# 2D fan-beam CT with independent source and detector rotation

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## Image Guided Radiotherapy (IGRT)

#### Imaging in the radiotherapy room

- Fluoroscopy
- Portal imaging
- CT on rail
- Ultrasound probe
- ...
- Cone-beam CT since 10 years
  - Treatment guidance
  - Retrospective studies
  - Adaptive Radiotherapy



[Jaffray et al., IJROBP, 2002]

## New PAIR device (Salzburg)

Patient Alignment system with an integrated x-ray Imaging Ring

- Ceiling mounted robotic arm
- Independent rotation of the source and the flat panel
- Couch translation
- Source collimation with 4 motorized jaws
- Fast switching between energies
- $41 \times 41 \text{ cm}^2$  flat panel



medPhoton G.m.b.H (courtesy of P. Steininger)

Installation: 1 prototype in Salzburg, 4 planned at MedAustron

#### Geometry in this presentation

D D MIDLINE θ ) a r(a,s) CENTER OF ROTATION s = 0

Fig. 2. Fan beam geometry with a displaced center-of-rotation for a flat detector.

[Gullberg et al., IEEE TMI, 1986]

#### Geometry in this presentation

D D MIDLINE r(a,s) CENTER OF ROTATION = 0 tilted Fig. 2. Fan beam geometry with a displaced center of rotation for a flat detector.

[Gullberg et al., IEEE TMI, 1986]

## Effect of tilt on sampling



#### Effect of tilt on sampling

Relationship

$$D = 100, \beta = 30$$



## Effect of tilt on sampling

#### Derivative

$$\frac{\mathrm{d}s}{\mathrm{d}u} = \frac{D^2 \cos\beta}{(D\cos\beta + u\sin\beta)^2} \quad (3)$$

At origin,

d

d

$$\frac{s}{u}(0) = \frac{1}{\cos\beta} \qquad (4)$$

which would also be the constant sampling ratio in the parallel situation.

$$D = 100, \beta = 30$$



#### Potential use to increase spatial resolution



From parallel projections  $p_{\rho}(\theta, t)$ , the Fourier slice theorem leads to the inversion formula

$$f(r,\phi) = \int_0^{2\pi} \int_{-R}^R p_p(\theta,t) h[r\cos(\theta-\phi)-t] \,\mathrm{d}t \,\mathrm{d}\theta \qquad (5)$$

with

$$h(t) = \int_{\mathbb{R}} \frac{|\mu|}{2} \exp^{2i\pi\mu t} d\mu.$$
 (6)

Implementation: filtered backprojection algorithm.

## Change of variable [Gullberg et al., TMI, 1986]

Assuming a flat detector at the origin (D=D'), we have

$$p_p(\theta, t) = p_f(\alpha, s)$$
 (7)

for

$$\begin{cases} t = (s + \tau)Z\\ \theta = \alpha + \tan^{-1}\left(\frac{s}{D}\right) \end{cases}$$
(8)

with

$$Z = \frac{D}{\sqrt{s^2 + D^2}} \qquad (9)$$



#### Change of variable [Gullberg et al., TMI, 1986]

Assuming that D and  $\tau$  are constant, the Jacobian matrix is

$$\frac{dt}{ds} = (D^2 - \tau s) \frac{Z^3}{D^2}$$
(10)  
$$\frac{d\theta}{ds} = \frac{Z^2}{D}$$
(11)  
$$\frac{dt}{d\alpha} = 0$$
(12)  
$$\frac{d\theta}{d\alpha} = 1$$
(13)

so its determinant is

$$J = \left| \left( D^2 - \tau s \right) \frac{Z^3}{D^2} \right| \tag{14}$$

#### Change of variable [Gullberg et al., TMI, 1986]

$$f(r,\phi) = \int_{0}^{2\pi} \int_{-W}^{W} p_{f}(\alpha,s)h\left[r\cos(\alpha+\tan^{-1}(\frac{s}{D})-\phi)-(s+\tau)Z\right](D^{2}-\tau s)\frac{Z^{3}}{D^{2}}dsd\alpha$$
$$= \int_{0}^{2\pi} \int_{-W}^{W} p_{f}(\alpha,s)h\left[UZ(s'-s)\right](D^{2}-\tau s)\frac{Z^{3}}{D^{2}}dsd\alpha$$
(15)

