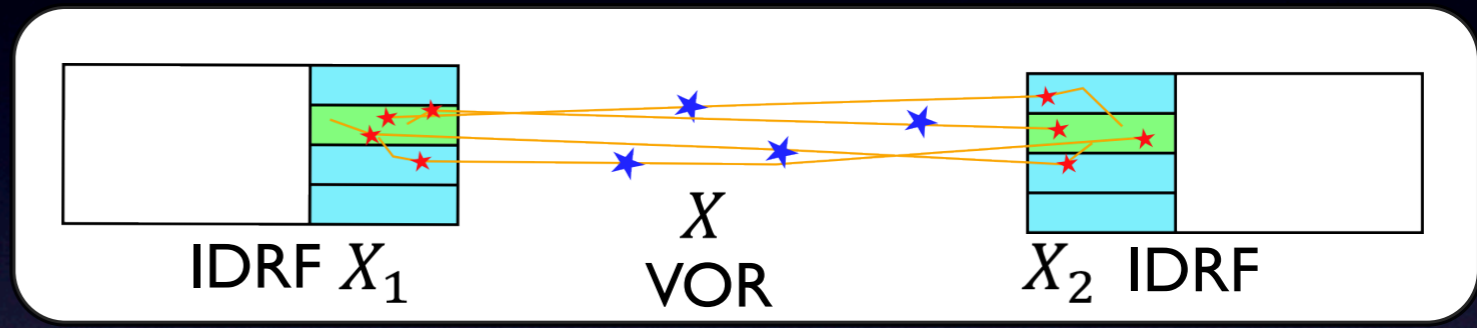
Considering the detector itself



Intrinsic Detector Response Function (IDRF)



VOR and IDRFs

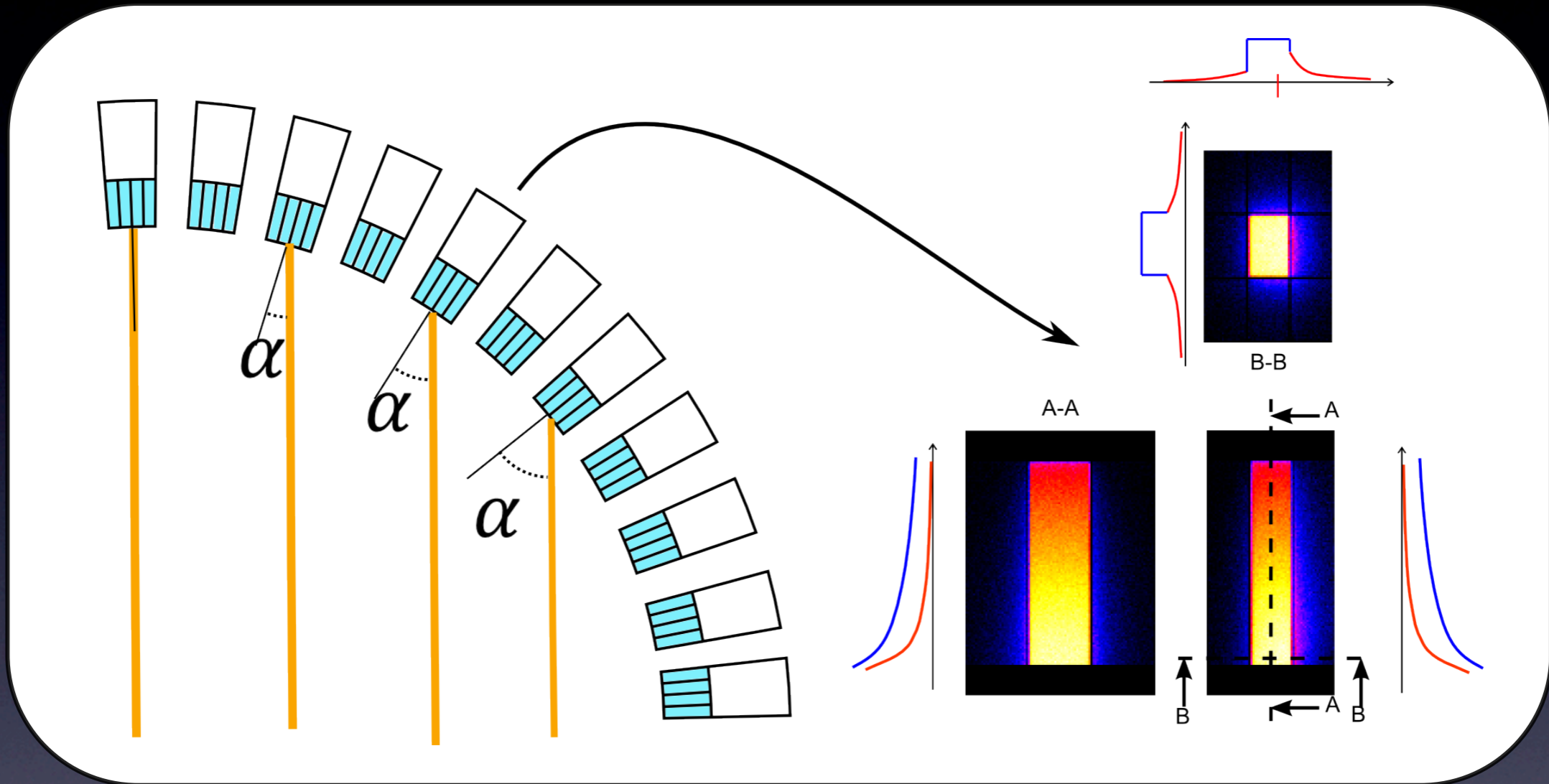


Relationship between the VOR and the IDRFs of both detectors [Gonzalez2011]:

$$X_{\text{VOR}} = \frac{1}{2}(1 - t)X_{1\text{IDRF}} + \frac{1}{2}(1 + t)X_{2\text{IDRF}}$$

Considering the detector itself

Full IDRF modeling based on Monte Carlo simulation [Awen2012]



Analytical model

- Geometrical effect
- Crystal penetration
- Crystal scattering
- Spatially variant
- Easy to extend with other information (DOI, TOF, etc)

Considering the detector itself

Iterative Random IDRf Sampling (IRIS) [Autret2012, Autret2013a]

1. Select both IDRf models related to both crystal detectors of the LOR.

$$X = \frac{1}{2}(1-t)X_1 + \frac{1}{2}(1+t)X_2$$

VOR
IDRF
IDRF

2. Generate a pair of random points using the IDRf models.

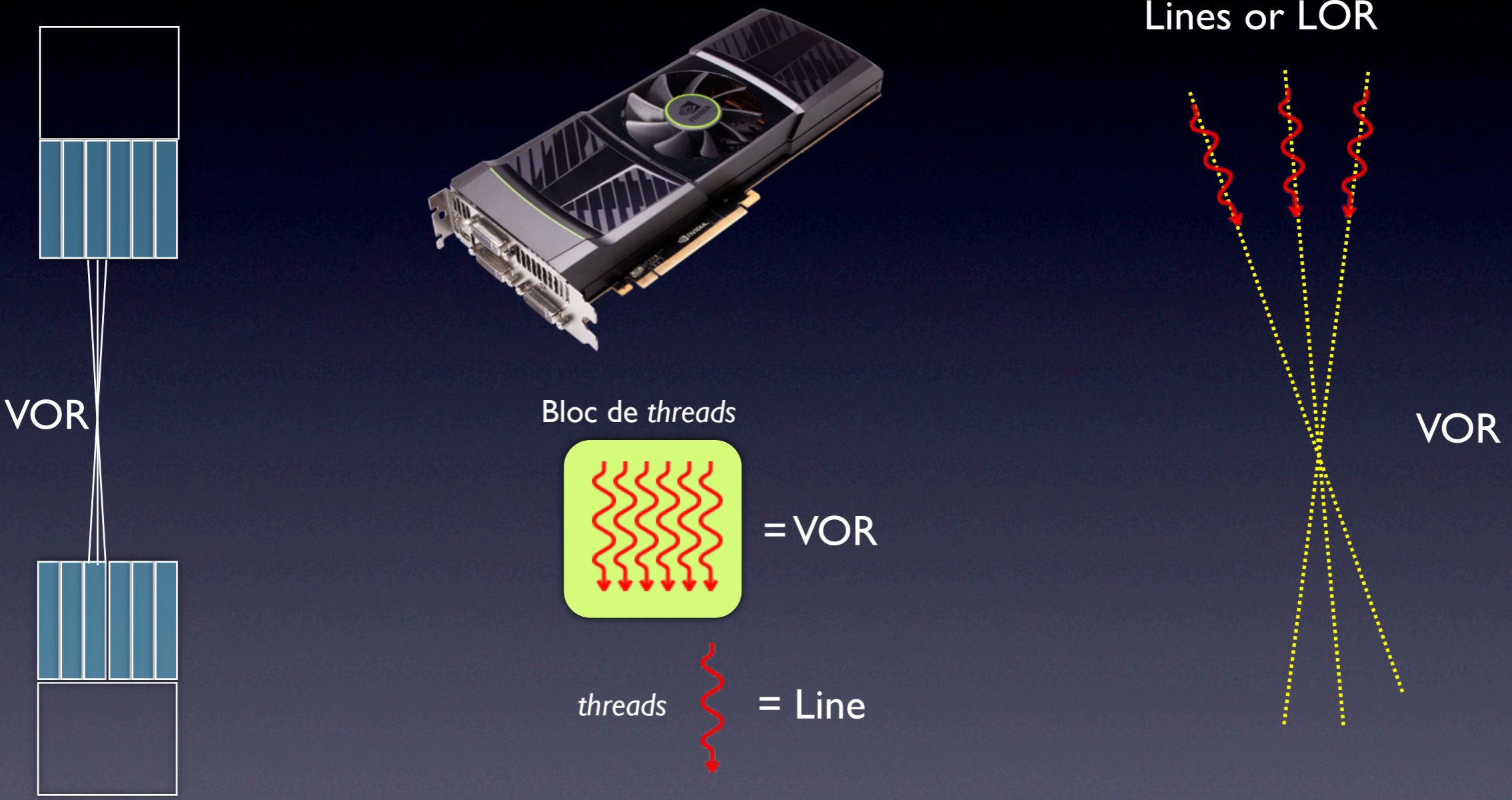
3. Render and accumulate the line connecting the generated pair points with the DDA algorithm [Bert2011].

Accumulation

VOR contributions

Considering the detector itself

IRIS is easy to use on GPU [Autret2012]

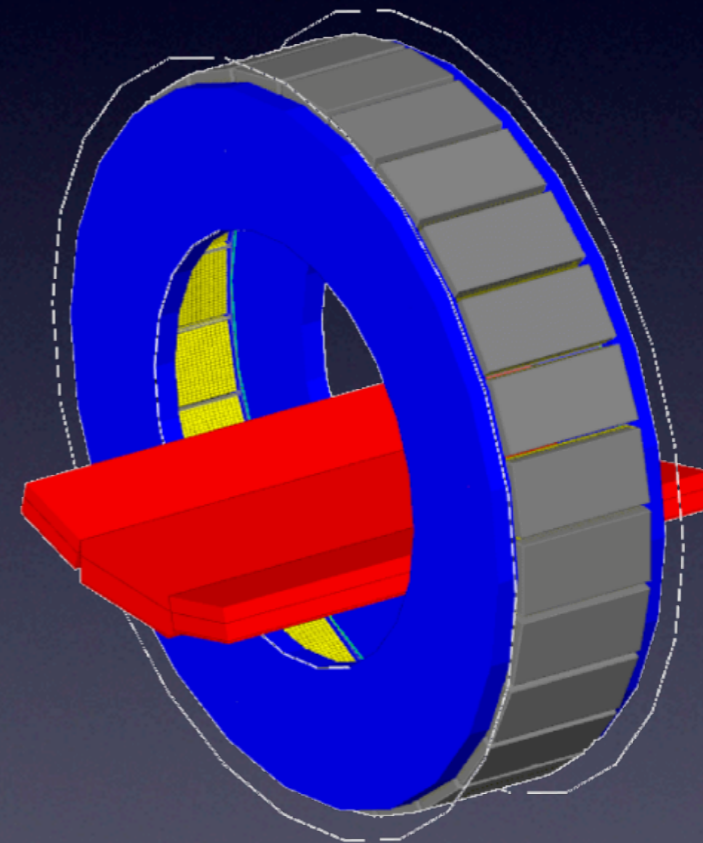


Evaluation study



Philips PET GEMINI scanner

- Monte Carlo Simulation [Lamare2006] performed with GATE [Jan2011]
- TOF resolution of 500 ps FWHM
- DOI resolution of 1 mm FWHM

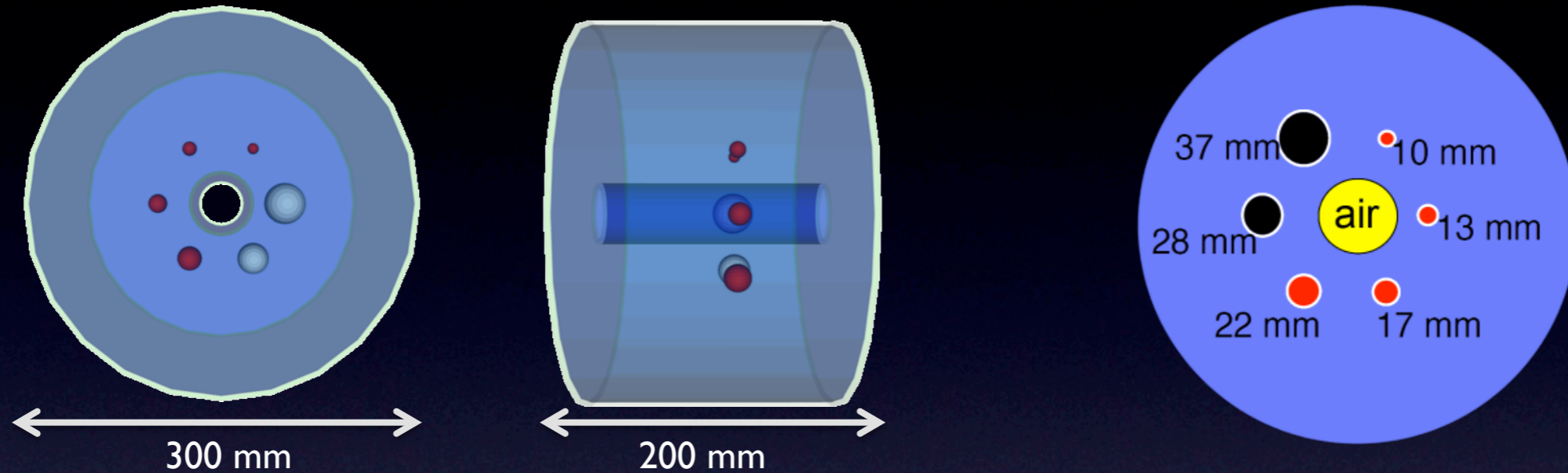


GATE modeling

Evaluation study

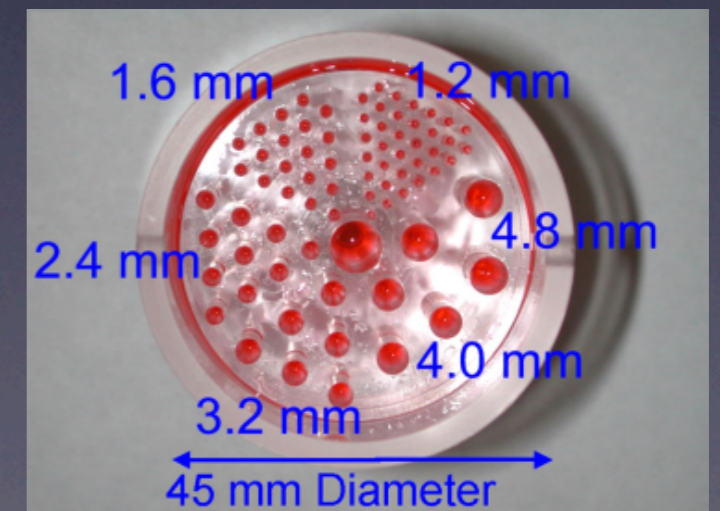
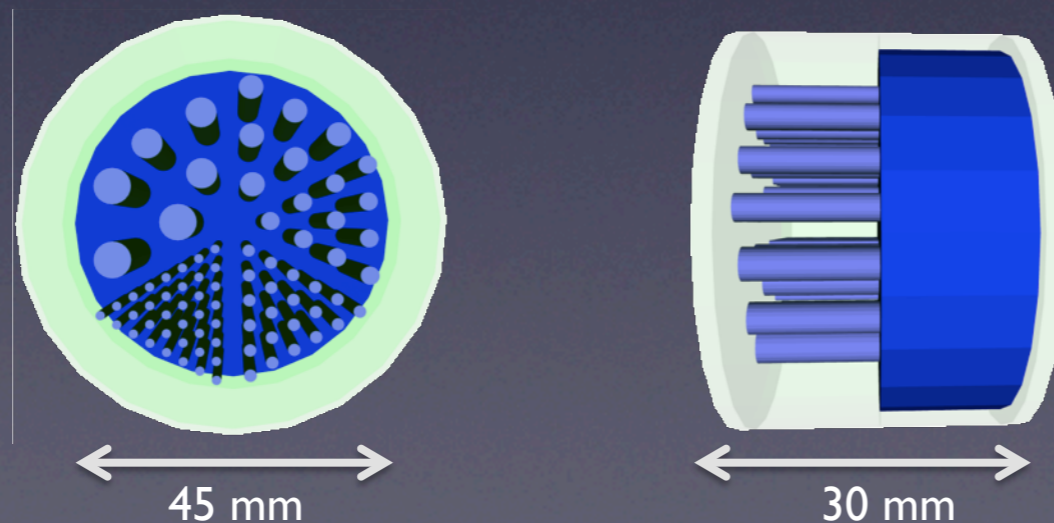
NEMA IEC NU2-2001 phantom

- 12×10^6 true coincidences



Miniature Derenzo phantom

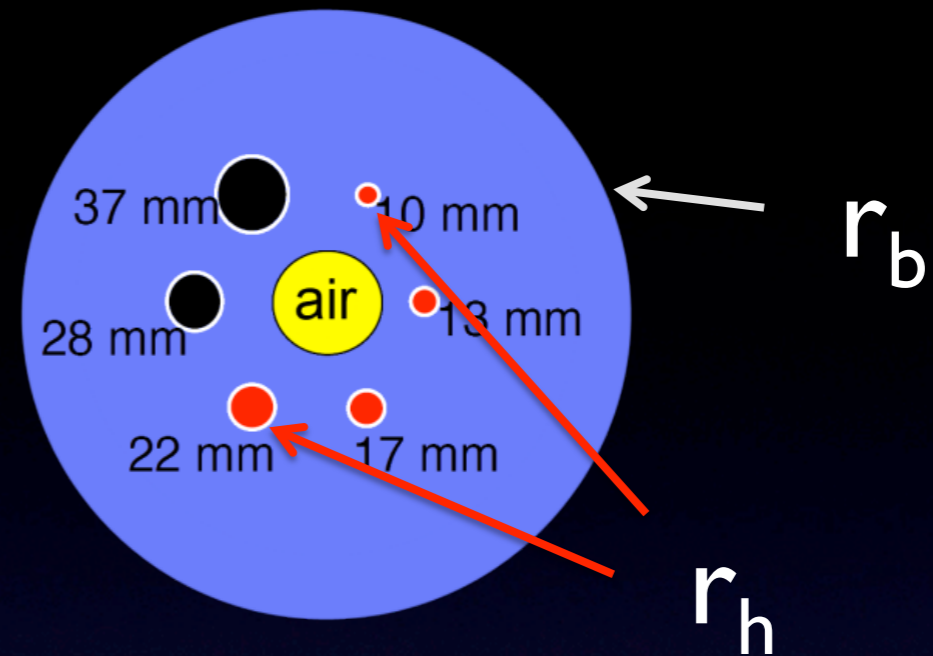
- One centered inside the FOV
- One 200 mm shifted from the center
- 4×10^6 true coincidences



Evaluation study

Contrast Recovery Coefficient (CRC)

$$CRC = \frac{\overline{r_h} - \overline{r_b}}{\overline{r_b}}$$



Signal-to-noise ratio (SNR) [Lodge2010] (background)



Reconstruction 1

Reconstruction 2

$$m_j = (v1_j + v2_j) / 2$$

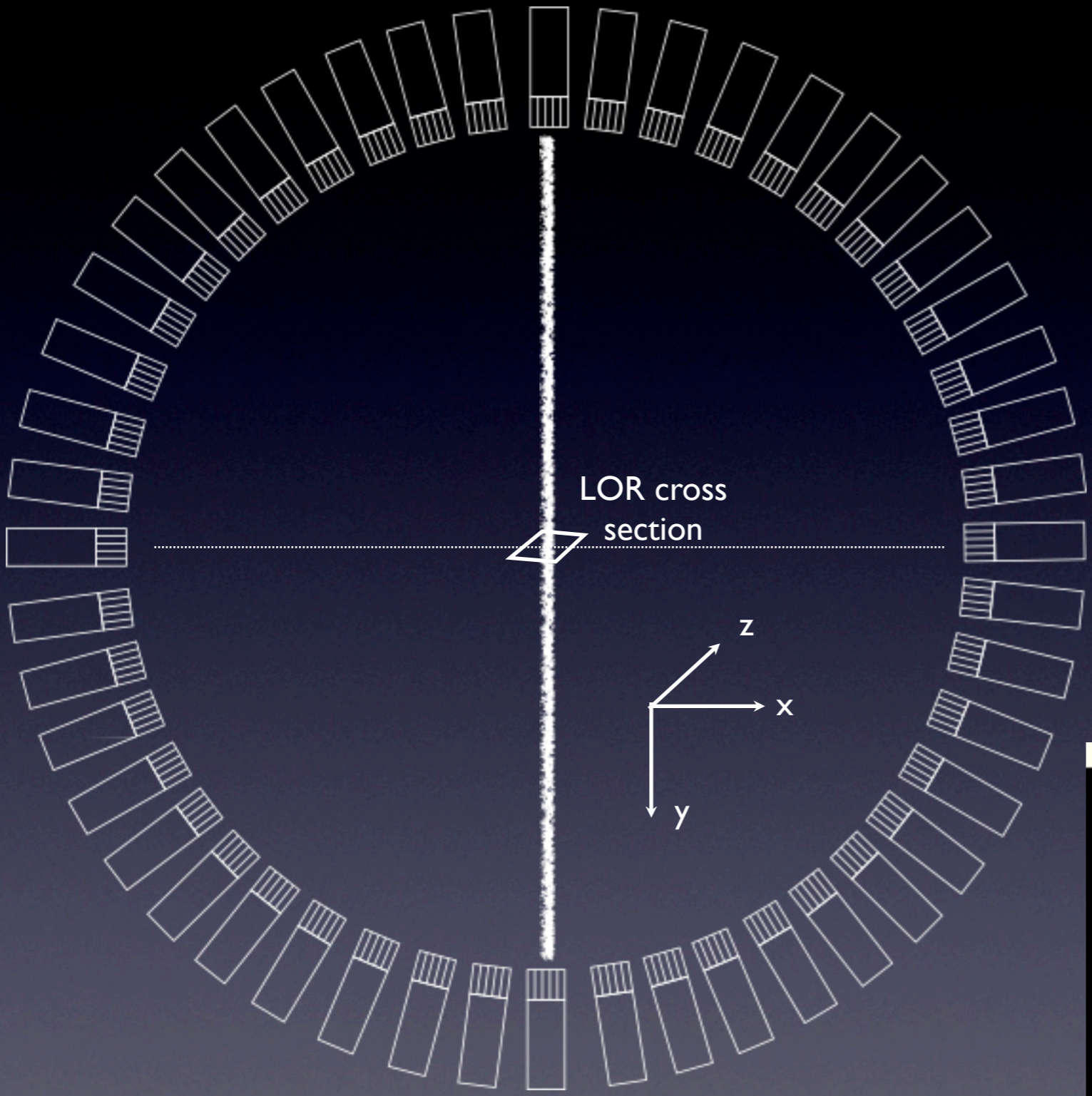
$$d_j = v1_j - v2_j$$

$$a_i = \text{mean}(m)$$

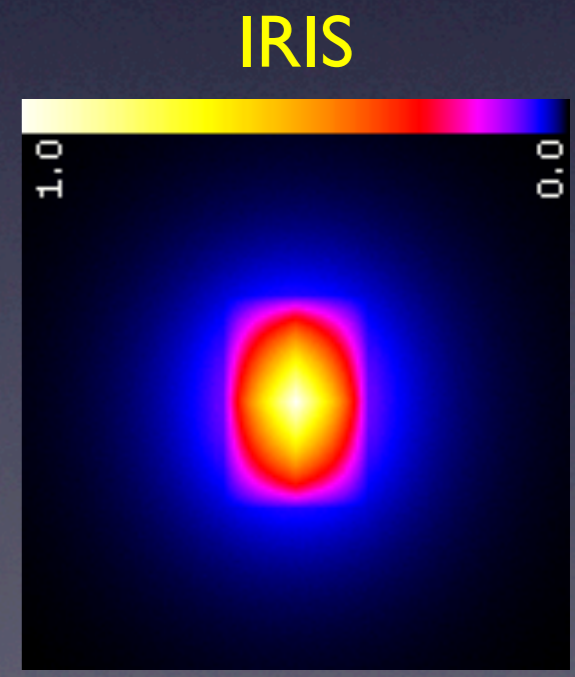
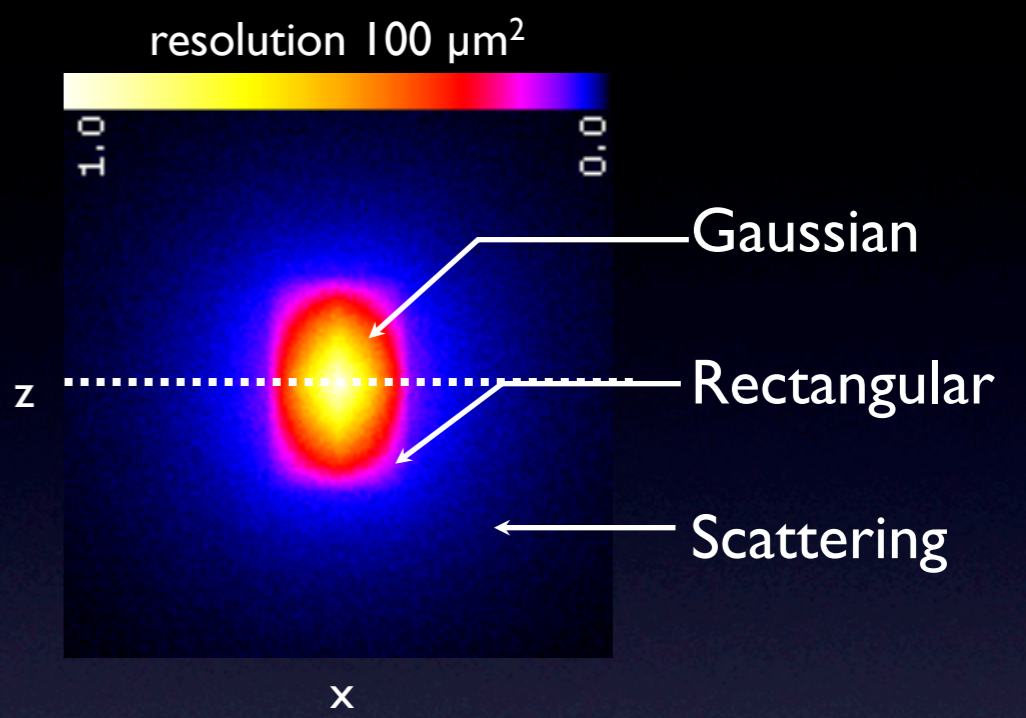
$$d_{sd}_i = \text{std}(d)$$

$$SNR = \frac{\sqrt{2}}{S} \sum_i^S \frac{a_i}{d_{sd}_i}$$

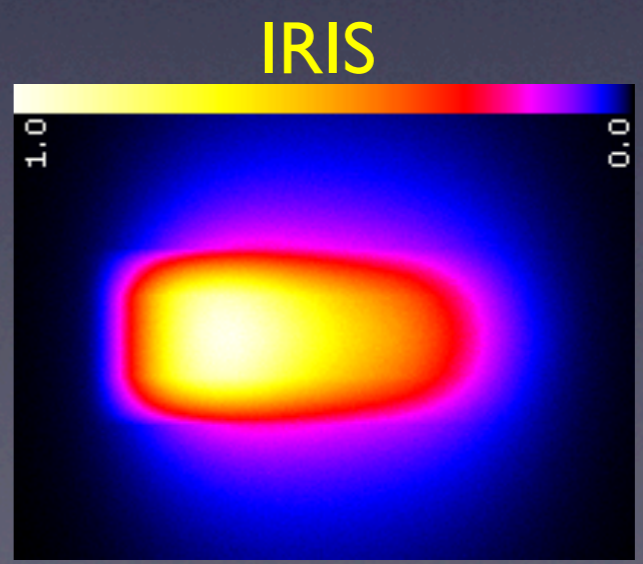
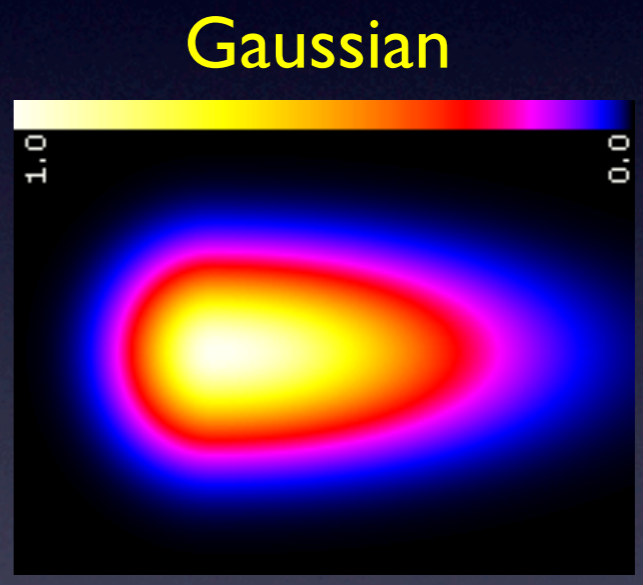
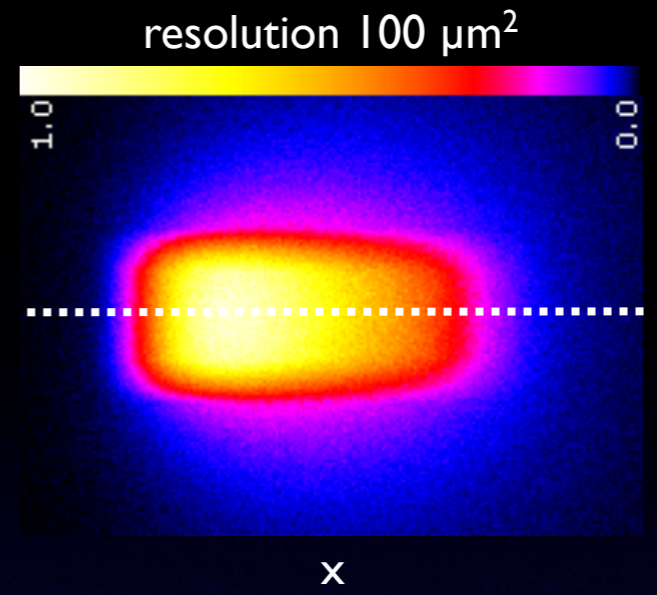
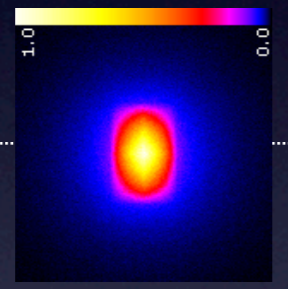
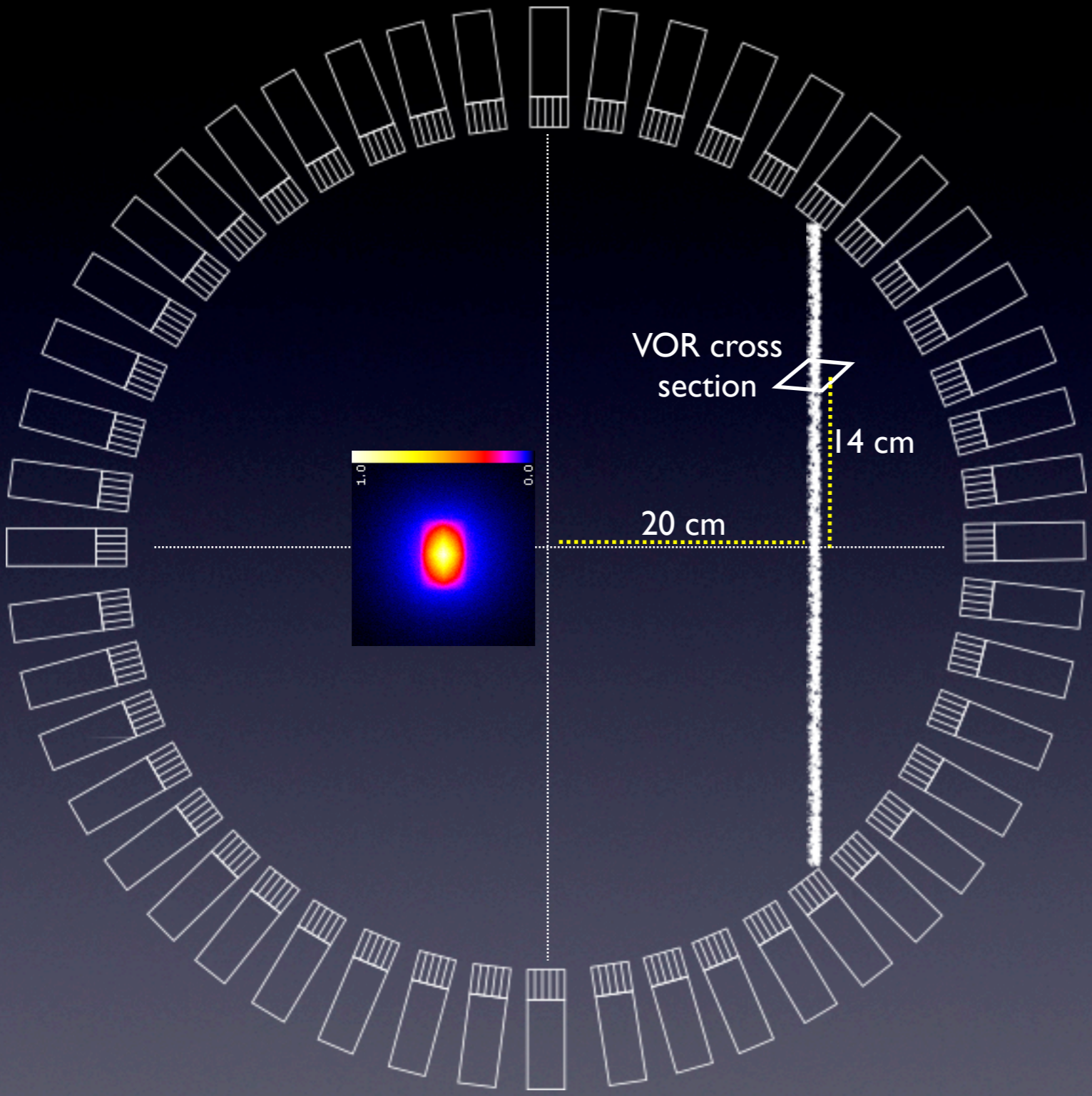
Results