with

$$U = \frac{r \sin(\alpha - \phi) + D}{D}$$
(16)  
$$s' = \frac{r D \cos(\alpha - \phi) - \tau D}{r \sin(\alpha - \phi) + \tau D}$$
(17)

$$-\frac{1}{r\sin(\alpha-\phi)+D}$$

We can then use an essential property of the filter:

$$h(at) = \frac{1}{a^2}h(t) \tag{18}$$

to obtain

$$f(r,\phi) = \int_0^{2\pi} \frac{1}{U^2} \int_{-W}^W p_f(\alpha,s) \frac{D - \frac{\tau s}{D}}{\sqrt{s^2 + D^2}} h(s'-s) \,\mathrm{d}s \,\mathrm{d}\alpha \quad (19)$$

- $D = 630 \text{ mm}, D' = 1100 \text{ mm}, \tau = 1 \text{ mm}$
- Projections
  - 1000
  - 768 samples
  - 0.2 mm spacing
- Reconstruction
  - $512 \times 512$  pixels
  - $0.125 \times 0.125 \,\mathrm{mm^2}$  spacing

#### Gray level window: [-582, -482] HU.



 $\tau = 0 \, \mathrm{mm}$ 



 $\tau = 1 \text{ mm}$ , no correction



#### Gray level window: [-582, -482] HU.



 $\tau = 1 \text{ mm}$ , new algorithm



#### Gray level window: [-582, -482] HU.



 $\tau = 1 \text{ mm}$ , uncorrected weights

#### Experiments



#### **Experiments**



#### Gray level window: [-582, -482] HU.



 $\beta = 30^{\circ}$ , uncorrected weights

![](_page_20_Figure_1.jpeg)

#### **Point Spread Function**

- $D = \tau = 1000 \text{ mm}, \ \beta = 45^{\circ}$
- Ball at (0, 0), radius
  0.01 mm, density 1000 HU
- Projections
  - 1000 projections
  - 10 mm spacing
  - 1000 rays per pixel
- Reconstruction
  - Centered on (0, 0)
  - 64 × 64 pixels
  - $1 \times 1 \,\mu m^2$  spacing

![](_page_21_Picture_11.jpeg)

#### **Point Spread Function**

- $D = \tau = 1000 \text{ mm}, \ \beta = 45^{\circ}$
- Ball at (800, 0), radius
  0.01 mm, density 1000 HU
- Projections
  - 1000 projections
  - 10 mm spacing
  - 1000 rays per pixel
- Reconstruction
  - Centered on (800, 0)
  - 64 × 64 pixels
  - $1 \times 1 \,\mu m^2$  spacing

![](_page_22_Picture_11.jpeg)

![](_page_23_Figure_1.jpeg)

![](_page_24_Figure_1.jpeg)

![](_page_25_Figure_1.jpeg)

![](_page_26_Figure_1.jpeg)

![](_page_27_Figure_1.jpeg)

![](_page_28_Figure_1.jpeg)

![](_page_29_Figure_1.jpeg)

![](_page_30_Figure_1.jpeg)

![](_page_31_Figure_1.jpeg)

![](_page_32_Figure_1.jpeg)

![](_page_33_Figure_1.jpeg)

![](_page_34_Figure_1.jpeg)

![](_page_35_Figure_1.jpeg)

![](_page_36_Figure_1.jpeg)

 $\tau$  depends on the gantry angle

 $\Rightarrow \tau : \alpha \to \tau(\alpha)$  (20)

Note that the exact same derivation has been performed by [Concepcion *et al.*, IEEE TMI, 1992]

![](_page_37_Figure_4.jpeg)

#### Change of variable [Crawford et al., Med Phys, 1988]

Assuming D constant and  $\tau$  constant, the Jacobian matrix is

$$\frac{dt}{ds} = (D^2 - \tau s) \frac{Z^3}{D^2}$$
(21)  
$$\frac{d\theta}{ds} = \frac{Z^2}{D}$$
(22)  
$$\frac{dt}{d\alpha} = Z \frac{d\tau}{d\alpha}$$
(23)  
$$\frac{d\theta}{d\alpha} = 1$$
(24)

so its determinant is

$$J = \left| \left( D^2 - \tau s - D \frac{\mathrm{d}\tau}{\mathrm{d}\alpha} \right) \frac{Z^3}{D^2} \right|$$
(25)

Inversion formula

$$f(r,\phi) = \int_0^{2\pi} \frac{1}{U^2} \int_{-W}^{W} p_f(\alpha,s) \frac{D - \frac{\tau s}{D} - \frac{d\tau}{d\alpha}}{\sqrt{s^2 + D^2}} h(s'-s) \, \mathrm{d}s \, \mathrm{d}\alpha$$
(26)

In [Concepcion *et al.*, IEEE TMI, 1992], opposite sign for the new term. Mathematically wrong but experimentally correct (work in progress)...