PET Philips GEMINI

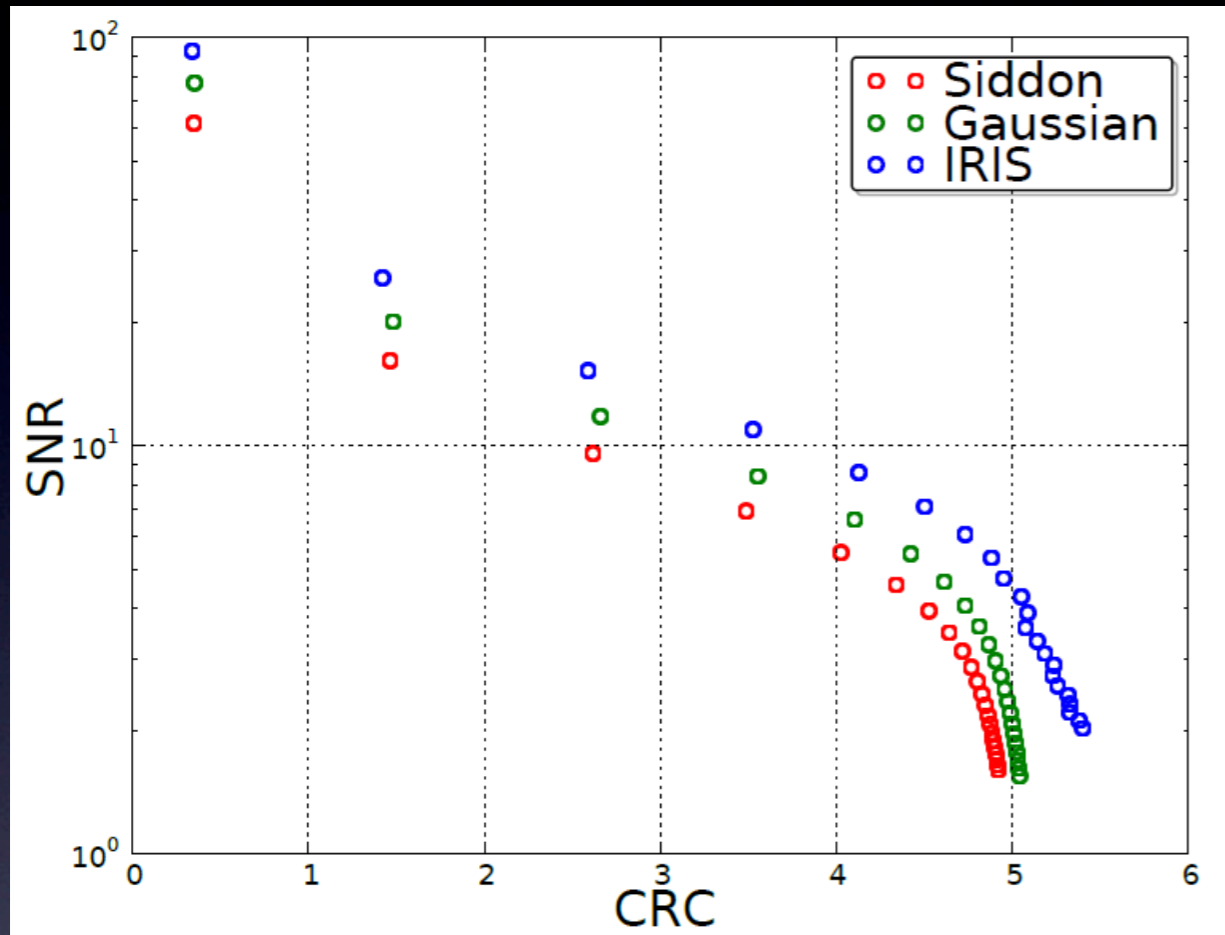


Results

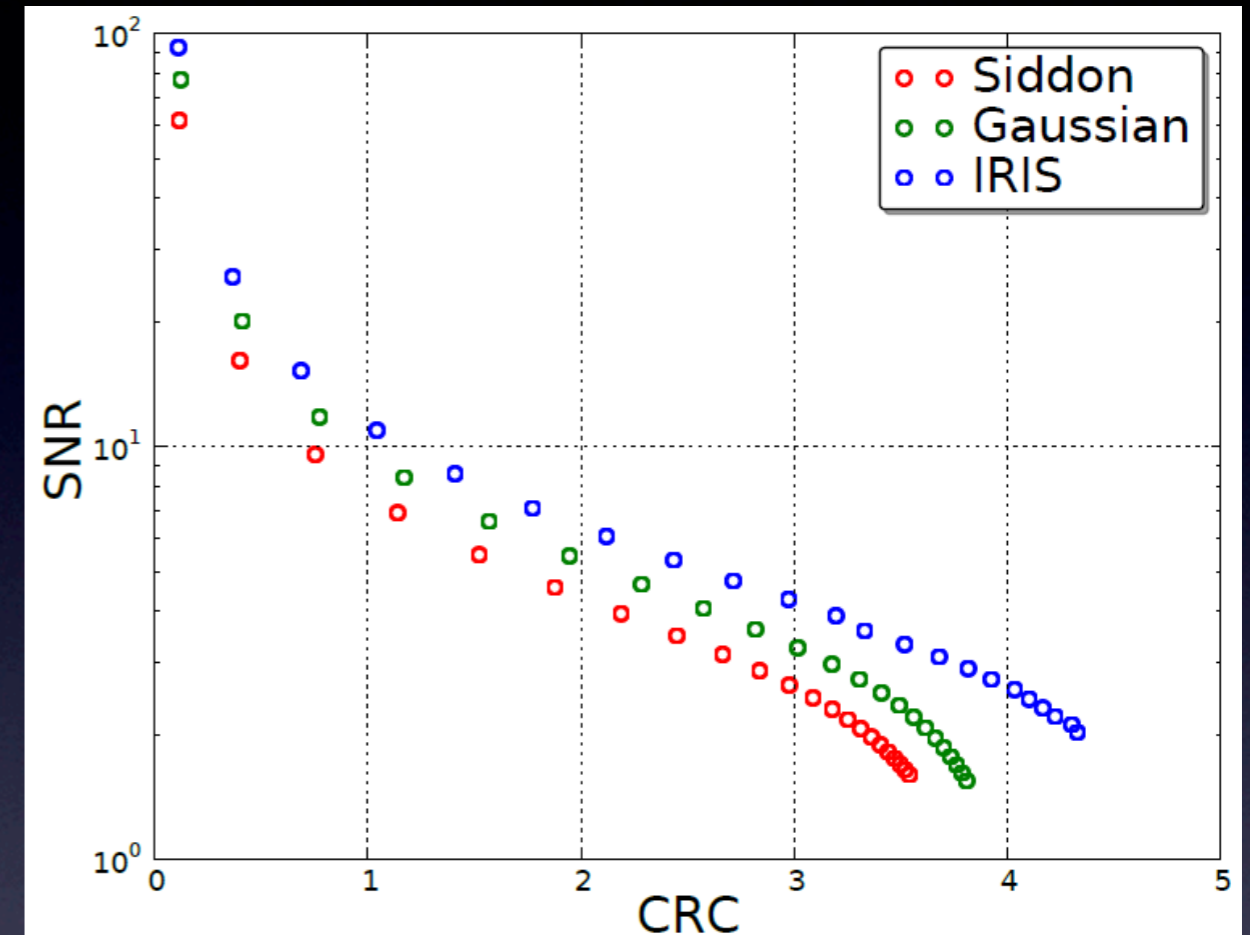


PET Philips GEMINI

CRC/SNR (LM-OSEM I subset 70 iterations) [Awen2013a]



CRC in the biggest hot sphere



CRC in the smallest hot sphere

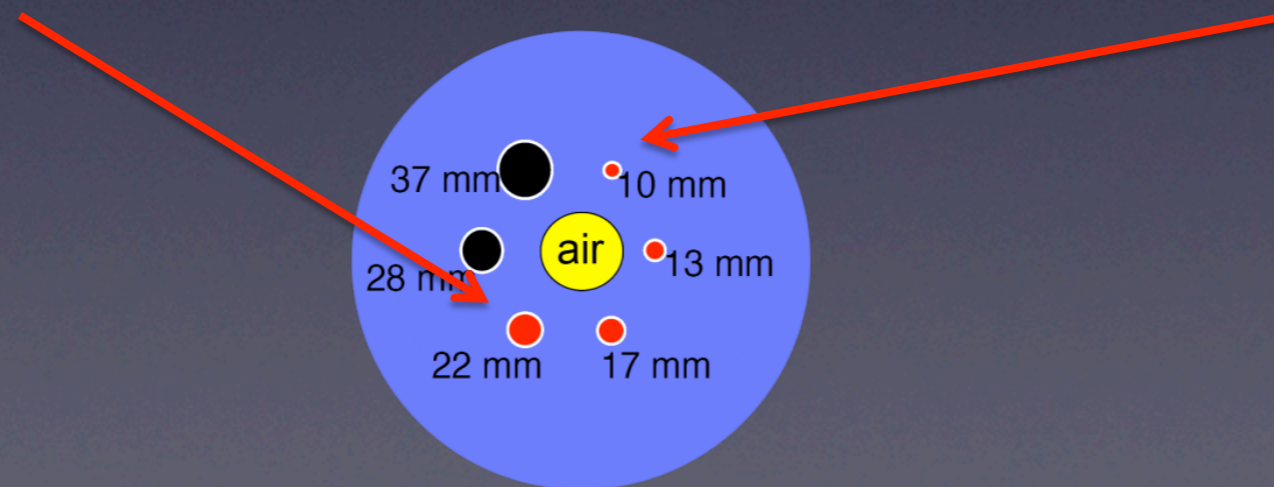
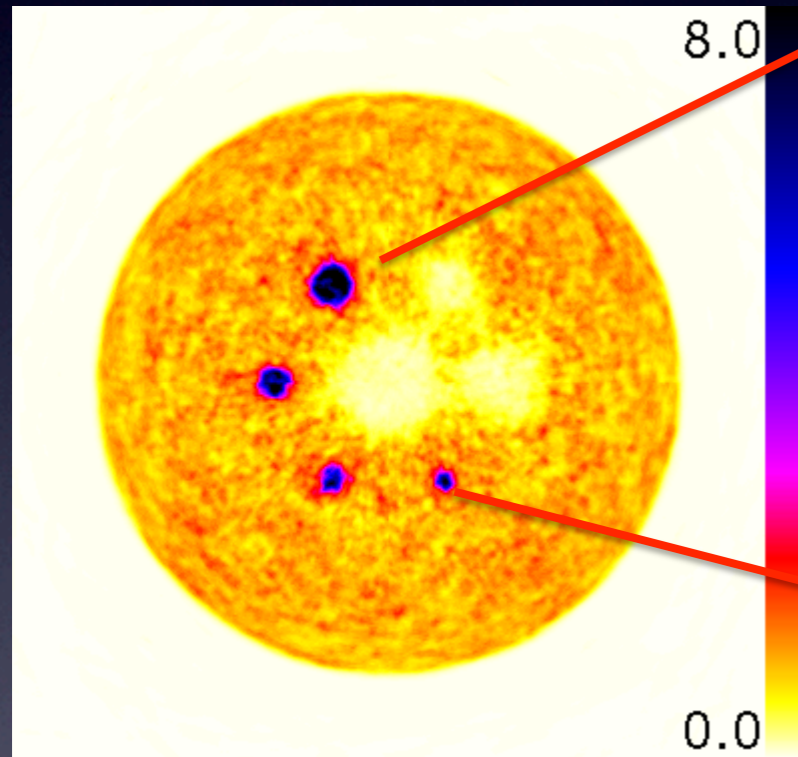
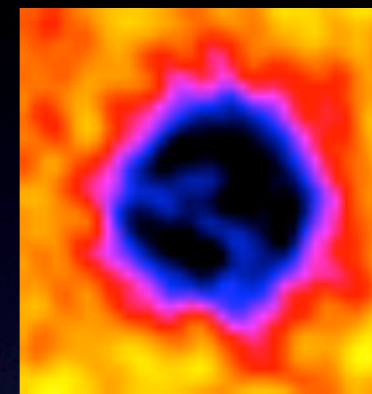


Image Quality

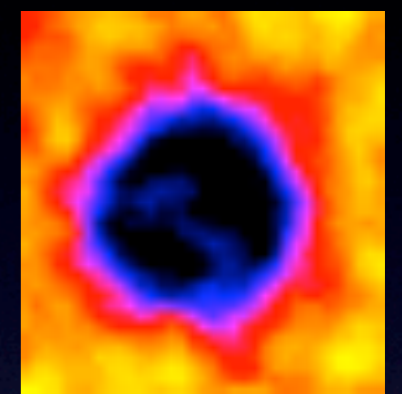
Reconstructed image for the same SNR (=4.5)



Siddon



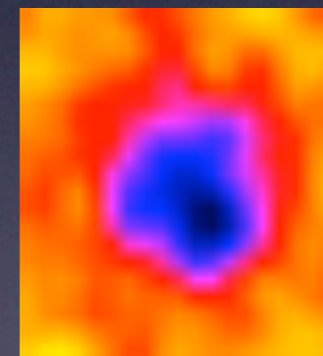
Gaussian



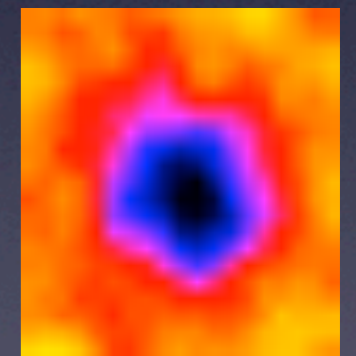
IRIS



Siddon



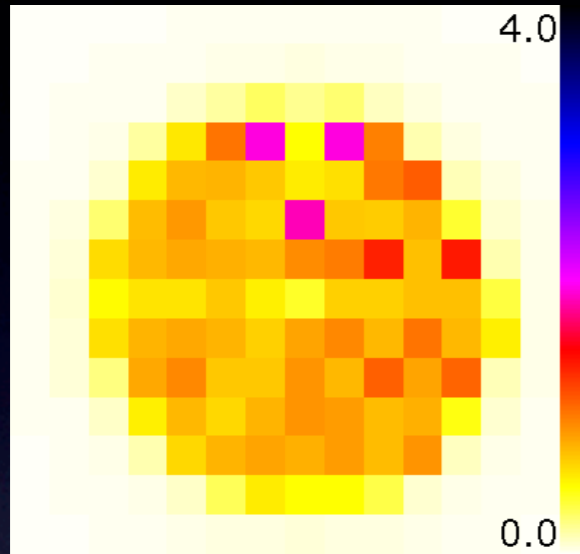
Gaussian



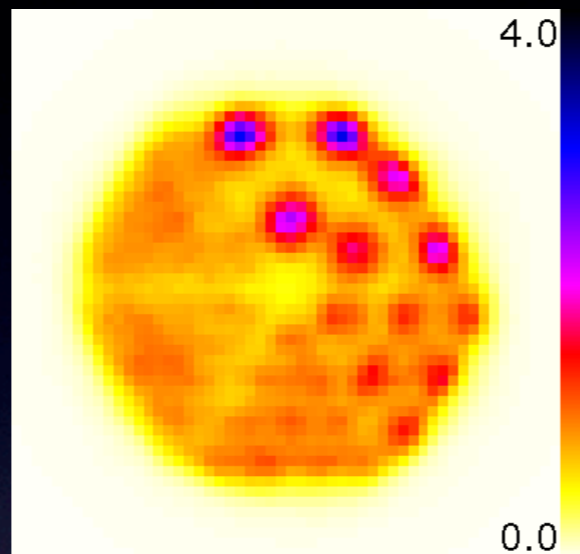
IRIS

Image Resolution

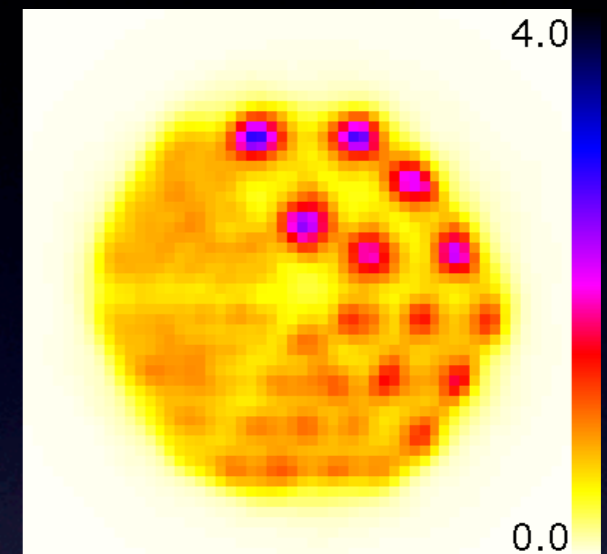
Centered miniature Derenzo (LM-OSEM 1 subset 15 iterations)



Siddon

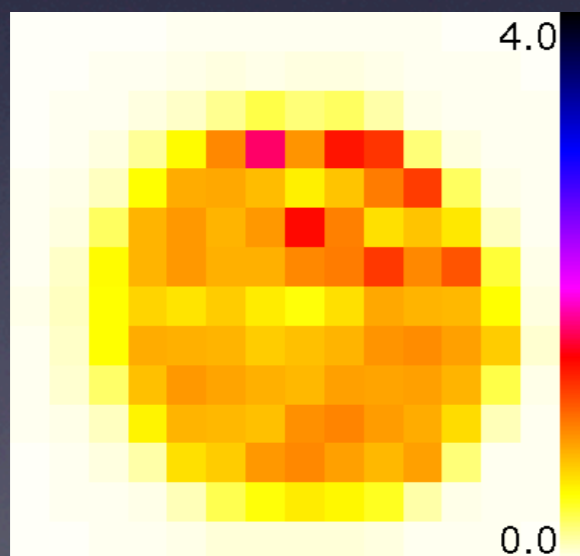


Gaussian

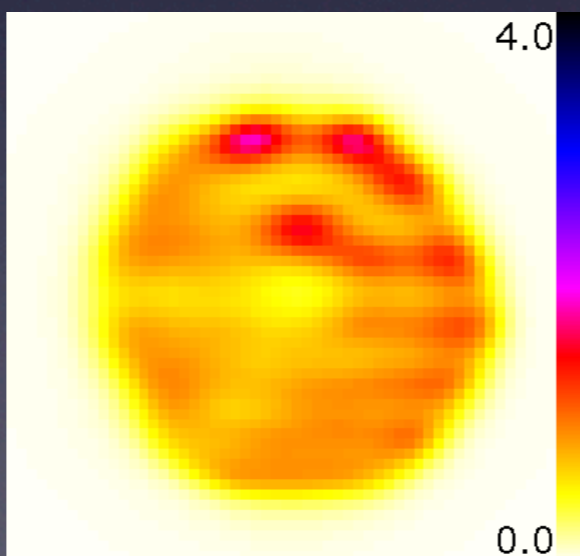


IRIS

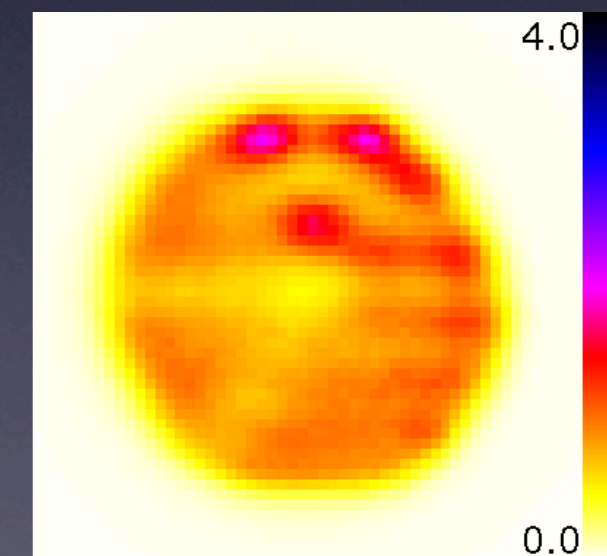
Shifted miniature Derenzo (LM-OSEM 1 subset 15 iterations)



Siddon



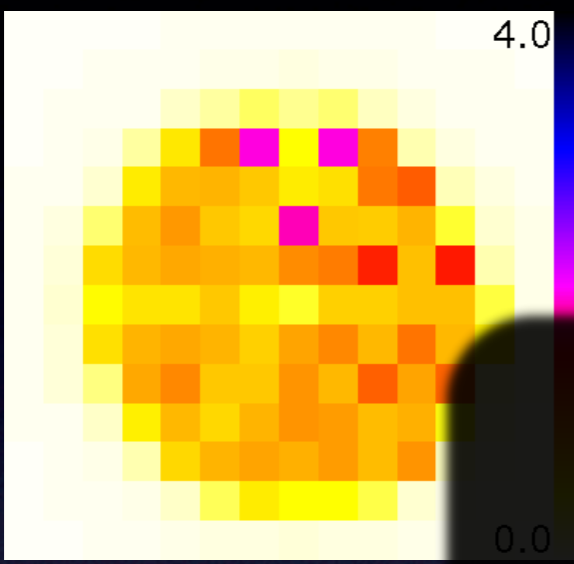
Gaussian



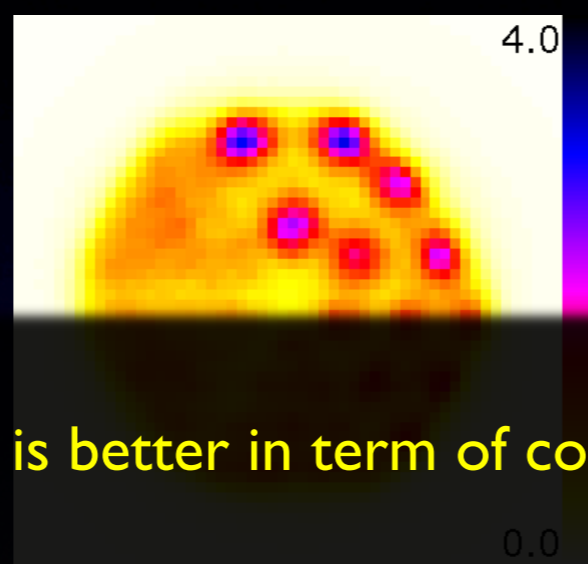
IRIS

Image Resolution

Centered miniature Derenzo (LM-OSEM 1 subset 15 iterations)

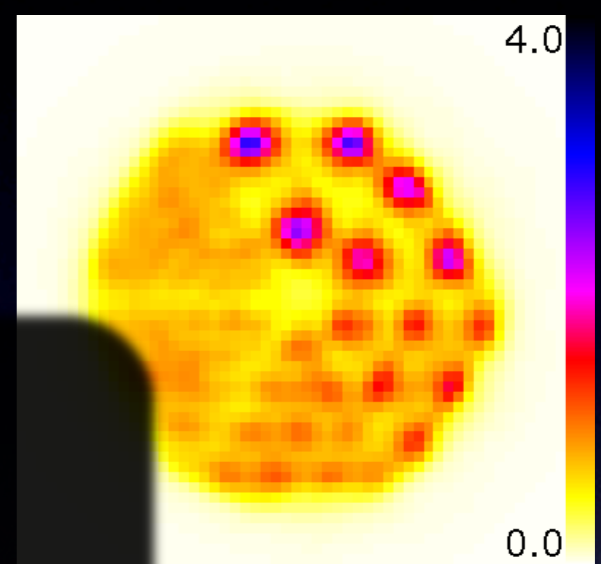


Siddon



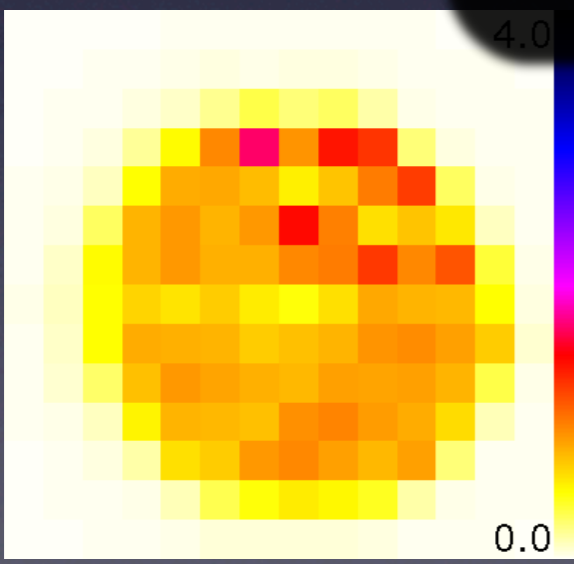
IRIS is better in term of contrast

How to improve that?

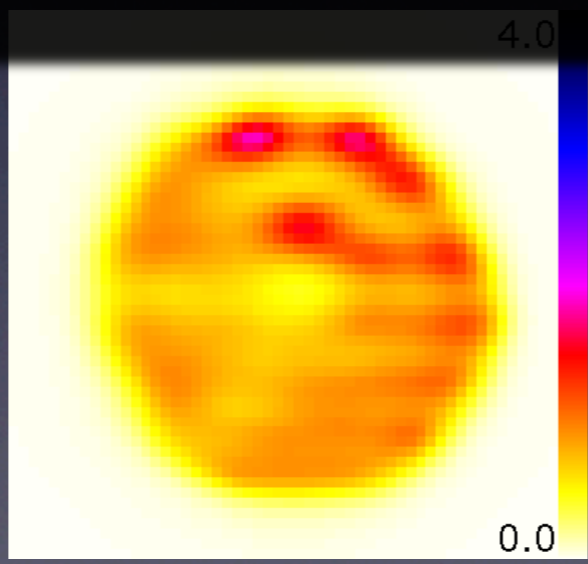


IRIS

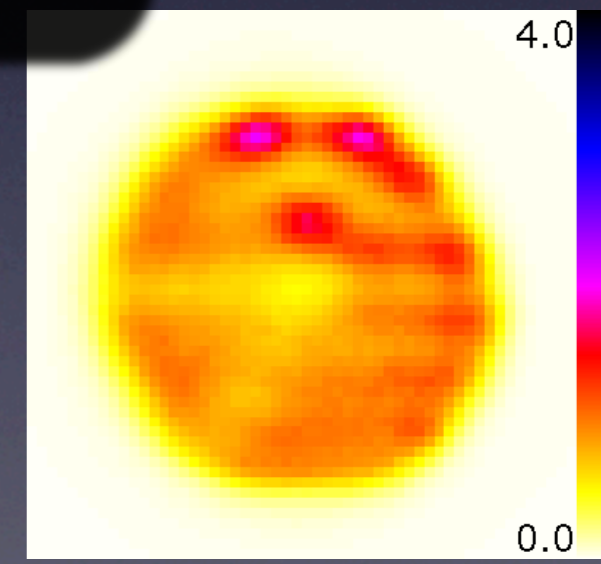
Shifted miniature Derenzo (LM-OSEM 1 subset 15 iterations)



Siddon



Gaussian

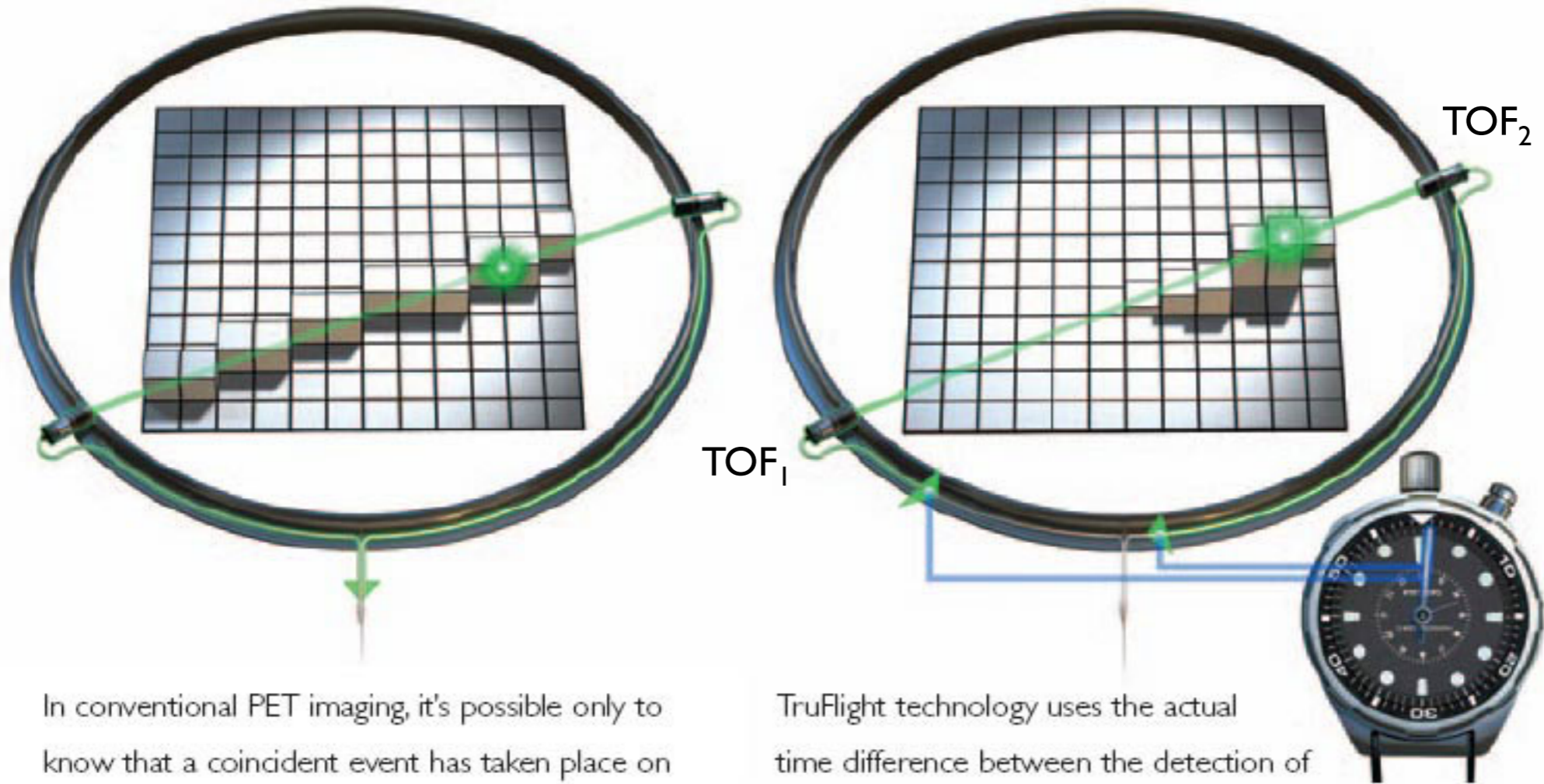


IRIS

Considering time-of-flight (TOF)



Philips TruFlight: The solution to better PET imaging



In conventional PET imaging, it's possible only to know that a coincident event has taken place on the line of response, but not the actual location of the event.

www.healthcare.philips.com

TruFlight technology uses the actual time difference between the detection of coincident events to more accurately identify the origin of the annihilation. Better identification leads to a quantifiable improvement in image quality.

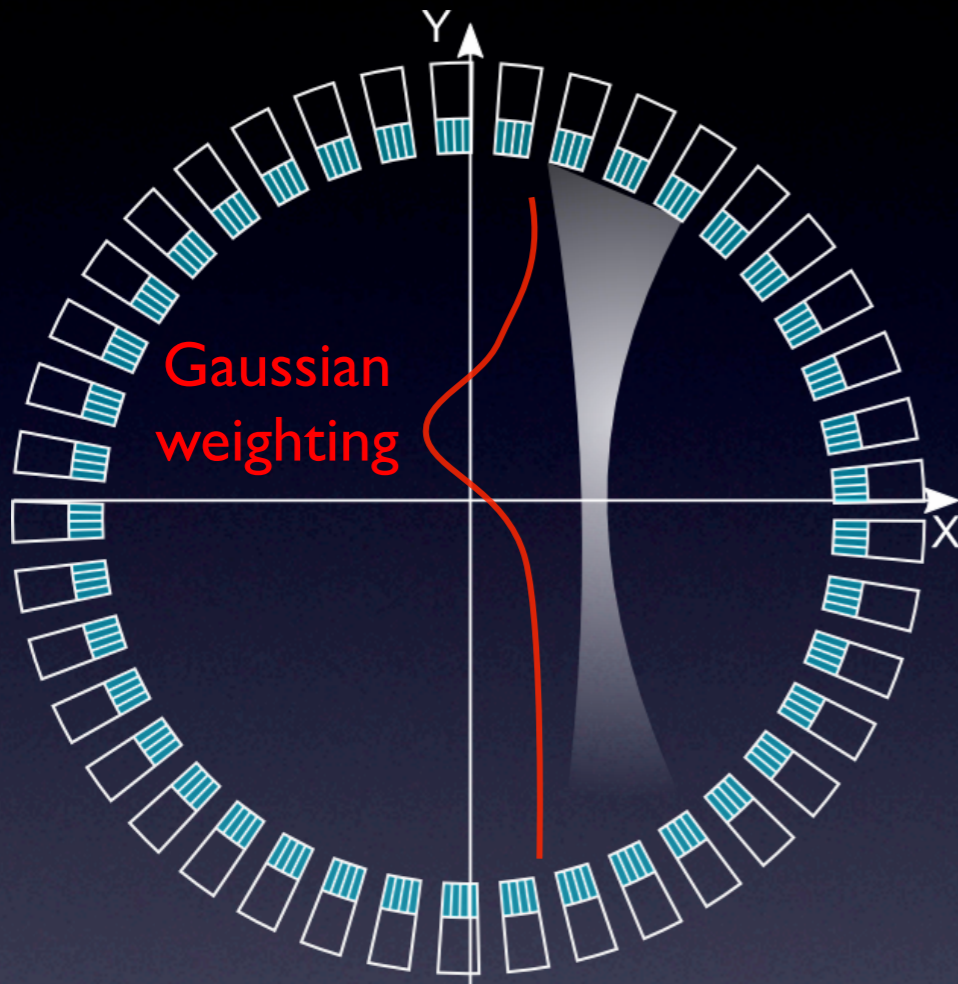
Along the LOR

Along a small part of the LOR

Typical TOF resolution is 500 ps FWHM (7.5 cm)

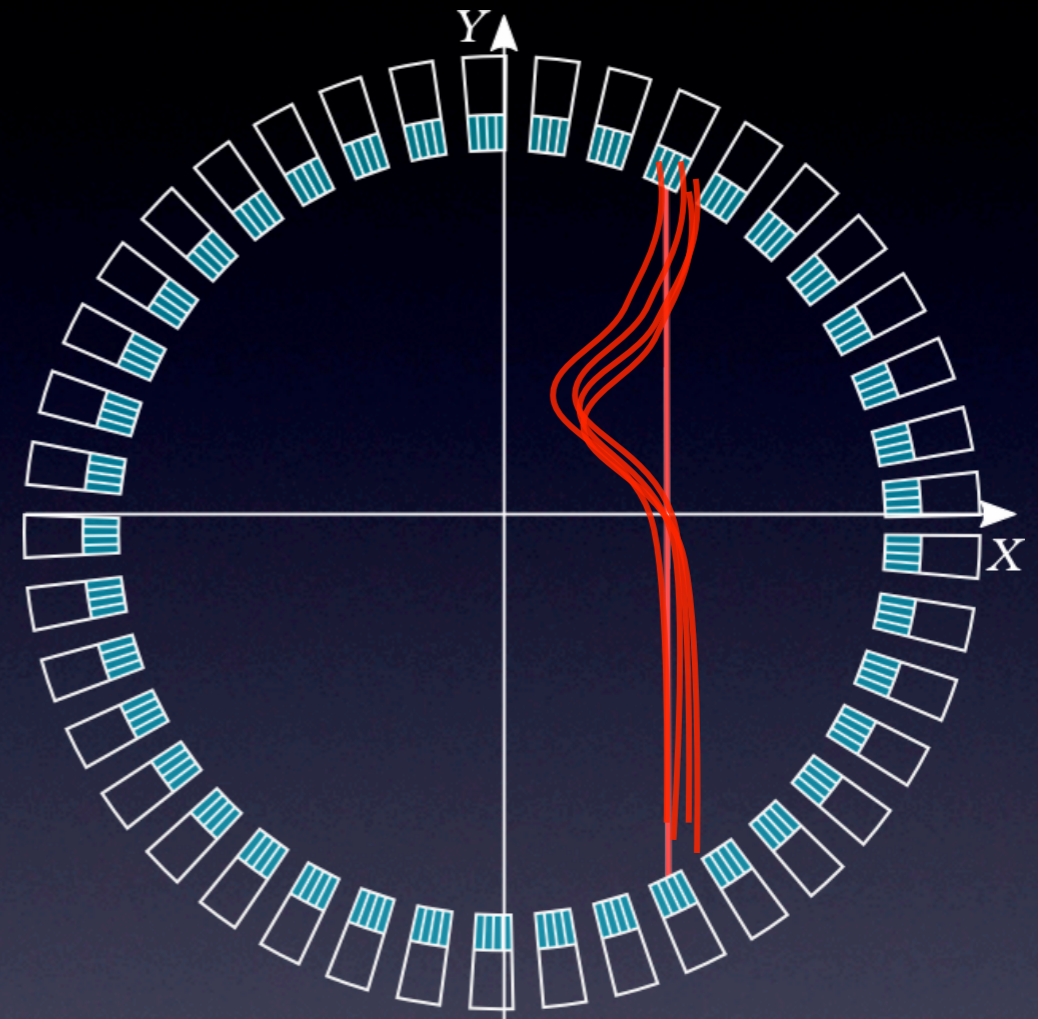
Considering time-of-flight (TOF)

Gaussian projector



Applied on the VOR

IRIS projector

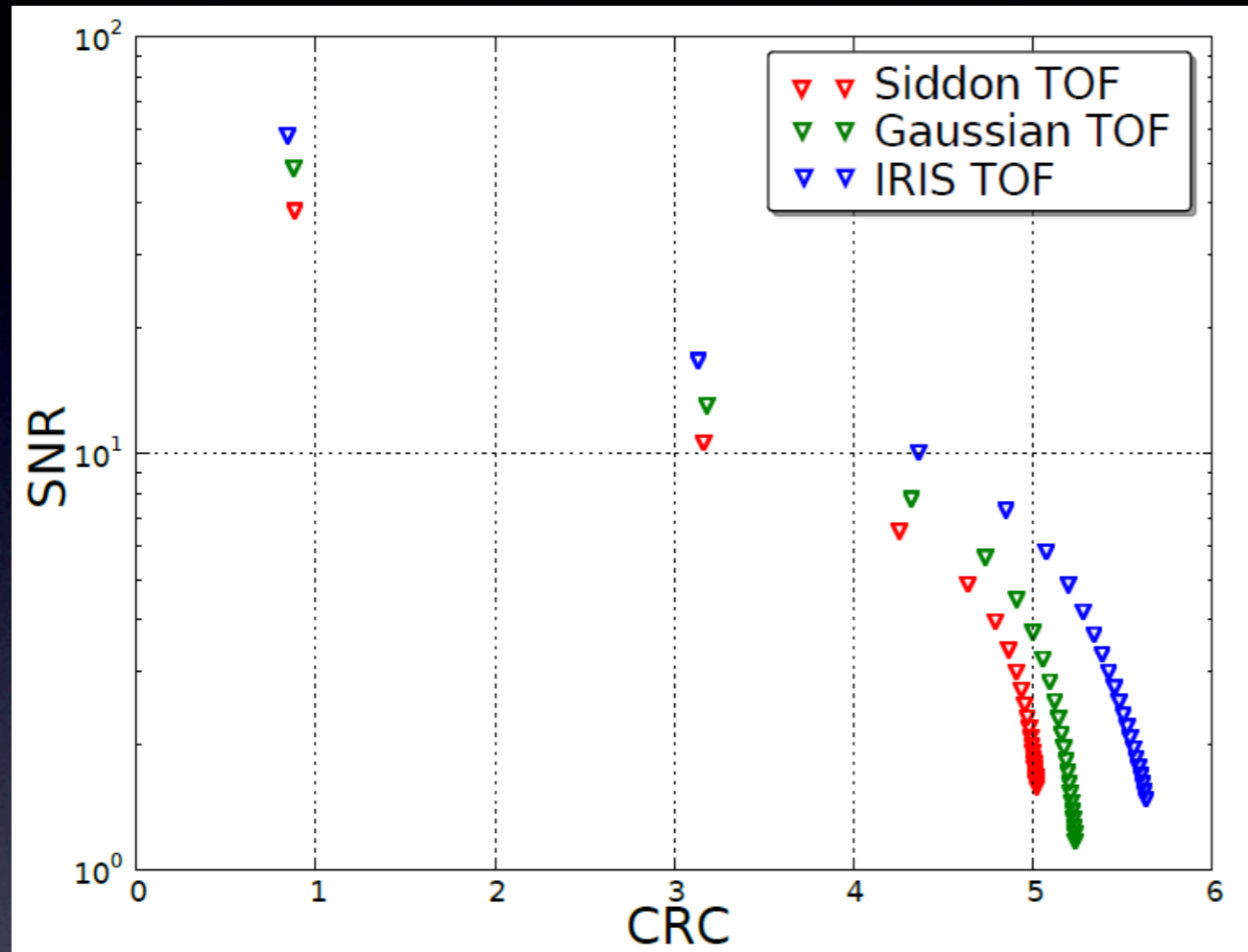


Applied on every random lines

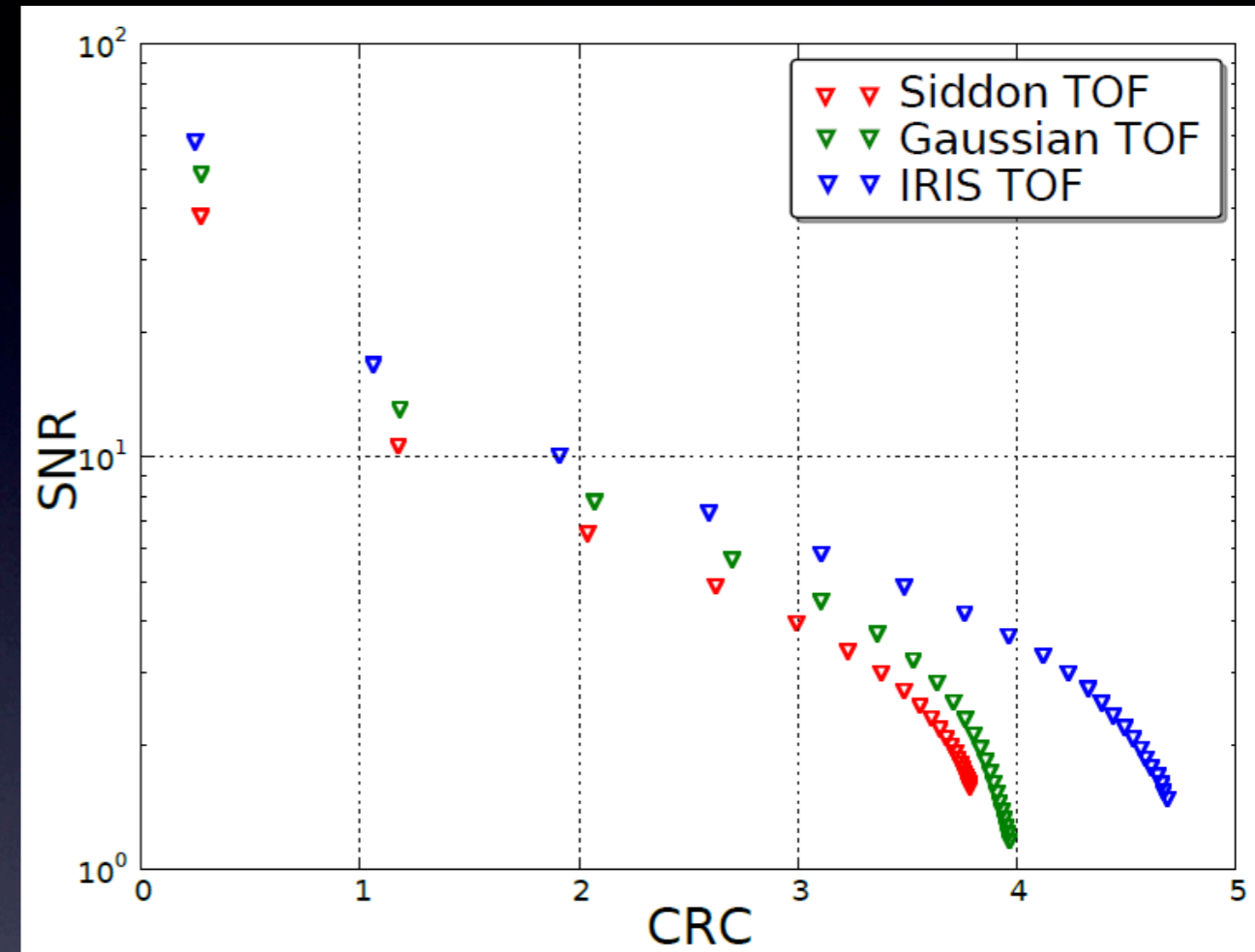
FWHM given by the TOF resolution

TOF weighting can be used on every projector

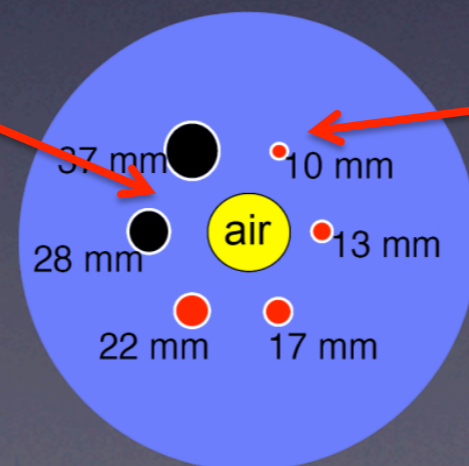
CRC/SNR (LM-OSEM I subset 70 iterations) [Awen2013b]