## Experiments [Crawford et al., Med Phys, 1988]

#### Gray level window: [-582, -482] HU.

![](_page_40_Picture_2.jpeg)

Assuming  $\tau = 0 \text{ mm}$ 

![](_page_40_Picture_4.jpeg)

Actual  $\tau(\alpha) = 3\sin(2\alpha) \text{ mm}$ 

## Experiments [Crawford et al., Med Phys, 1988]

#### Gray level window: [-582, -482] HU.

![](_page_41_Picture_2.jpeg)

Assuming  $\tau = 0 \text{ mm}$ 

![](_page_41_Picture_4.jpeg)

Assuming 
$$\frac{d\tau}{d\alpha} = 0 \text{ mm}$$

#### **Experiments**

## Gray level window: [-582, -482] HU.

![](_page_42_Picture_2.jpeg)

Actual  $\tau(\alpha) =$ 630 × *tan*(30°) sin(2 $\alpha$ ) mm

![](_page_42_Picture_4.jpeg)

Assuming 
$$\frac{d\tau}{d\alpha} = 0 \text{ mm}$$

## *D* also depends on the gantry angle

 $\Rightarrow D: \alpha \to D(\alpha)$  (27)

![](_page_43_Figure_3.jpeg)

Assuming D constant and  $\tau$  constant, the Jacobian matrix is

$$\frac{\mathrm{d}t}{\mathrm{d}s} = (D^2 - \tau s) \frac{Z^3}{D^2}$$
(28)  
$$\frac{\mathrm{d}\theta}{\mathrm{d}s} = \frac{Z^2}{D}$$
(29)

$$\frac{\mathrm{d}t}{\mathrm{d}\alpha} = Z \frac{\mathrm{d}\tau}{\mathrm{d}\alpha} + (s+\tau) \frac{Z^3 s^2}{D^3} \frac{\mathrm{d}D}{\mathrm{d}\alpha}$$
(30)  
$$\frac{\mathrm{d}\theta}{\mathrm{d}\alpha} = 1 - \frac{Z^2 s}{D^3} \frac{\mathrm{d}D}{\mathrm{d}\alpha}$$
(31)

so its determinant is

$$J = \left| \left( D^2 - \tau s - D \frac{\mathrm{d}\tau}{\mathrm{d}\alpha} - s \frac{\mathrm{d}D}{\mathrm{d}\alpha} \right) \frac{Z^3}{D^2} \right|$$
(32)

#### Inversion formula

$$f(r,\phi) = \int_0^{2\pi} \frac{1}{U^2} \int_{-W}^{W} p_f(\alpha,s) \frac{D - \frac{\tau s}{D} - \frac{d\tau}{d\alpha} - \frac{s}{D} \frac{dD}{d\alpha}}{\sqrt{s^2 + D^2}} h(s'-s) \, \mathrm{d}s \, \mathrm{d}\alpha$$
(33)

#### **Experiments**

![](_page_46_Figure_1.jpeg)

- R = 200 mm, F = 100 mm
- Projections
  - 2000
  - 1000 samples
  - 0.25 mm spacing
- Reconstruction
  - $512 \times 512$  pixels
  - 0.125 mm<sup>2</sup> spacing
  - Centered around (F,0)

#### **Experiments**

#### Gray level window: [-582, -482] HU.

![](_page_47_Picture_2.jpeg)

New formula

![](_page_47_Picture_4.jpeg)

Assuming 
$$\frac{dD}{d\alpha} = 0 \text{ mm}$$

• Tilting an ideal detector improves CT resolution

Inversion formula for any 2D derivable trajectory

• Requires the derivative of the parameters with respect to the gantry angle

• What is the sensitivity to noise in geometric parameters?

• What is the optimal angular sampling?

• Will it really improve resolution when hardware considerations come into the picture?