CRC in the biggest hot sphere



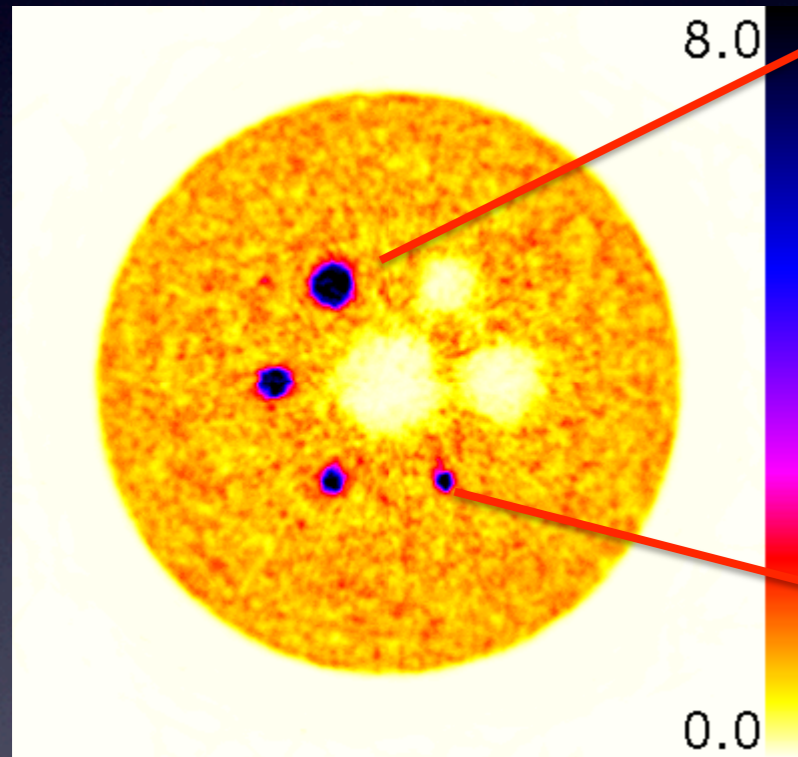
CRC in the smallest hot sphere



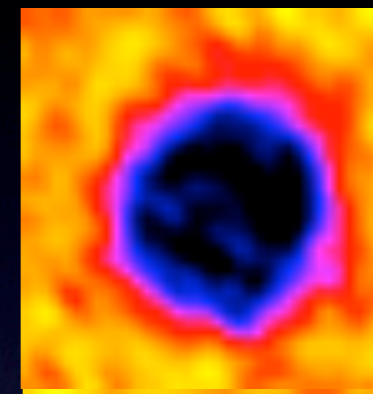
Improve convergence,
SNR and contrast

Image Quality

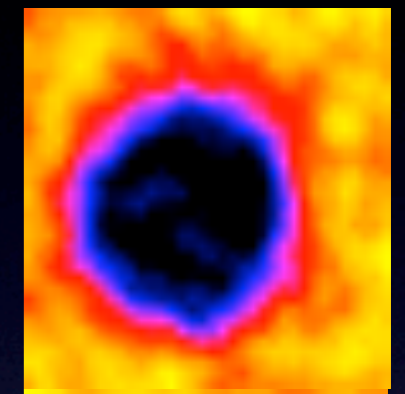
Reconstructed image for the same SNR (=4.5)



Siddon



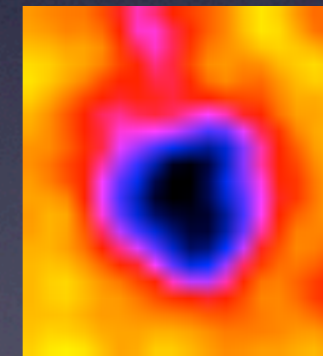
Gaussian



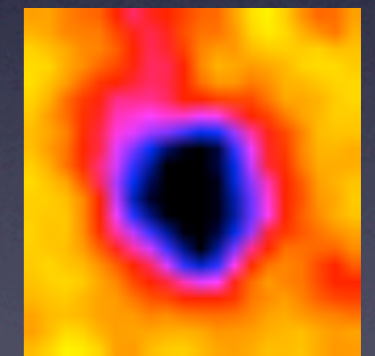
IRIS



Siddon



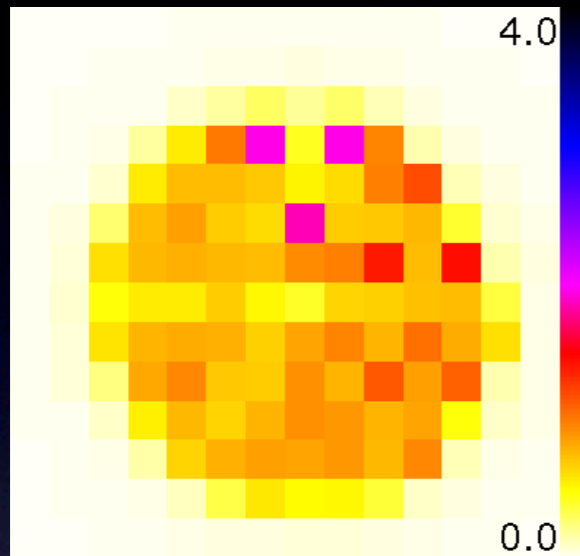
Gaussian



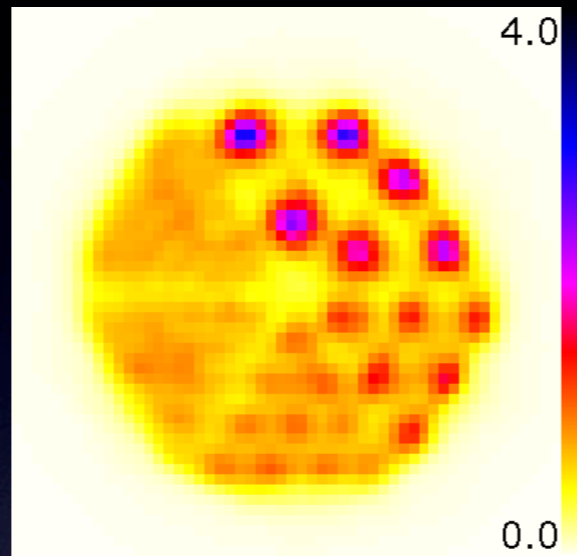
IRIS

Image Resolution

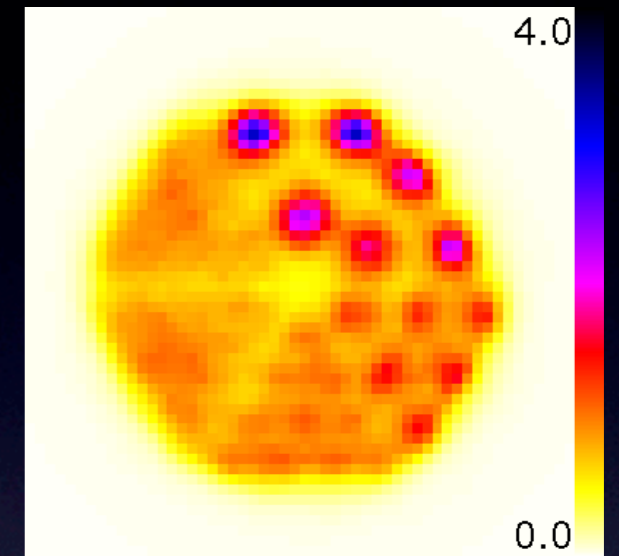
Centered miniature Derenzo (LM-OSEM 1 subset 15 iterations)



Siddon

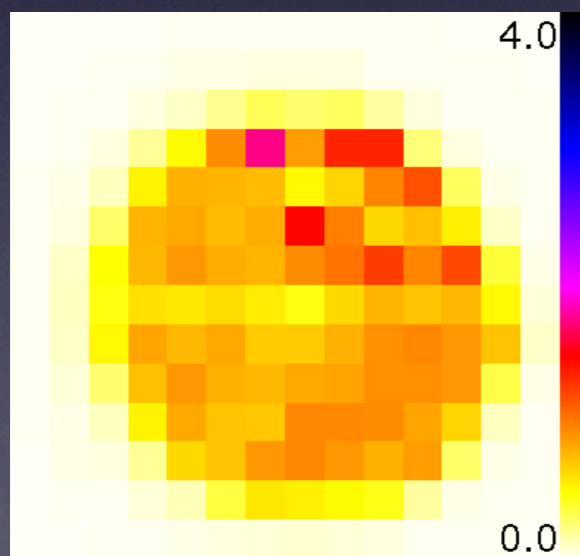


Gaussian



IRIS

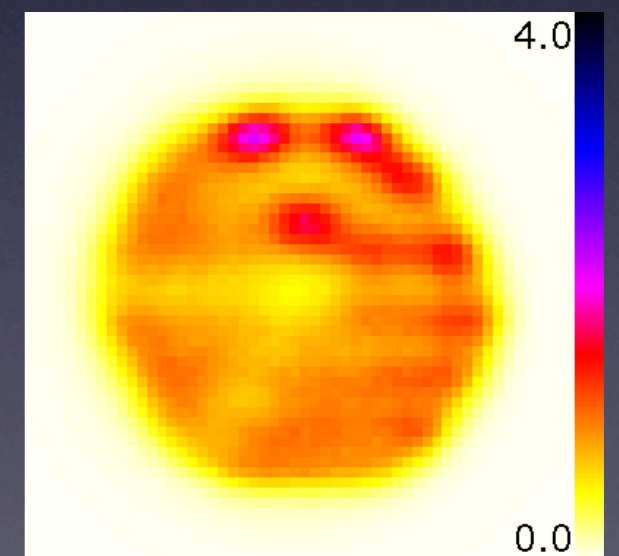
Shifted miniature Derenzo (LM-OSEM 1 subset 15 iterations)



Siddon



Gaussian



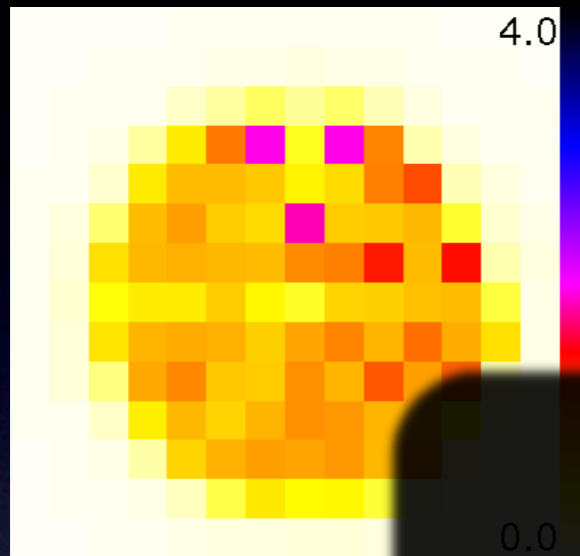
IRIS

Results TOF

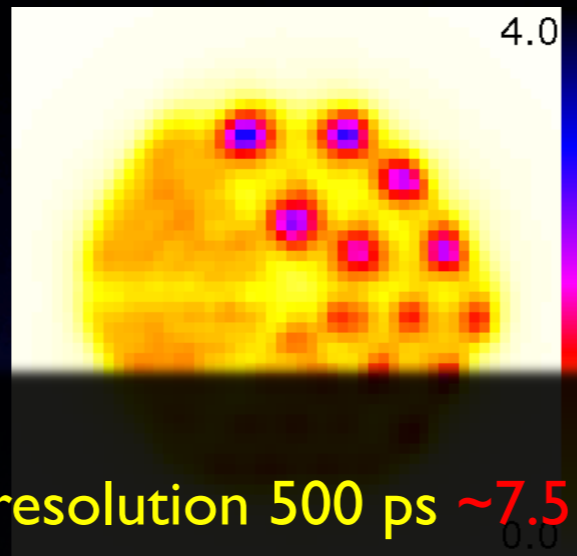


Image Resolution

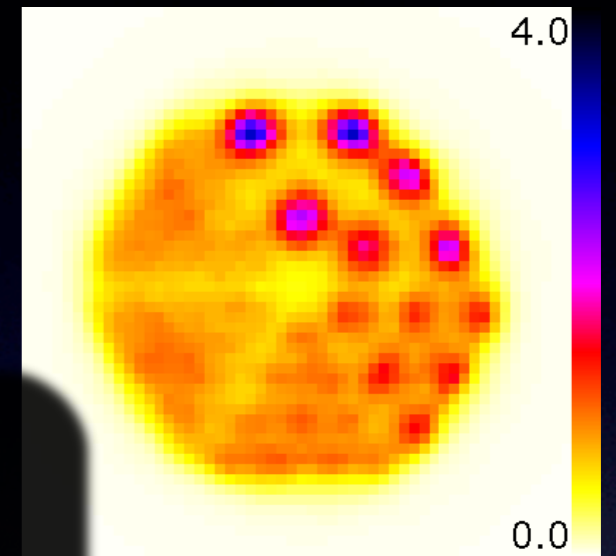
Centered miniature Derenzo (LM-OSEM 1 subset 15 iterations)



Siddon



Gaussian



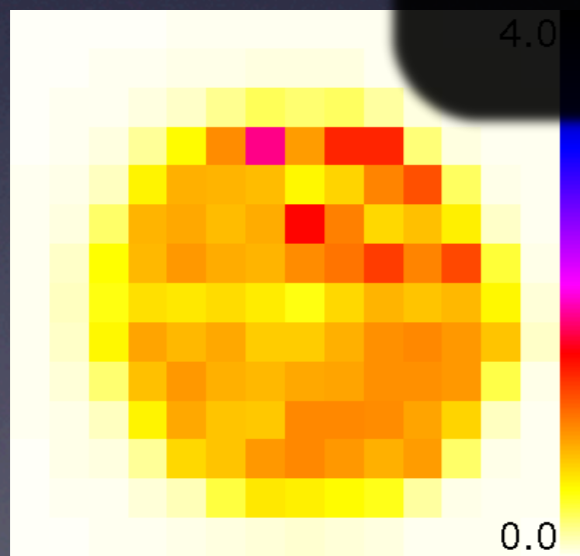
IRIS

TOF resolution 500 ps ~7.5 cm

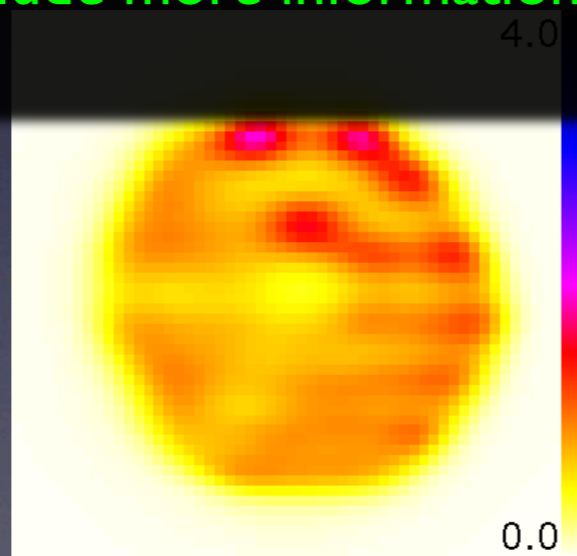
Diameter of the miniature Derenzo phantom: 5 cm

Shifted miniature Derenzo (LM-OSEM 1 subset 15 iterations)

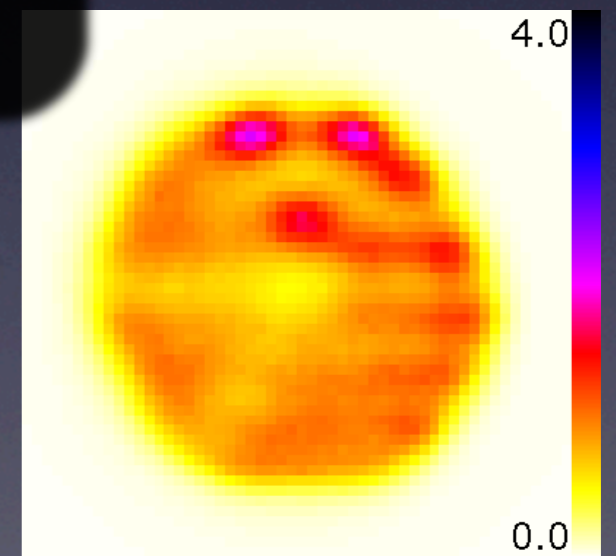
Include more information!



Siddon



Gaussian

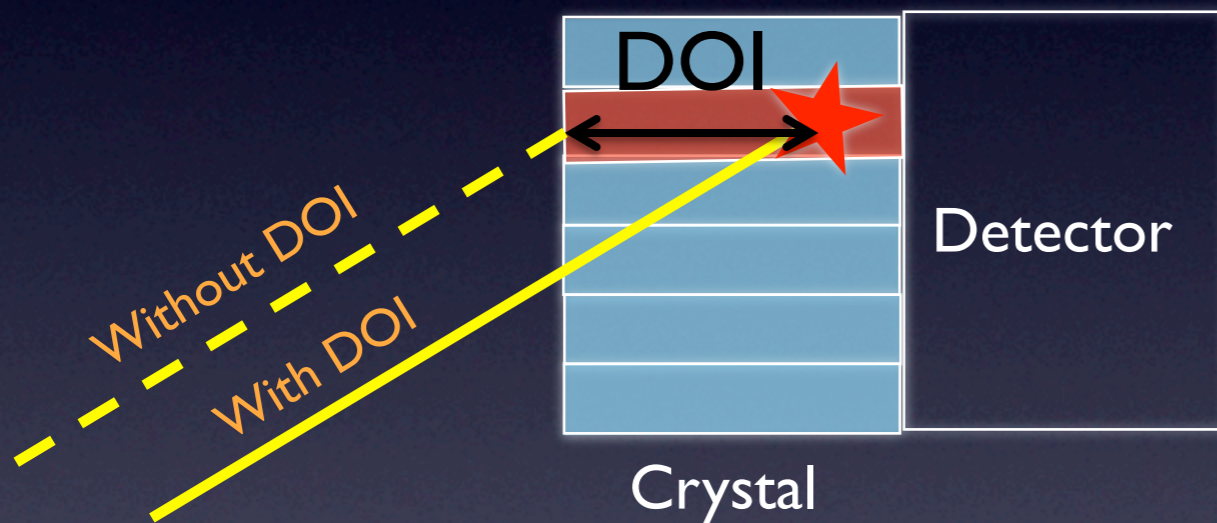


IRIS

Considering Depth-of-Interaction (DOI)



Only available on prototype detector

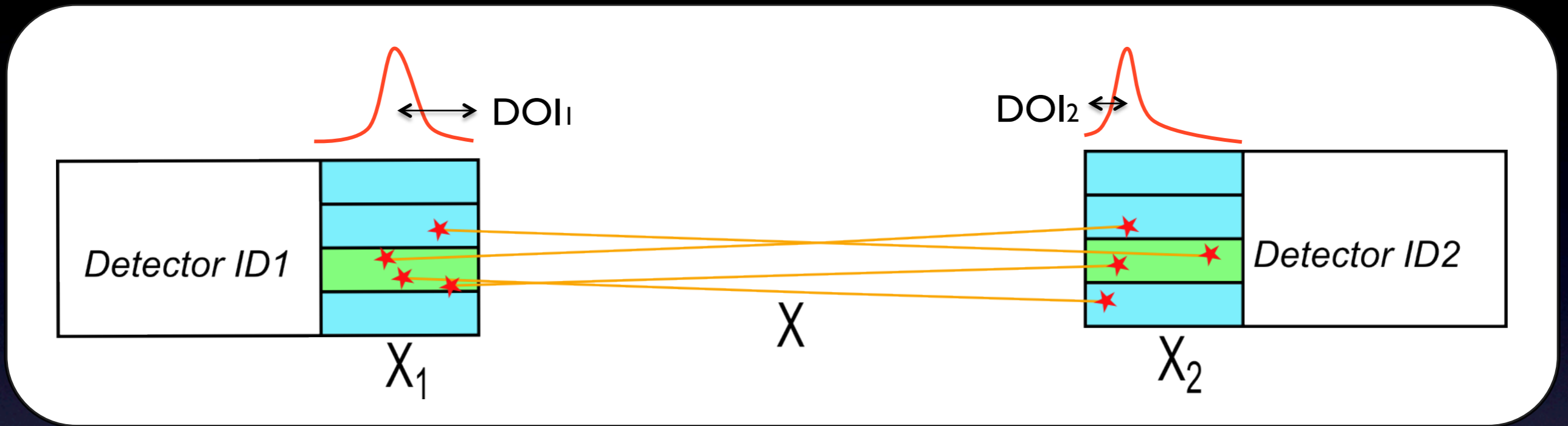


Crystal depth where the photon was detected

Improve LOR location for a given resolution (FWHM 1 mm)

Considering Depth-of-Interaction (DOI)

IRIS projector



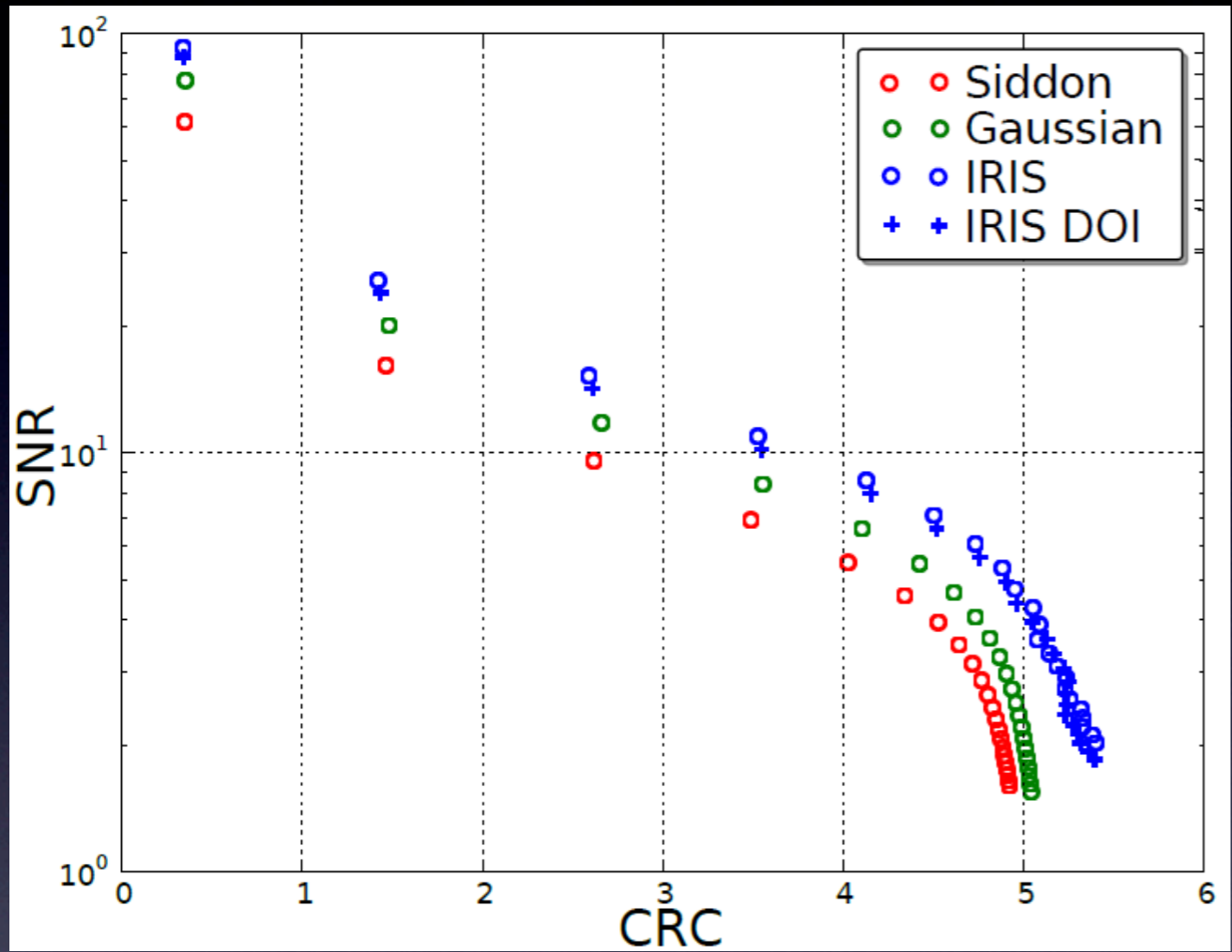
Modulate the IDRF with the a Gaussian function given by the FWHM of the DOI resolution

Easy to use with ray or multi-ray projectors (Siddon, Chen, IRIS, etc.)

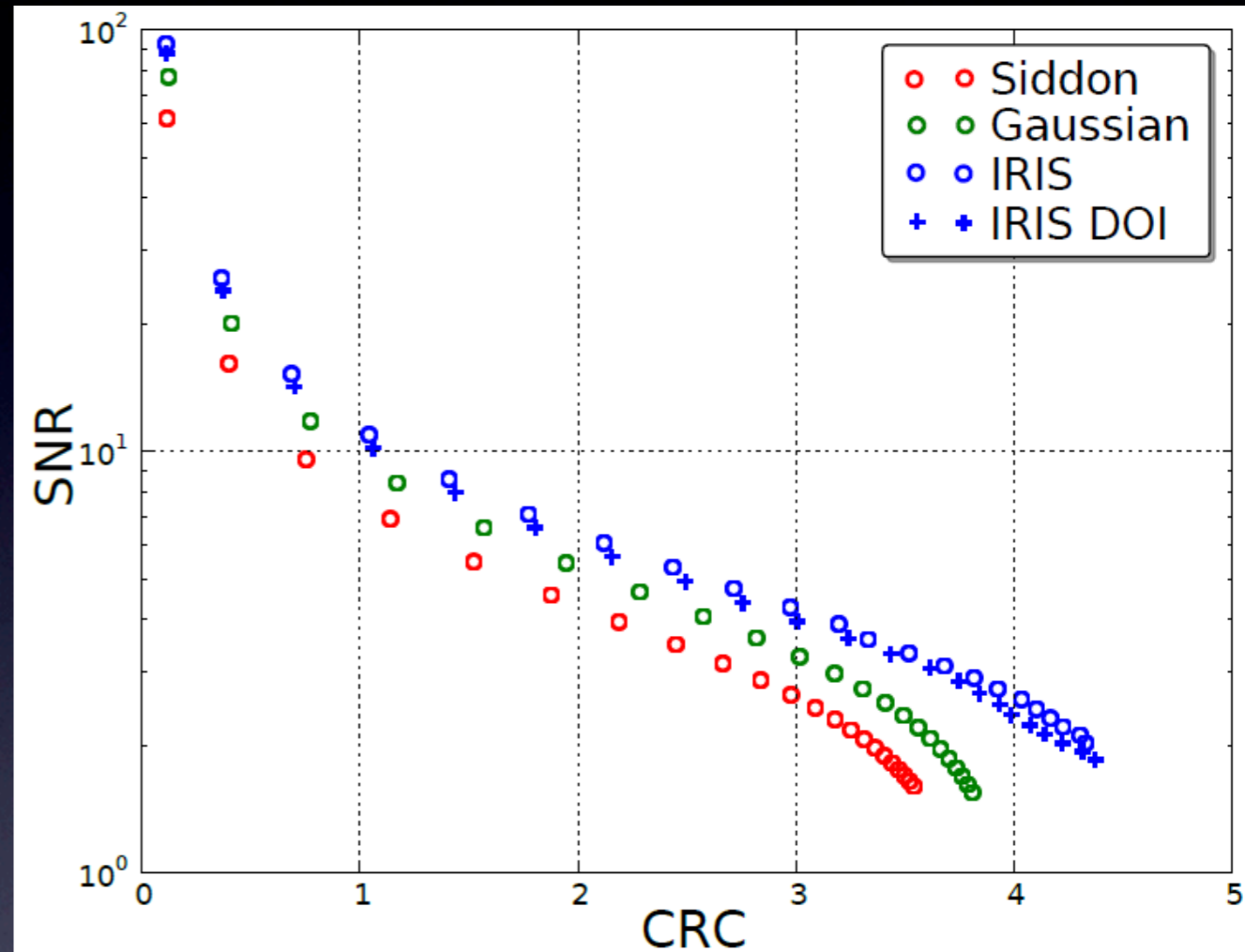
Difficult for VOR modeling projector (especially Gaussian)

Gaussian model + DOI = Not a Gaussian anymore!

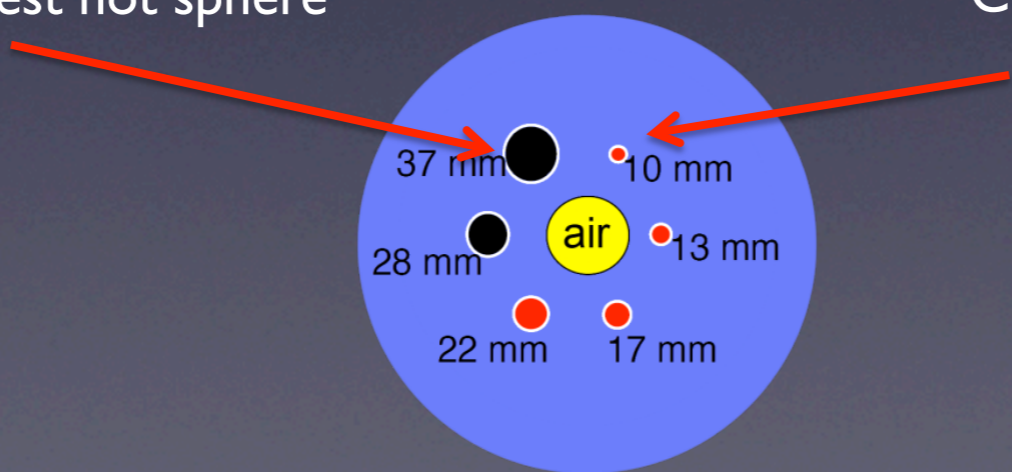
CRC/SNR (LM-OSEM 1 subset 70 iterations)



CRC in the biggest hot sphere



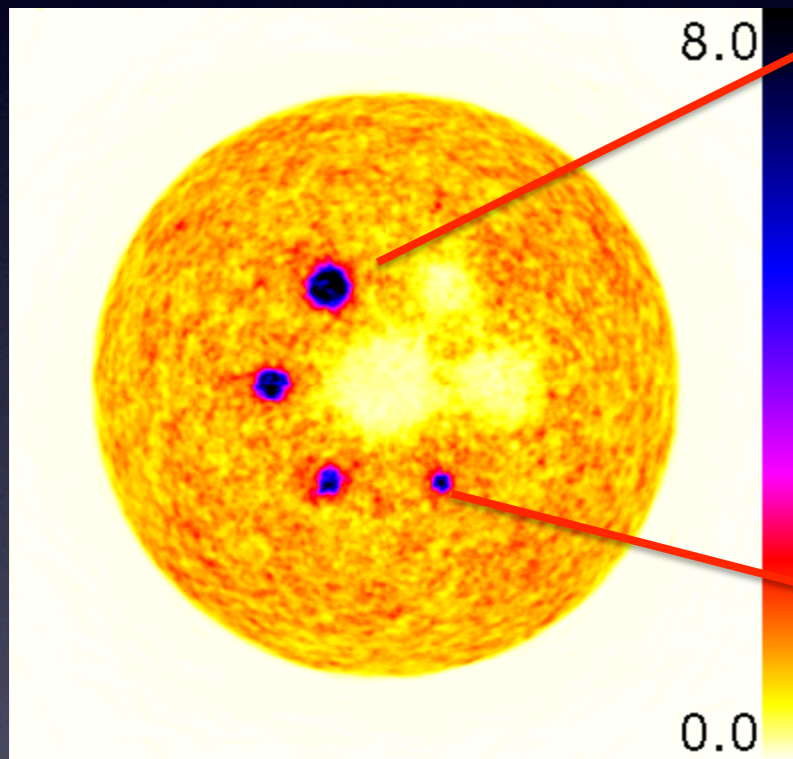
CRC in the smallest hot sphere



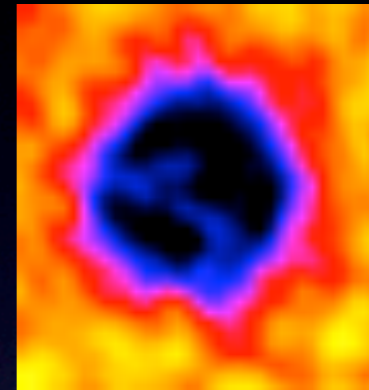
Not really improve the contrast

Image Quality

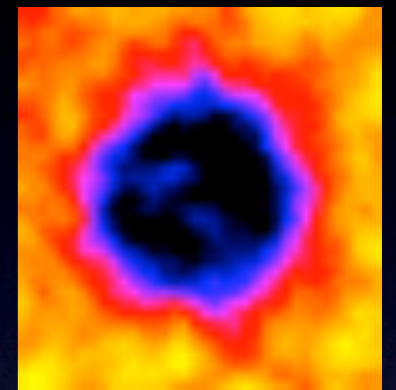
Reconstructed image for the same SNR (=4.5)



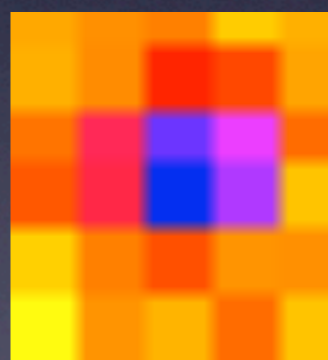
Siddon



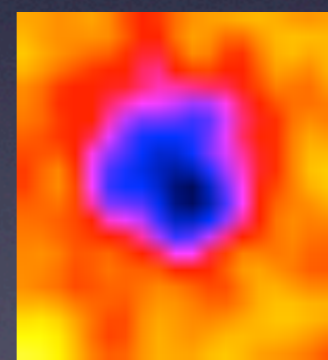
Gaussian



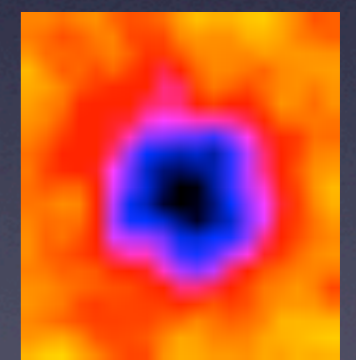
IRIS DOI



Siddon



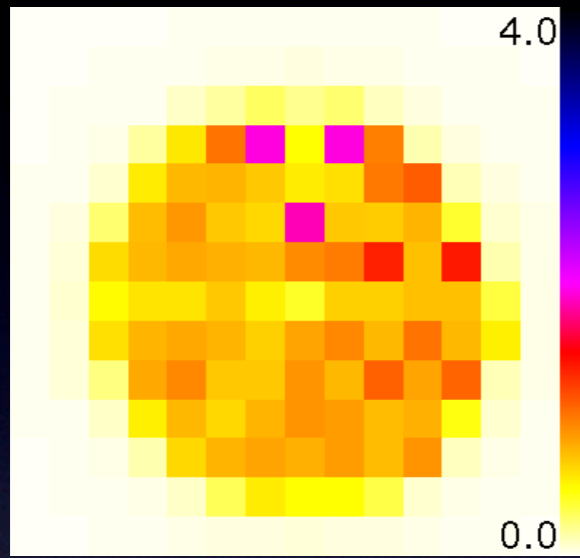
Gaussian



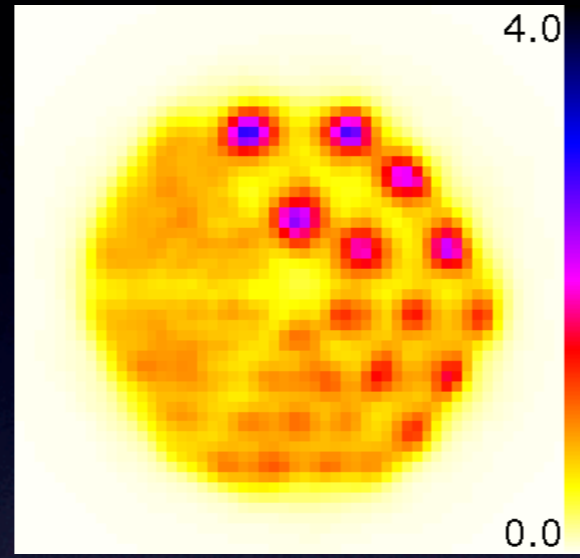
IRIS DOI

Image Resolution

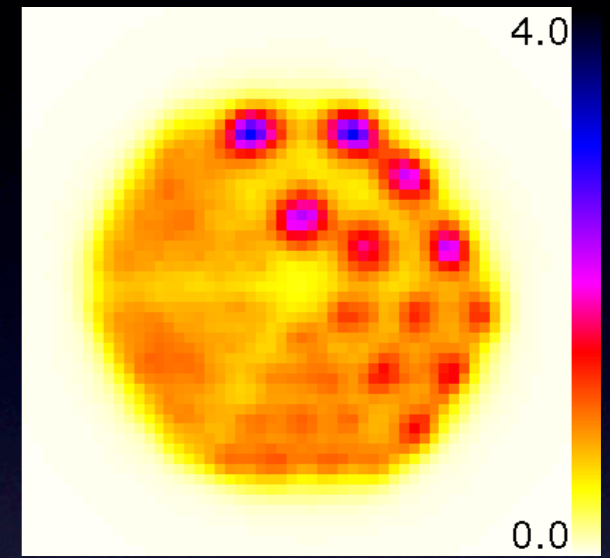
Centered miniature Derenzo (LM-OSEM 1 subset 15 iterations)



Siddon

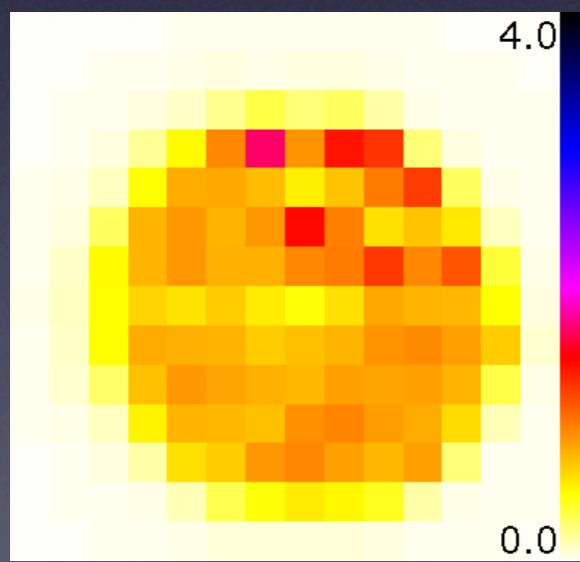


Gaussian

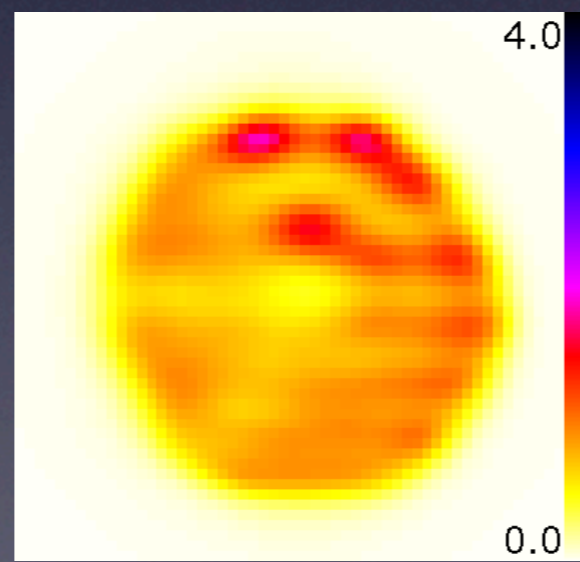


IRIS DOI

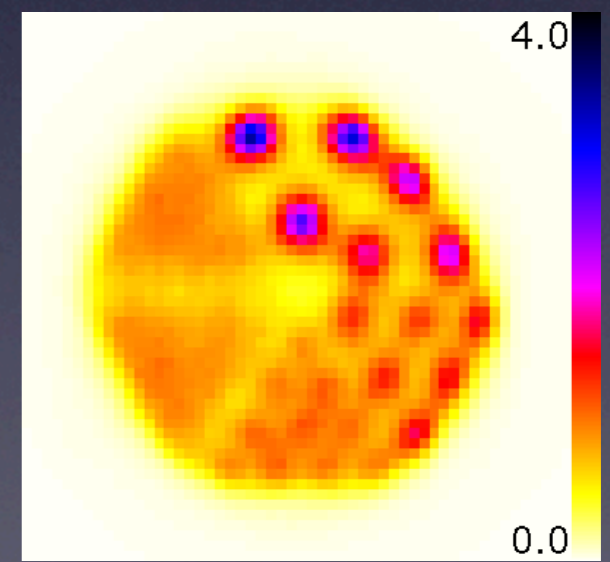
Shifted miniature Derenzo (LM-OSEM 1 subset 15 iterations)



Siddon

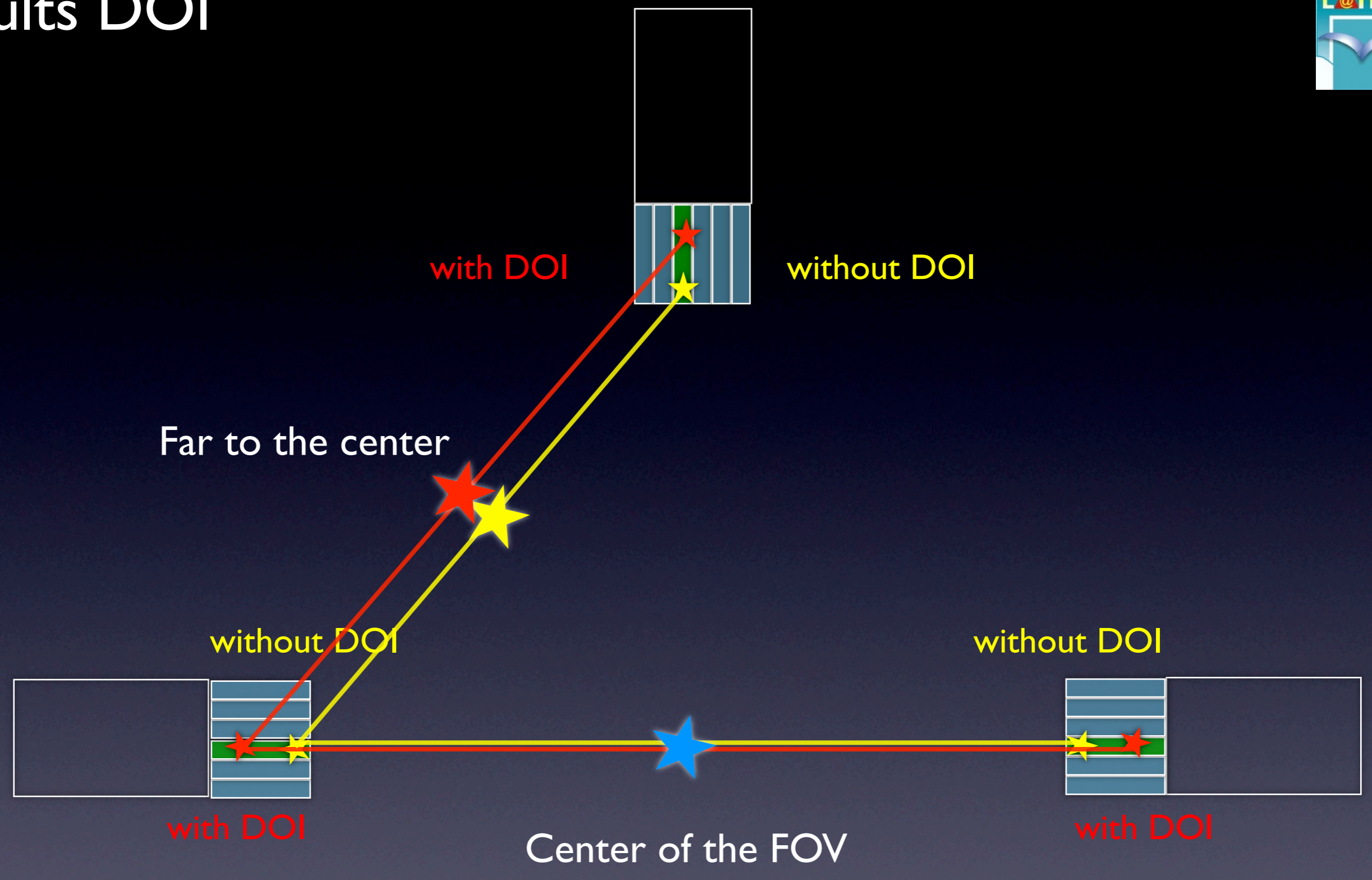


Gaussian



IRIS DOI

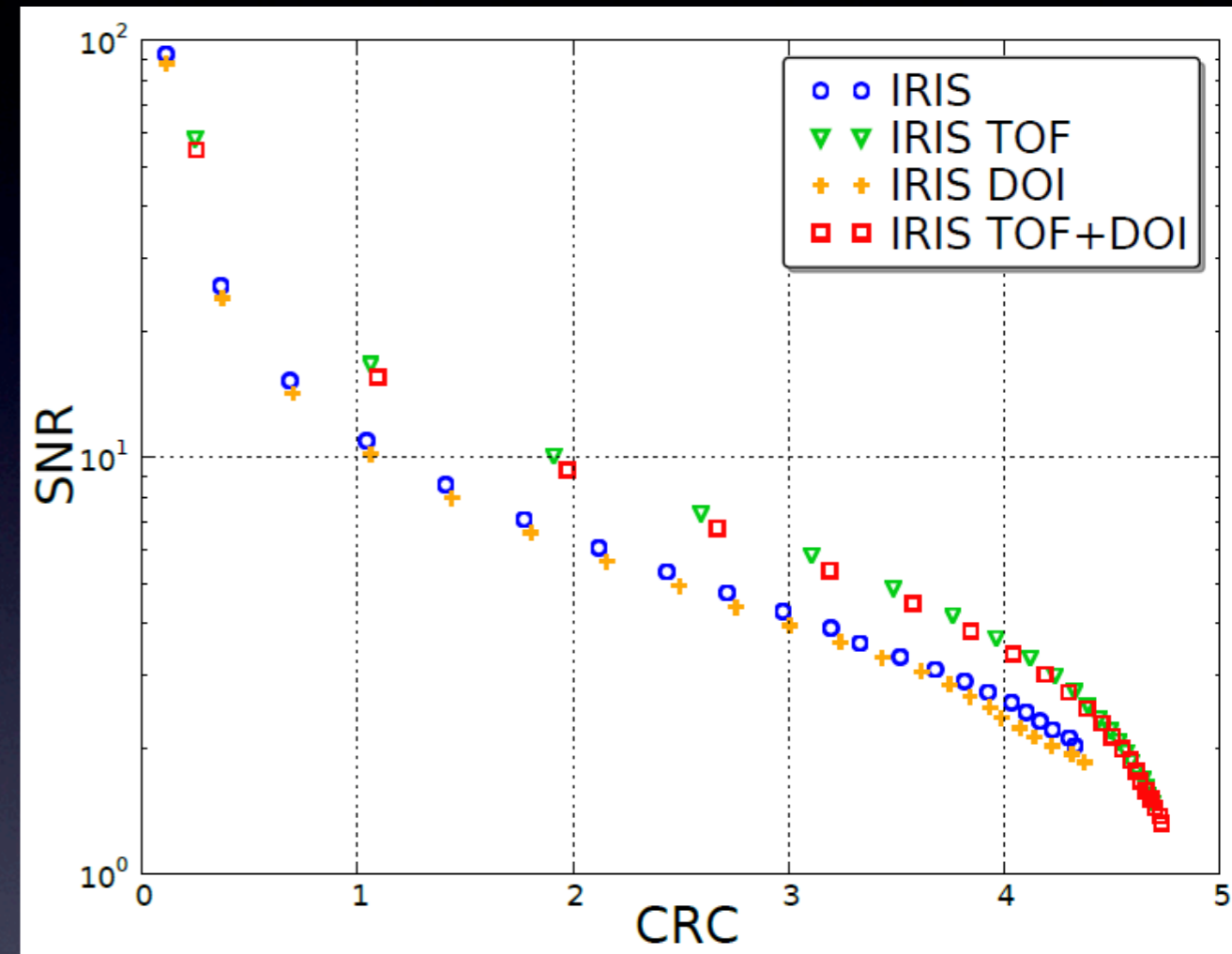
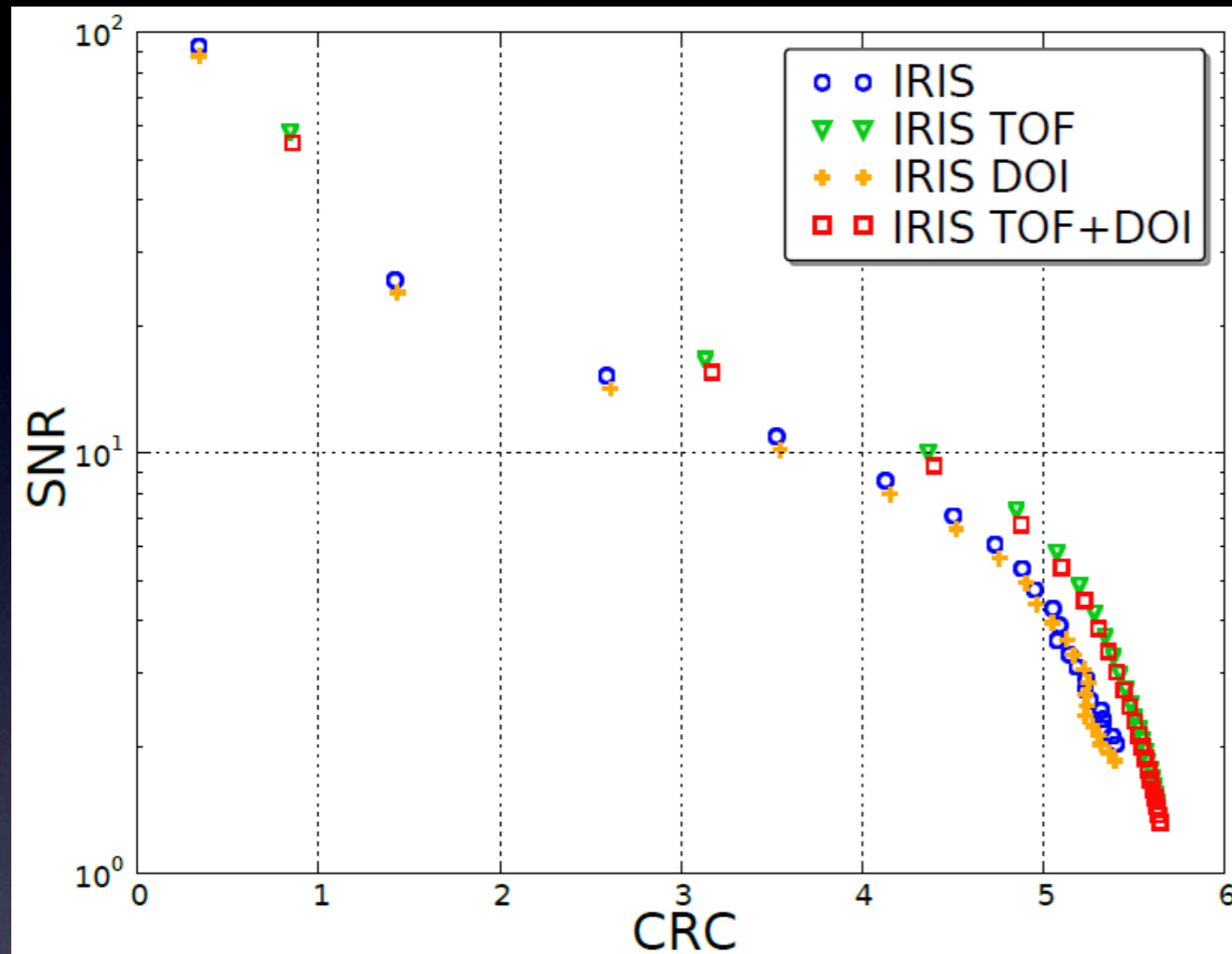
Results DOI



Results TOF+DOI



CRC/SNR (LM-OSEM I subset 70 iterations)



CRC in the biggest hot sphere

CRC in the smallest hot sphere

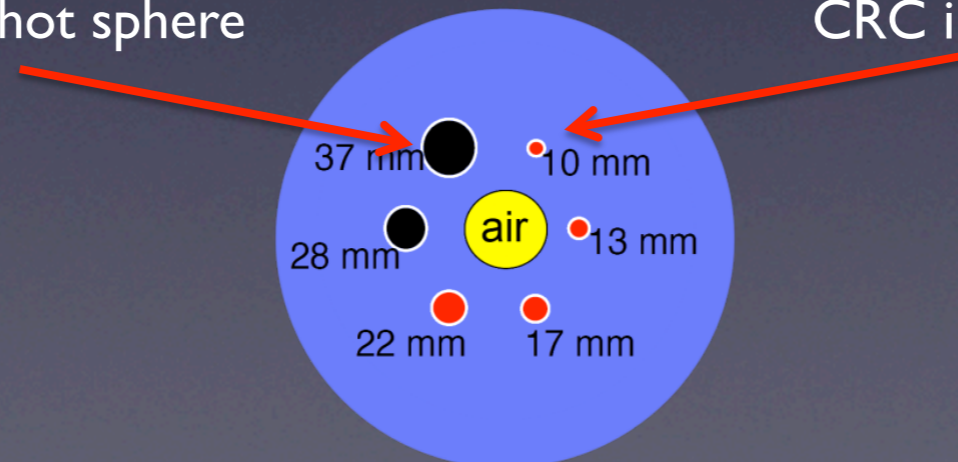
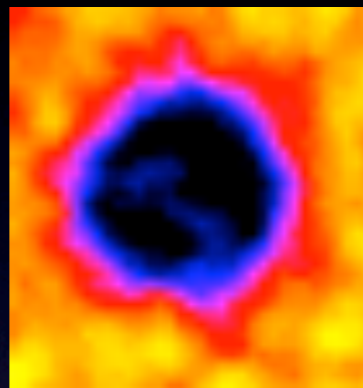
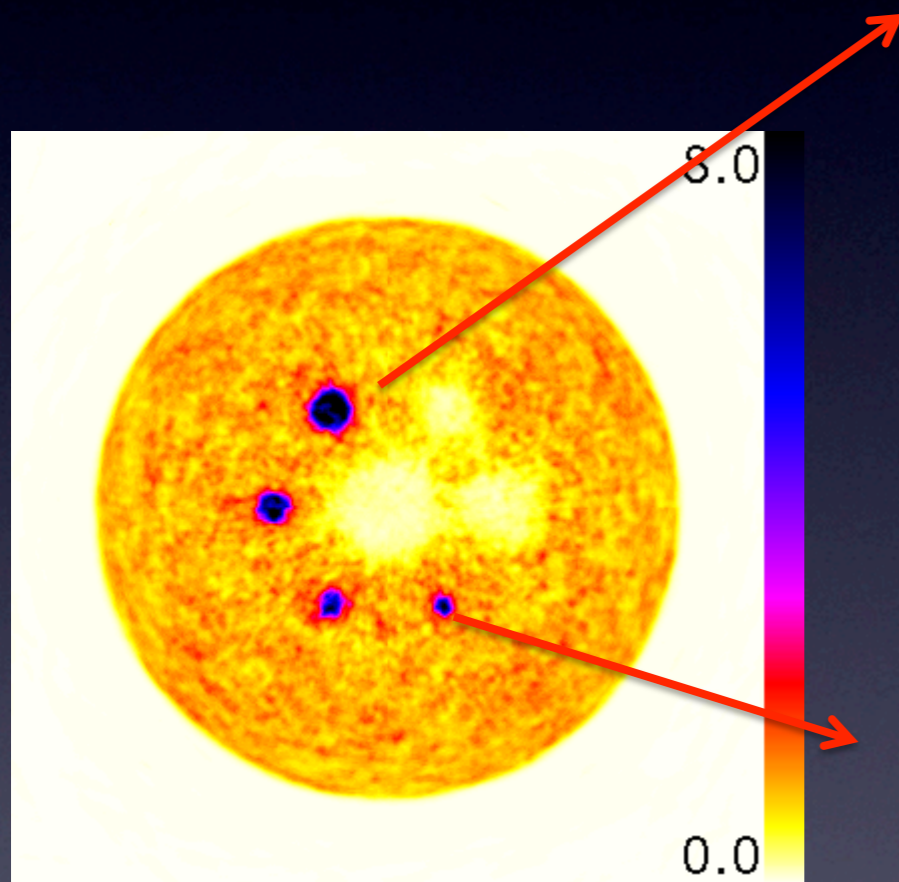
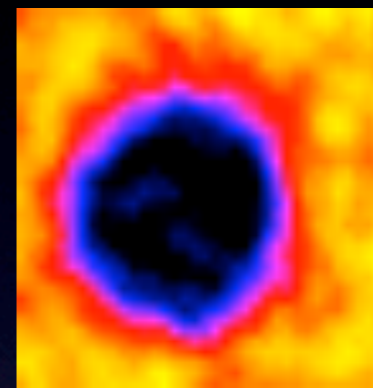


Image Quality

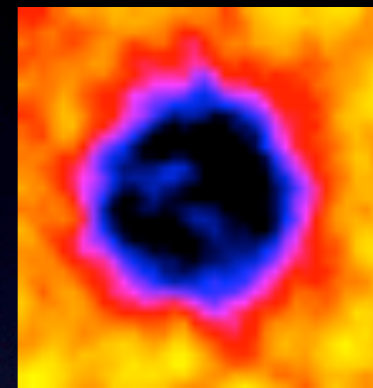
Reconstructed image for the same SNR (=4.5)



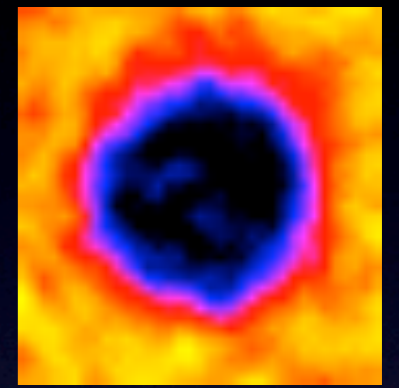
IRIS



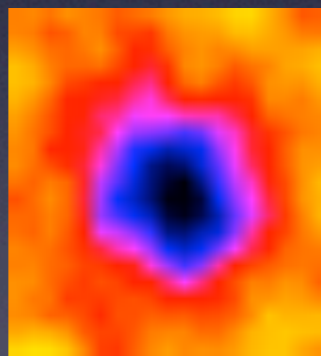
IRIS TOF



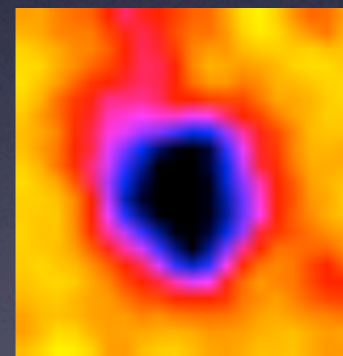
IRIS DOI



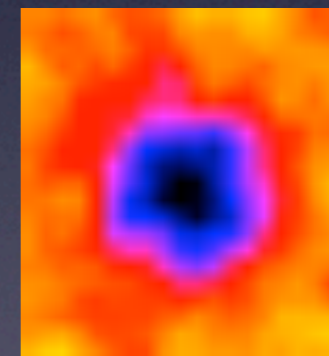
IRIS DOI+TOF



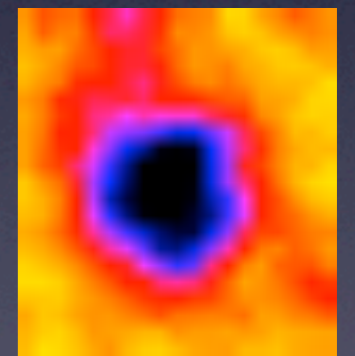
IRIS



IRIS TOF



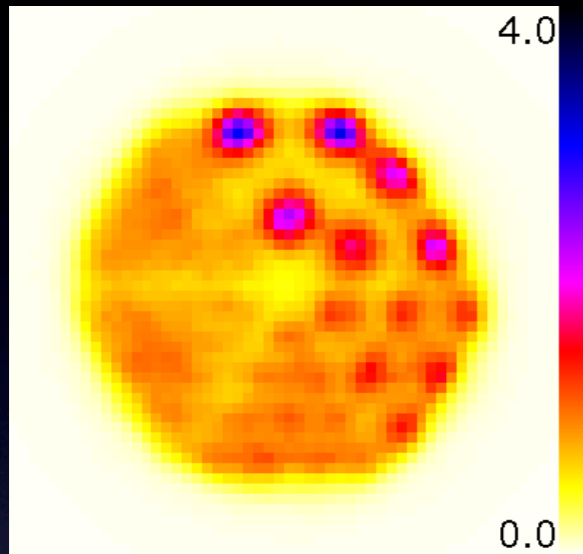
IRIS DOI



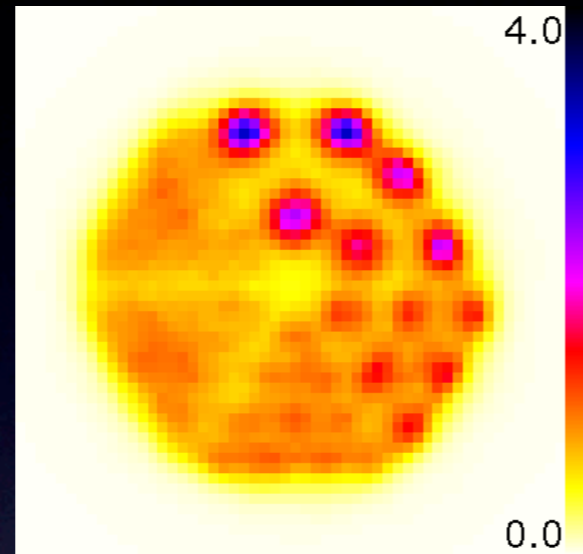
IRIS DOI+TOF

Image Resolution

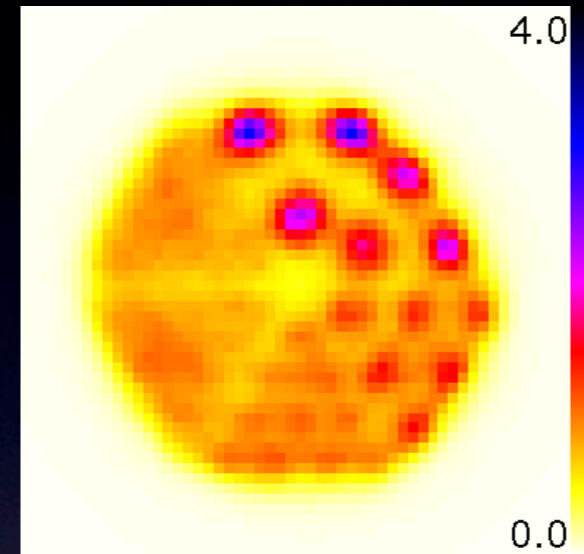
Centered miniature Derenzo (LM-OSEM 1 subset 15 iterations)



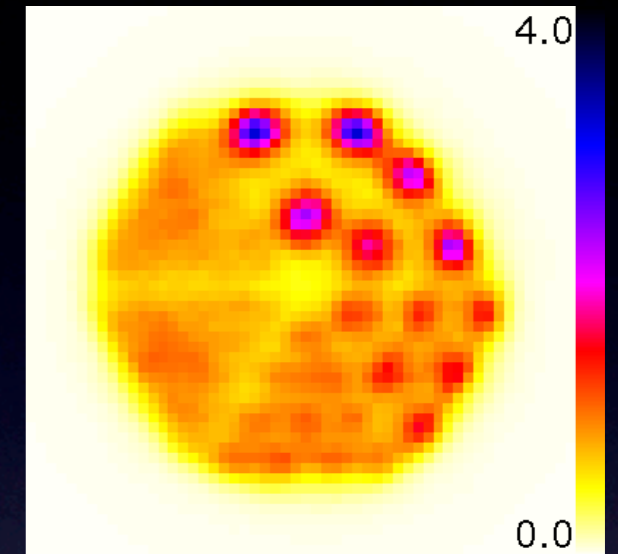
IRIS



IRIS TOF

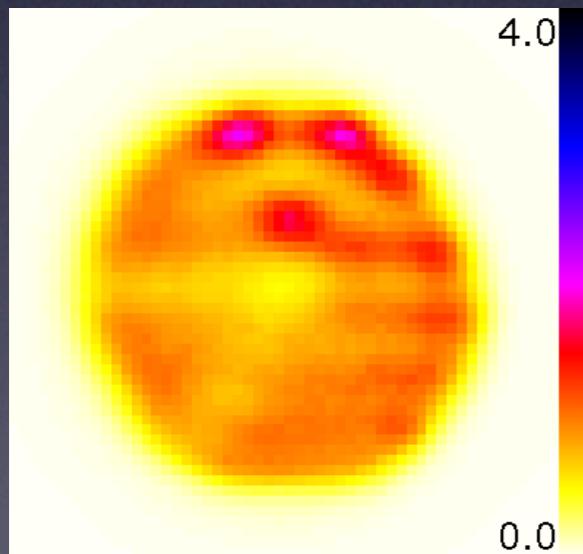


IRIS DOI

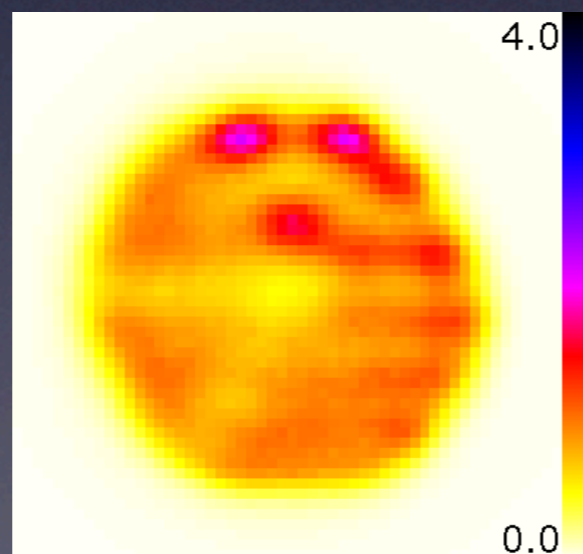


IRIS DOI+TOF

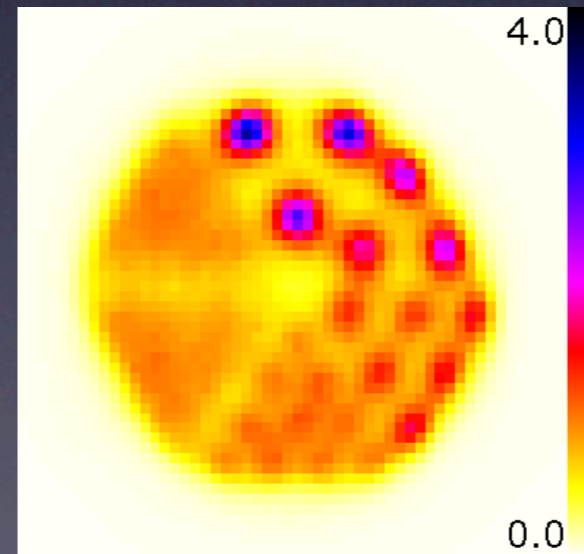
Shifted miniature Derenzo (LM-OSEM 1 subset 15 iterations)



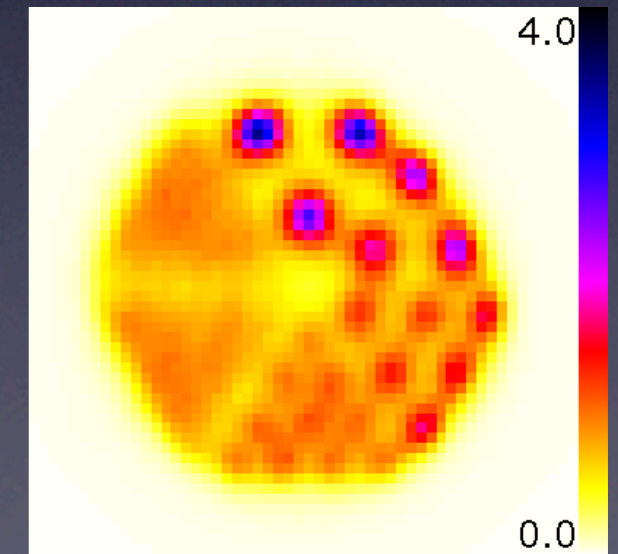
IRIS



IRIS TOF



IRIS DOI

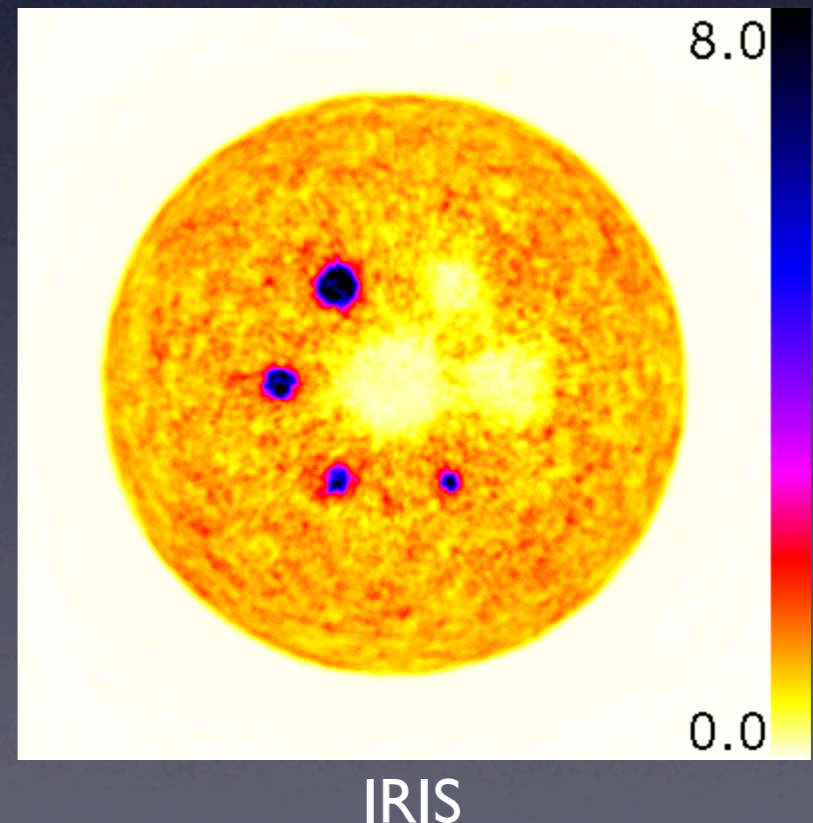
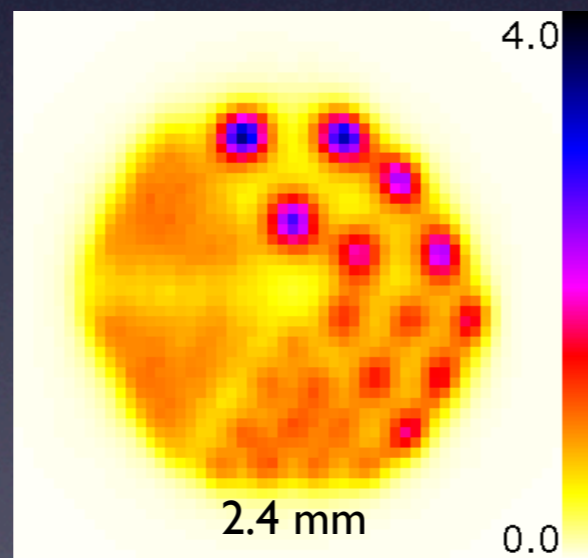
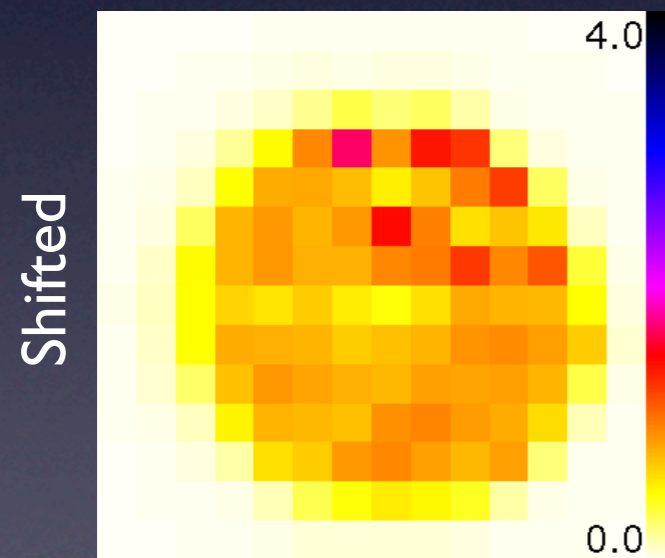
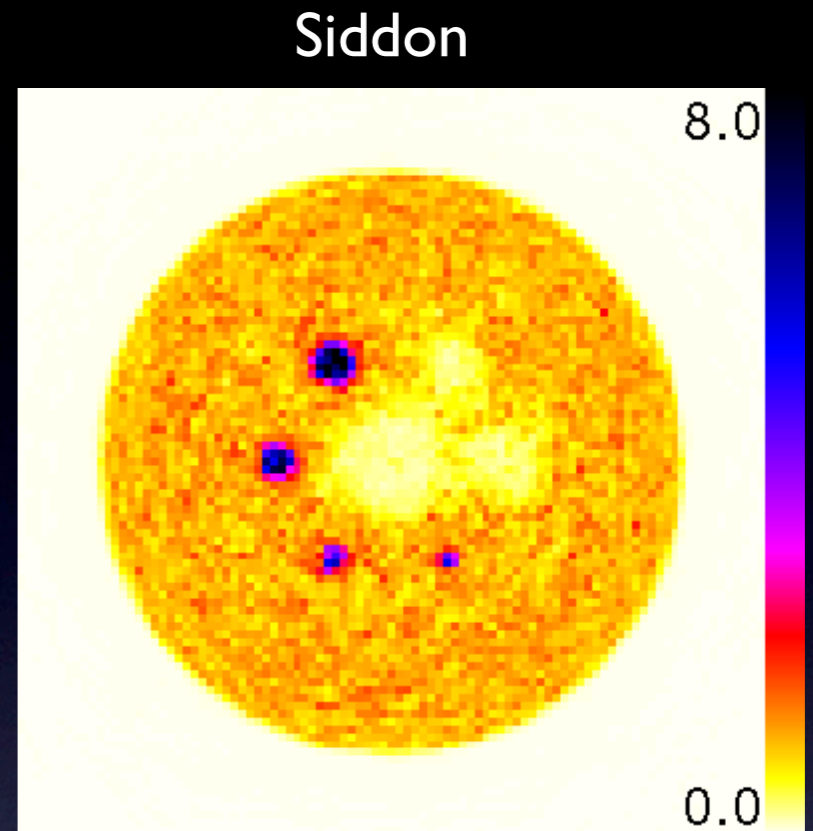
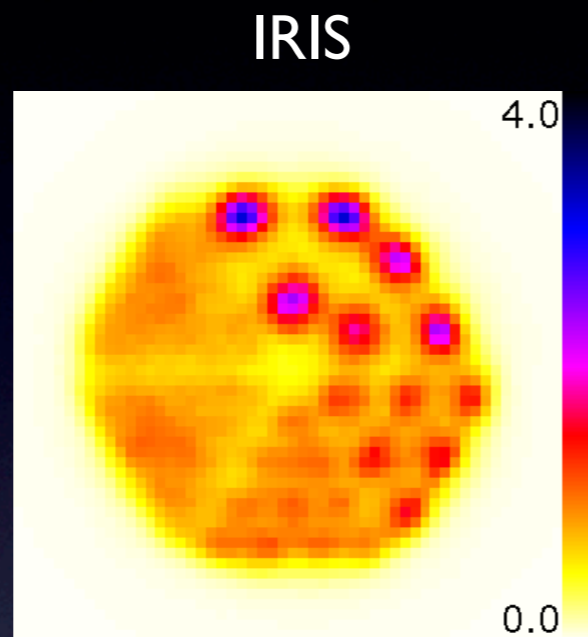
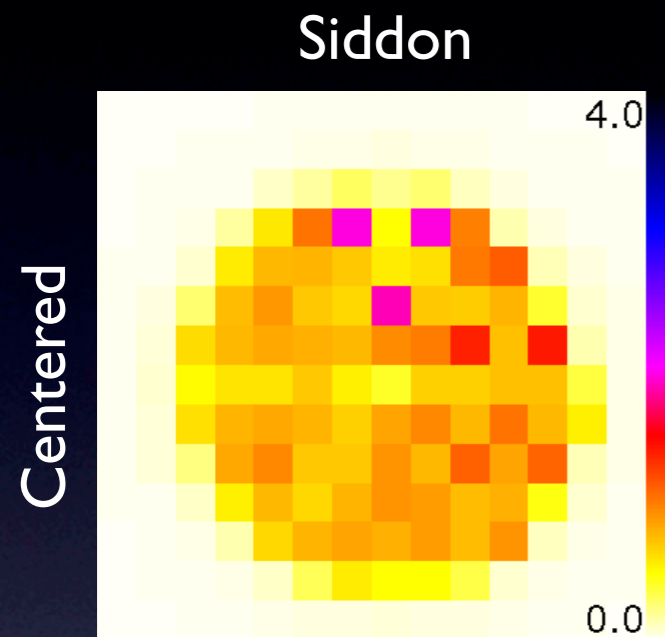


IRIS DOI+TOF

Results TOF+DOI



Final reconstruction



Conclusion

New IRIS projector including geometry, TOF and DOI:

- Accurate detector modeling
- Improved image quality and resolution
- TOF: improve image quality (SNR, contrast and convergence)
- DOI: improve image resolution (specially off center)
- Easy to perform on GPU (only need to draw simple lines)

Perspectives:

- Evaluation with different scanner geometry and resolutions of TOF and DOI
- Include other detector information (energy, ...)

Thank for your attention

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